



Homoclinic Bifurcation of a Quadratic Family of Real Functions with Two Parameters

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Abstract

In this work the homoclinic bifurcation of the family

$H = \{h_{a,b}(x) = ax^2 + b : a \in \mathbb{R}/\{0\}, b \in \mathbb{R}\}$ is studied. We proved that this family has a homoclinic tangency associated to $x = 0$ of P_1 for $b = \frac{-2}{a}$. Also

we proved that $W^u(P_1)$ does not intersect the backward orbit of P_1 for $b > \frac{-2}{a}$, but has intersection for $b < \frac{-2}{a}$ with $a > 0$. So H has this type of the bifurcation.

Subject Areas

Dynamical System

Keywords

Local Unstable Set, Unstable Set, Homoclinic Point, Homoclinic Orbit, Non-Degenerate, Homoclinic Tangency, Homoclinic Bifurcation

1. Introduction

There are various definitions for the homoclinic bifurcation. In the sense of Devaney, the homoclinic bifurcation is a global type of bifurcations, that is, this type of bifurcation is a collection of local and simple types of bifurcations [1] (like, period-doubling and saddle-node of bifurcation [2]).

According to [3] [4] [5] we have another definition of the homoclinic bifurcation via the notions of the unstable sets of a repelling periodic point (fixed point) and the intersection of this set with the backward orbits of this point.

The purpose of this work is to prove the family

$H = \{h_{a,b}(x) = ax^2 + b : a \in \mathbb{R}/\{0\}, b \in \mathbb{R}\}$ has homoclinic bifurcation at $b = \frac{-2}{a}$

following the second definition.

2. Definitions and Basic Concepts

2.1. Definition 1: [6]

A fixed point P is said to be **expanding** for a map f if there exists a neighborhood $U(P)$ such that $|f'(x)| > 1$ for any $x \in U(P)$.

The neighborhood in the previous definition is exactly **the local unstable set**.

2.2. Definition 2: [7]

Let P be a repelling fixed point for a function $f: I \rightarrow I$ on a compact interval $I \subset \mathbb{R}$, then there is an open interval about P on which f is one-to-one and satisfies the **expansion** property. $|f(x) - f(P)| > |x - P|, \forall x \in I$ where $x \neq P$.

The interval in the previous definition is exactly **the unstable set of P** .

2.3. Definition 3: [8]

Let P is fixed point and $f'(P) > 1$ for a map $f: \mathbb{R} \rightarrow \mathbb{R}$. A point q is called **homoclinic point to P** if $q \in W_{loc}^u(P)$ and there exists $n > 0$ such that $f^n(q) = P$.

2.4. Definition 4: [9]

The union of the forward orbit of q with a suitable sequence of preimage of q is called **the homoclinic orbit of P** . That is

$$O(q) = \{P, \dots, q_{-2}, q_{-1}, q, q_1, q_2, \dots, q_m = P\} \text{ where } q_{i+1} = f(q_i) \text{ for } i \leq m-1, \\ q_m = P \text{ and } \lim_{i \rightarrow -\infty} q_i = P.$$

2.5. Definition 5: [10]

The critical x point is **non-degenerate** if $f''(x) \neq 0$. The critical point x is **degenerate** if $f''(x) = 0$.

2.6. Definition 6: [11]

Let f be a smooth map on $I \subset \mathbb{R}$, and let p be a hyperbolic fixed point for the map f . If $W^u(p)$ intersects the backward orbit of p at a nondegenerate critical point x_{cr} of f then x_{cr} is called a **point of homoclinic tangency associated to p** .

2.7. Definition 7: [3]

Let f_φ be a smooth map on $I \subset \mathbb{R}$, and let p be a hyperbolic fixed point for a map f_φ . We say that f_φ has **homoclinic bifurcation associated to p at $\varphi = \hat{\varphi}$** if:

- 1) For $\varphi < \hat{\varphi}$ ($\varphi > \hat{\varphi}$), $W^u(p)$ and the backward orbit of p has no intersect.
- 2) For $\varphi = \hat{\varphi}$, $f_{\hat{\varphi}}$ has a point of homoclinic tangency x_{cr} associated to p .
- 3) For $\varphi > \hat{\varphi}$ ($\varphi < \hat{\varphi}$), the intersection of $W^u(p)$ with the backward orbit of p is nonempty.

3. Homoclinic Bifurcation of the Family

$$H = \{h_{a,b}(x) = ax^2 + b : a \in \mathbb{R} \setminus \{0\}, b \in \mathbb{R}\}$$

In this section, we show that the family H has a point of homoclinic tangency associated to P_1 at $b = \frac{-2}{a}$, and H has a homoclinic bifurcation.

We need the following results proved in [12].

At the first, the fixed points of $h_{a,b}(x)$ are

$$P_1 = \frac{1 + \sqrt{1 - 4ab}}{2a}, P_2 = \frac{1 - \sqrt{1 - 4ab}}{2a}.$$

a) Proposition:

For $h_{a,b}(x) \in H$ with $a > 0$ the local unstable set of the fixed point P_1 is $w_{loc}^u(P_1) = \left(\frac{1}{2|a|}, \infty\right)$.

b) Lemma:

For $h_{a,b}(x) \in H$, $h_{a,b}^{-1}(P_1) = \mp \sqrt{\frac{P_1 - b}{a}} = \mp P_1$ where $P_1 > b$ for $a > 0$.

c) Theorem:

For $h_{a,b}(x) \in H$ with $a > 0$, the unstable set of the fixed point P_1 is $w^u(P_1) = \left(\frac{1}{|a|} - P_1, \infty\right)$.

d) Remark: [13]

The local unstable set of the fixed point P_2 is $w_{loc}^u(P_2) = \left(-\infty, \frac{-1}{2|a|}\right)$, and the unstable set of the fixed point P_2 is $w^u(P_2) = \left(-\infty, \frac{-1}{|a|} - P_2\right)$. In this work we will omit the result about P_2 because $(h'_{a,b}(P_2) < -1)$, when $b < \frac{-3}{4a}$ for $a > 0$ $b > \frac{-3}{4a}$ for $a < 0$). Thus we will not care for the fixed point P_2 . (See definition (2.3)).

e) Remark:

For $h_{a,b}(x) \in H$, $h_{a,b}^{-2}(P_1) = \mp \sqrt{\frac{-P_1 - b}{a}}$.

f) Proposition:

For $h_{a,b} \in H$, if $b < \frac{-(5 + 2\sqrt{5})}{4a}$ with $a > 0$, then the second preimage of the fixed point P_1 belongs to the local unstable set of P_1 .

g) Proposition:

For $h_{a,b} \in H$, if $\frac{-(5 + 2\sqrt{5})}{4a} \leq b \leq \frac{-2}{a}$ with $a > 0$, then the third preimage

of the fixed point P_1 belongs to the local unstable set of P_1 .

h) Theorem:

For the family $H = \{h_{a,b}(x) = ax^2 + b : a > 0\}$, there exist homoclinic points to the fixed point P_1 whenever $b \leq \frac{-2}{a}$. Moreover $h_{a,b}^{-2}(P_1) = q_{1,1}, h_{a,b}^{-3}(P_1) = q_{2,1}$ are the first homoclinic points for $b < \frac{-(5+2\sqrt{5})}{4a}, \frac{-(5+2\sqrt{5})}{4a} \leq b \leq \frac{-2}{a}$ respectively.

i) Example:

For $h_{1,-6}(x) = x^2 - 6$, a homoclinic orbit of a homoclinic point $\sqrt{3}$ is: $O(\sqrt{3}) = \{3, -3, \sqrt{3}, \dots, 3\}$.

The main result:

3.1. Lemma 1

For $h_{a,b}(x) = ax^2 + b$ with $a \in \mathbb{R}/\{0\}$, the critical point of $h_{a,b}(x)$ is 0, and it is a non-degenerate critical point.

Proof:

Clearly that the critical point of $h_{a,b}(x)$ is zero.

Since $a \neq 0$, then

$$h''_{a,b}(x) = 2a \neq 0.$$

So $h_{a,b}(x)$ has a non-degenerate critical point at $x = 0$. ■

3.2. Lemma 2

If $b = 0$ of $h_{a,b}(x) \in H$ with $a \in \mathbb{R}/\{0\}$, then the backward orbit of the repelling fixed point P_1 is undefined in \mathbb{R} .

Proof:

$$h_{a,0}(x) = ax^2, \text{ clearly } P_1 = \frac{1}{a}.$$

Now the first preimage of $h_{a,0}(x)$ is

$$h_{a,0}^{-1}(x) = \mp \sqrt{\frac{x}{a}}, \text{ where } x > 0 \text{ for } a > 0.$$

By Lemma (3-b), we have

$$h_{a,0}^{-1}\left(\frac{1}{a}\right) = \mp \sqrt{\frac{1}{a^2}} = \mp \frac{1}{a} = \mp P_1.$$

But $+P_1$ is a fixed point, and $-P_1 = -\frac{1}{a} \notin W_{loc}^u(P_1) = \left(\frac{1}{2a}, \infty\right)$, see Proposition (3-a).

By Remark (3-e) we have

$$h_{a,0}^{-2}(P_1) = \mp \sqrt{\frac{-P_1}{a}} = \mp \sqrt{\frac{-\frac{1}{a}}{a}} = \mp \sqrt{\frac{-1}{a^2}} \notin \mathbb{R},$$

since $\frac{1}{a^2} > 0, \forall a \in \mathbb{R}/\{0\}$.

Therefore $h_{a,0}^{-n}(P_1)$ are undefined in \mathbb{R} with $n \geq 2$.

Thus the backward orbit of the repelling fixed point P_1 is undefined in \mathbb{R} ■

3.3. Theorem 1

For the family $h_{a,b}(x) = ax^2 + b, 0$ belong to the backward orbit of P_1 whenever $b = \frac{-2}{a}$ with $a \in \mathbb{R}/\{0\}$, and the backward orbit of P_1 is:

$$h_{a, \frac{-2}{a}}^{-n}\left(P_1 = \frac{2}{a}\right) = \left\{\frac{2}{a}, -\frac{2}{a}, 0, \frac{\sqrt{2}}{a}, \dots\right\}.$$

Proof:

We test the values of n which makes $h_{a,b}^{-n}(P_1) = 0$.

By Lemma (3-b), $h_{a,b}^{-1}(P_1) = \pm P_1$.

So $h_{a,b}^{-1}(P_1) \neq 0$.

Now suppose that $h_{a,b}^{-2}(P_1) = 0$, by Remark (3-e) then

$$h_{a,b}^{-2}(P_1) = \mp \sqrt{\frac{-P_1 - b}{a}} = 0, \text{ thus}$$

$$\frac{-P_1 - b}{a} = 0$$

$$-P_1 - b = 0$$

$$P_1 = -b.$$

Since the fixed point $P_1 = \frac{1 + \sqrt{1 - 4ab}}{2a}$, therefore

$$\frac{1 + \sqrt{1 - 4ab}}{2a} = -b,$$

then

$$1 + \sqrt{1 - 4ab} = -2ab$$

$$\sqrt{1 - 4ab} = -2ab - 1$$

$$1 - 4ab = 4a^2b^2 + 4ab + 1$$

$4a^2b^2 + 8ab = 0$, which implies

$4ab(ab + 2) = 0$, then either

$b = 0$, but by the above Lemma (3.2) the backward orbit of P_1 is undefined, so we omit this case.

Or $ab + 2 = 0$, thus

$$b = \frac{-2}{a}.$$

Now, $P_1 = \frac{2}{a}$ and to find the backward orbit of P_1 , we consider

$$h_{a, \frac{-2}{a}}^{-1}(x) = \pm \frac{\sqrt{ax + 2}}{a}.$$

By Lemma (3-b) $h_{a,b}^{-1}(P_1) = \pm P_1$, then

$h_{a,-2}^{-1}\left(\frac{2}{a}\right) = \pm \frac{2}{a}$. But $+\frac{2}{a}$ is a fixed point, therefore

$$h_{a,-2}^{-1}\left(\frac{2}{a}\right) = -\frac{2}{a}.$$

So

$$h_{a,-2}^{-2}\left(\frac{2}{a}\right) = \frac{\sqrt{a\left(\frac{-2}{a}\right)+2}}{a} = 0.$$

$$h_{a,-2}^{-3}\left(\frac{2}{a}\right) = \frac{\sqrt{a(0)+2}}{a} = \frac{\sqrt{2}}{a}, \text{ and so on.}$$

Therefore the backward orbit of $P_1 = \frac{2}{a}$ is:

$$h_{a,-2}^{-n}\left(P_1 = \frac{2}{a}\right) = \left\{\frac{2}{a}, -\frac{2}{a}, 0, \frac{\sqrt{2}}{a}, \dots\right\}. \blacksquare$$

3.4. Example

For $h_{1,-2}(x) = x^2 - 2$, 0 belongs to the backward orbit of $P_1 = 2$ (Figure 1), and the backward orbit of P_1 is $h_{1,-2}^{-n}(2) = \{2, -2, 0, \sqrt{2}, \dots, 2\}$.

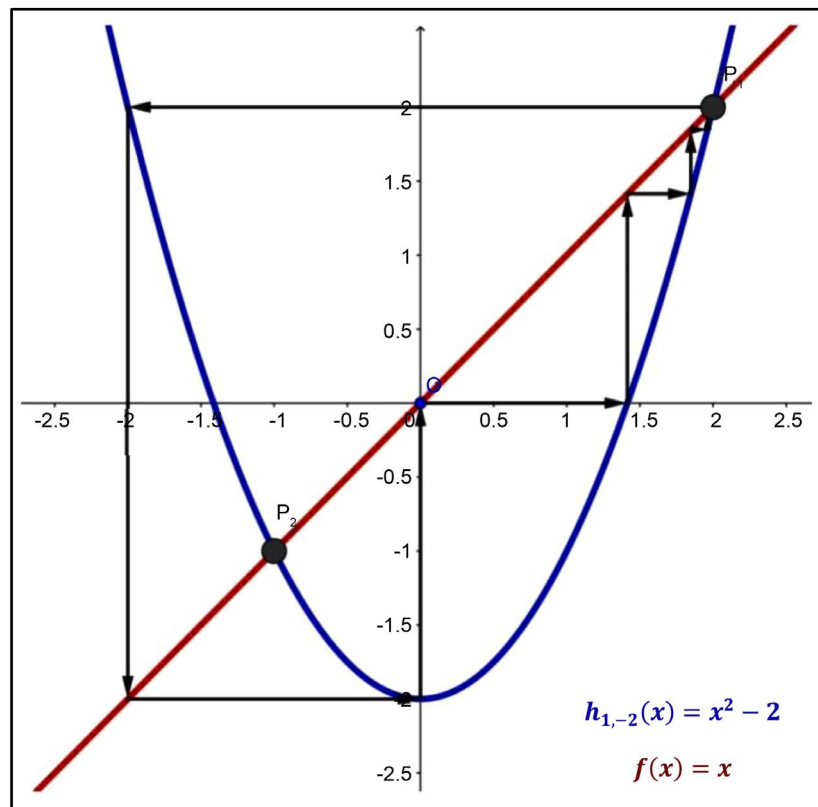


Figure 1. For $h_{1,-2}(x) = x^2 - 2$, the backward orbit of $P_1 = 2$.

3.5. Theorem 2

If $b > \frac{-2}{a}$ for $h_{a,b}(x) \in H$ with $a > 0$, then there is no intersection of the backward orbit with the unstable set of P_1 .

Proof:

The backward orbit of P_1

By Lemma (3-b) $h_{a,b}^{-1}(P_1) = \pm P_1$, since $+P_1$ is a fixed point, then we consider

$$h_{a,b}^{-1}(P_1) = -P_1.$$

By Remark (3-e), $h_{a,b}^{-2}(P_1) = \mp \sqrt{\frac{-P_1 - b}{a}}$.

If $-P_1 > b$, then by Theorem (3-h),

$b \leq \frac{-2}{a}$ which is a contradiction with $b > \frac{-2}{a}$. Therefore

$-P_1 < b$, which implies

$$h_{a,b}^{-2}(P_1) \notin \mathbb{R}.$$

So $h_{a,b}^{-n}(P_1)$ are undefined in \mathbb{R} with $n \geq 2$.

Thus the backward orbit of P_1 is undefined.

So the intersection of $W^u(P_1)$ with the backward orbit of P_1 is also undefined. ■

3.6. Theorem 3

If $b = \frac{-2}{a}$ for $h_{a,b}(x) \in H$ with $a > 0$, then $h_{a, \frac{-2}{a}}$ has a point of homoclinic tangency at 0 associated to P_1 .

Proof:

By Theorem (3.3), $h_{a, \frac{-2}{a}}^{-n}\left(P_1 = \frac{2}{a}\right) = \left\{\frac{2}{a}, -\frac{2}{a}, 0, \frac{\sqrt{2}}{a}, \dots\right\}$.

By Theorem (3-c), $W^u(P_1) = \left(\frac{1}{a} - P_1, \infty\right)$, then

$$W^u\left(P_1 = \frac{2}{a}\right) = \left(\frac{1}{a} - \frac{2}{a}, \infty\right), \text{ i.e.}$$

$$W^u\left(P_1 = \frac{2}{a}\right) = \left(-\frac{1}{a}, \infty\right). \text{ Now}$$

$$h_{a, \frac{-2}{a}}^{-n}\left(\frac{2}{a}\right) \text{ intersects } W^u\left(P_1 = \frac{2}{a}\right) \text{ at } 0.$$

By Lemma (3.1) 0 is a non-degenerate critical point. So $h_{a, \frac{-2}{a}}$ has a point of homoclinic tangency at 0 associated to P_1 . ■

3.7. Theorem 4

If $b < \frac{-2}{a}$ for $h_{a,b}(x) \in H$ with $a > 0$, then the backward orbit of P_1 crosses the unstable set $W^u(P_1)$.

Proof:

First consider the backward orbit of P_1 .

By Lemma (3-b) $h_{a,b}^{-1}(P_1) = \pm P_1$.

But $+P_1$ is a fixed point, therefore we consider

$$h_{a,b}^{-1}(P_1) = -P_1.$$

By Remark (3-e), $h_{a,b}^{-2}(P_1) = \mp \sqrt{\frac{-P_1 - b}{a}}$.

Since $b < \frac{-2}{a}$, then by Theorem (3-h)

$$h_{a,b}^{-2}(P_1) \in \mathbb{R}.$$

Let $h_{a,b}^{-2}(P_1) = q_{1,1}$, $h_{a,b}^{-3}(P_1) = q_{2,1}$.

By Proposition (3-f), if $b < \frac{-(5+2\sqrt{5})}{4a}$, then $q_{1,1} \in W_{loc}^u(P_1)$.

By Proposition (3-g), if $\frac{-(5+2\sqrt{5})}{4a} \leq b < \frac{-2}{a}$, then $q_{2,1} \in W_{loc}^u(P_1)$.

Now since the local unstable set of the repelling fixed point contained in the unstable set of the repelling fixed point. Therefore

$$h_{a,b}^{-n}(P_1) \cap W^u(P_1) \neq \emptyset. \blacksquare$$

Following examples explain the cases for $b > \frac{-2}{a}$, $b = \frac{-2}{a}$ and $b < \frac{-2}{a}$ (with $a > 0$) respectively.

3.8. Example 1

For $h_{1,-1}(x) = x^2 - 1$, we have no intersection of the backward orbit of P_1 with the unstable set of P_1 .

Solution:

Consider the fixed point of $h_{1,-1}(x)$ is $P_1 = \frac{1+\sqrt{5}}{2}$, and

$$h_{1,-1}^{-1}(x) = \pm\sqrt{x+1}.$$

The backward orbit of $P_1 = \frac{1+\sqrt{5}}{2}$

$h_{1,-1}^{-1}\left(\frac{1+\sqrt{5}}{2}\right) = \pm\frac{1+\sqrt{5}}{2}$, where $+\frac{1+\sqrt{5}}{2}$ is a fixed point, therefore we consider

$h_{1,-1}^{-1}\left(\frac{1+\sqrt{5}}{2}\right) = -\frac{1+\sqrt{5}}{2}$. Now

$$h_{1,-1}^{-2}\left(\frac{1+\sqrt{5}}{2}\right) = \mp\sqrt{-\frac{1+\sqrt{5}}{2}+1} \notin \mathbb{R}.$$

So $h_{1,-1}^{-n}\left(\frac{1+\sqrt{5}}{2}\right)$ are undefined in \mathbb{R} with $n \geq 2$.

Thus the backward orbit of P_1 is undefined.

So the intersection of $W^u\left(\frac{1+\sqrt{5}}{2}\right)$ with the backward orbit of P_1 is also undefined. ■

3.9. Example 2

For $h_{1,-2}(x) = x^2 - 2$, then $h_{1,-2}$ has a point of tangency at 0 associated to P_1 .

Solution:

Consider the fixed point of $h_{1,-2}(x)$ is $P_1 = 2$.

By Example (3.4), The backward orbit of $P_1 = 2$ is

$$h_{1,-2}^{-n}(2) = \{2, -2, 0, \sqrt{2}, \dots, 2\}.$$

On the other hand, the unstable set of $P_1 = 2$ is

$W^u(2) = (-1, \infty)$, (see Theorem (3-c)). Now

$h_{1,-2}^{-n}(2)$ intersects $W^u(2)$ at 0.

By Lemma (3.1), 0 is a non-degenerate critical point. So $h_{1,-2}$ has a point of tangency at 0 associated to $P_1 = 2$. ■

3.10. Example 3

For $h_{1,-6}(x) = x^2 - 6$, the backward orbit of P_1 crosses the unstable set $W^u(P_1)$.

Solution:

First consider the fixed point $P_1 = 3$.

The backward orbit of 3 is:

$h_{1,-6}^{-n}(3) = \{3, -3, \sqrt{3}, \dots, 3\}$ (see Example (3-i)), with

$h_{1,-6}^{-1}(3) = h_{1,-2}^2(\sqrt{3})$, and $h_{1,-6}^{-2}(3) = \sqrt{3}$.

Since $\sqrt{3}$ is a homoclinic point of $P_1 = 3$, then

$$\sqrt{3} \in W_{loc}^u(3).$$

Now since the local unstable set of the repelling fixed point $P_1 = 3$ contained in the unstable set of the repelling fixed point $P_1 = 3$. Therefore

$$h_{1,-6}^{-n}(3) \cap W^u(3) \neq \emptyset. \blacksquare$$

Note, the main theorem in the work :

3.11. Theorem 5

$h_{a,b}(x) = ax^2 + b, a > 0$ has a homoclinic bifurcation associated to the repelling fixed point of $h_{a,b}$, $P_1 = \frac{1+\sqrt{1-4ab}}{2a}$, at $b = \frac{-2}{a}$.

Proof:

1) For $b > \frac{-2}{a}$, by Theorem (3.5) the intersection of the backward orbit of P_1 and the unstable set of P_1 is undefined.

2) For $b = \frac{-2}{a}$, by Theorem (3.6) $h_{a, \frac{-2}{a}}$ has a point of homoclinic tangency

associated to P_1 at $x = 0$.

3) For $b < \frac{-2}{a}$, by Theorem (3.7) the backward orbit of P_1 crosses the unstable set of P_1 , $W^u(P_1)$.

Therefore $h_{a,b}$ has a homoclinic bifurcation associated to P_1 at $b = \frac{-2}{a}$. ■

3.12. Example

$h_{1,-2}(x) = x^2 - 2$ has a homoclinic bifurcation associated to the repelling fixed point of $h_{1,-2}$, $P_1 = 2$, at $b = -2$.

$h_{1,-2}(x)$ has a homoclinic bifurcation associated to the repelling fixed point of $h_{1,-2}$, $P_1 = 2$, at $b = -2$. See examples (3.8), (3.9), (3.10).

3.13. Remark

For $a < 0$, we have same results which proved above for $a > 0$. In fact, we can prove in similar ways, that: $h_{a,b}(x) = ax^2 + b, a < 0$ has a homoclinic bifurcation associated to the repelling fixed point of $h_{a,b}$, $P_1 = \frac{1 + \sqrt{1 - 4ab}}{2a}$, at $b = \frac{-2}{a}$.

4. Conclusion

We conclude that the family $H = \{h_{a,b}(x) = ax^2 + b : a \in \mathbb{R} \setminus \{0\}, b \in \mathbb{R}\}$ has homoclinic tangency associated to P_1 at the critical point $x = 0$. Also for $b > \frac{-2}{a}$ we have no intersection between the backward orbit of P_1 and the unstable set of P_1 , and the backward orbit of P_1 crosses the unstable set of P_1 for $b < \frac{-2}{a}$. So we have homoclinic bifurcation at $b = \frac{-2}{a}$.

Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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