

The Onset of Ferromagnetic Convection in a Micropolar Ferromagnetic Fluid Layer Heated from Below

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ABSTRACT

The onset of ferromagnetic convection in a micropolar ferromagnetic fluid layer heated from below in the presence of a uniform applied vertical magnetic field has been investigated. The rigid-isothermal boundaries of the fluid layer are considered to be either paramagnetic or ferromagnetic and the eigenvalue problem is solved numerically using the Galerkin method. It is noted that the paramagnetic boundaries with large magnetic susceptibility χ delays the onset of ferromagnetic convection the most when compared to very low magnetic susceptibility as well as ferromagnetic boundaries. Increase in the value of magnetic parameter M_1 and spin diffusion (couple stress) parameter N_3 is to hasten, while increase in the value of coupling parameter N_1 and micropolar heat conduction parameter N_5 is to delay the onset of ferromagnetic convection. Further, increase in the value of M_1 , N_1 , N_5 and χ as well as decrease in N_3 is to diminish the size of convection cells.

Keywords: Micropolar Ferrofluid; Ferromagnetic Convection; Paramagnetic Boundaries; Rigid Boundaries; Magnetic Susceptibility

1. Introduction

Ferrofluids or magnetic fluids are commercially manufactured colloidal liquids usually formed by suspending mono domain nanoparticles (their diameter is typically 3 - 10 nm) of magnetite in non-conducting liquids like heptane, kerosene, water etc. and they are also called magnetic nanofluids. These fluids get magnetized in the presence of an external magnetic field and due to their both liquid and magnetic properties they have emerged as reliable materials capable of solving complex engineering problems. An extensive literature pertaining to this field and also the important applications of these fluids to many practical problems can be found in the books by Rosensweig [1], Berkovsky *et al.* [2] and Hergt *et al.* [3]. It is also recognized that these fluids have promising potential for heat transfer applications in electronics, micro and nanoelectromechanical systems (MEMS and NEMS), and air-conditioning and ventilation

Several theories were used to describe the motion of ferrofluids and amongst them the continuum description of the ferrofluids has been in existence since the work of Neuringer and Rosensweig [4]. Their theory is called "quasi-stationary theory". Based on this theory, several studies on convective instability in a ferrofluid layer have

been undertaken in the past. Finlayson [5] has studied the convective instability of a magnetic fluid layer heated from below in the presence of a uniform vertical magnetic field. Gotoh and Yamada [6] have carried out the same study by assuming the fluid to be confined between two magnetic pole pieces. Stiles *et al.* [7] have analyzed linear and weakly nonlinear thermoconvective instability in a thin layer of ferrofluid subject to a weak uniform external magnetic field in the vertical direction. Blennerhassett *et al.* [8] have analyzed the heat transfer characteristics in a strongly magnetized ferrofluids. The nonlinear stability analysis for a magnetized ferrofluid layer heated from below has been performed by Sunil and Mahajan [9] for the case of stress free boundaries. Whereas, Nanjundappa and Shivakumara [10] have investigated the effects of variety of velocity and temperature boundary conditions on the onset of thermomagnetic convection in an initially quiescent ferrofluid layer in the presence of a uniform magnetic field. By using quasistationary theory but treating the ferrofluids as binary mixtures, Shliomis [11] and Shliomis and Smorodin [12] have studied convective instability of magnetized ferrofluids by considering the influence of concentration gradients and Soret effects. The latter authors have also pre-

dicted oscillatory instability in a certain region of magnetic field and the fluid temperature. In a review article, Odenbach [13] has focused on recent developments in the field of rheological investigations of ferrofluids and their importance for the general treatment of ferrofluids.

The development of different kinds of ferrofluids exhibiting significant changes in their microstructure has outlined the need of new description for ferrofluids. It is believed that quasi-stationary theory is reasonably valid for colloidal suspensions of Néel particles in which the particle magnetic moment \mathbf{m} rotates inside the particle and the particle does not rotate itself and hence no momentum transfer, from the particle to the fluid, occurs when the applied magnetic field has a changing direction or magnitude. On the other hand, for Brownian particle in which the vector \mathbf{m} is locked into the crystal axis of the particle and rotates along with the particle rotation, with finite magnetic relaxation time, one has to incorporate the intrinsic rotation of the particle and there is thus momentum transfer to the carrier fluid in the form of a viscous friction. Based on these facts, the equations involving rotational or vortex viscosity and the nonequilibrium magnetization equation, involving Brownian relaxation time, are used to discuss thermoconvective instability of a ferrofluid in a strong external magnetic field by Stiles and Kagan [14]. However, more appropriate equations which allow proper consideration of internal rotation and vortex viscosity have been considered by Kaloni and Lou [15] to investigate convective instability problem in the horizontal layer of a magnetic fluid with Brownian relaxation mechanism. Recently, Paras Ram and Kushal Sharma [16] have studied the effect of magnetic field-dependent viscosity (MFD) along with porosity on the revolving Axi-symmetric steady ferrofluid flow with rotating disk.

Since the ferrofluids are colloidal suspensions of nanoparticles, as suggested by Rosensweig [1] in his monograph, it is pertinent to consider the effect of microrotation of the particles in the study. Based on this fact, studies have been undertaken by treating ferrofluids as micropolar fluids and the theory of micropolar fluid proposed by Eringen [17] has been used in investigating the problems. Micropolar fluids have been receiving a great deal of interest and research focus due to their applications like solidification of liquid crystals, the extrusion of polymer fluids, cooling of a metallic plate in a bath colloidal suspension solutions and exotic lubricants. In the uniform magnetic field, the magnetization characteristic depends on particle spin but does not on fluid velocity. Hence micropolar ferrofluid stability studies have become an important field of research these days. Although convective instability problems in a micropolar fluid layer subject to various effects have been studied extensively, the works pertaining to micropolar ferrofluids is

in much-to-be desired state. Many researchers [18-23] have been rigorously investigated the Rayleigh-Benard situation in Eringen's micropolar non-magnetic fluids. From all these studies, they mainly found that stationary convection is the preferred mode for heating from below. Sharma and Kumar [24] and Sharma and Gupta [25] also gave a good understanding of thermal convection of micropolar fluids. Zahn and Greer [26] have considered interesting possibilities in a planar micropolar ferromagnetic fluid flow with an AC magnetic field. They have examined a simpler case where the applied magnetic fields along and transverse to the duct axis are spatially uniform and varying sinusoidally with time. Abraham [27] has investigated the problem of Rayleigh-Benard convection in a micropolar ferromagnetic fluid layer permeated by a uniform magnetic field for stress-free boundaries. Reena and Rana [28,29] have studied the some convection problems on micropolar fluids saturating a porous medium. Recently, Thermal instability problem in a rotating micropolar ferrofluid has also been considered by Qin and Kaloni [30] and Sunil *et al.* [31], and references therein.

However, the increased importance of ferrofluids in many heat transfer applications demand the study of the onset of ferromagnetic convection in a layer of micropolar ferrofluid for more realistic velocity and magnetic boundary conditions. The aim of the present paper is, therefore, to investigate the onset of ferromagnetic convection in a micropolar ferrofluid layer heated from below in the presence of a uniform vertical magnetic field by considering the bounding surfaces as rigid- isothermal and which are either paramagnetic or ferromagnetic. The resulting eigenvalue problem is solved numerically using the Galerkin technique. The critical thermal Rayleigh number and associated wave number account for the stability character.

2. Mathematical Formulation

The physical configuration considered is as shown in **Figure 1**. We consider an initially quiescent horizontal incompressible micropolar ferrofluid layer of characteristic thickness d in the presence of an applied uniform magnetic field H_0 in the vertical direction with the angular momentum ω . The lower and the upper boundaries are rigid-isothermal which are either paramagnetic or ferromagnetic. Let T_0 and $T_1 (< T_0)$ be the temperatures of the lower and upper rigid boundaries, respectively with $\Delta T (= T_0 - T_1)$ being the temperature difference. A Cartesian co-ordinate system (x, y, z) is used with the origin at the bottom of the layer and z -axis is directed vertically upward. Gravity acts in the negative z -direction, $\mathbf{g} = -g\hat{k}$ where \hat{k} is the unit vector in the z -direction.

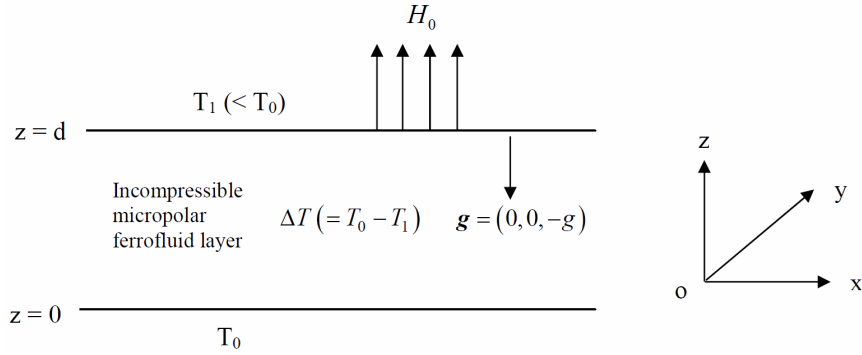


Figure 1. Physical configuration.

The basic equations governing the motion of an incompressible Boussinesq micropolar ferromagnetic fluid for the above model are as follows [1,6,17,30]:

Continuity equation

$$\nabla \cdot \mathbf{q} = 0. \quad (1)$$

Angular momentum equation

$$\rho_0 \left[\frac{\partial \mathbf{q}}{\partial t} + (\mathbf{q} \cdot \nabla) \mathbf{q} \right] = -\nabla p + \rho \mathbf{g} + (\mathbf{B} \cdot \nabla) \mathbf{H} + (\eta + \xi_r) \nabla^2 \mathbf{q} + 2\xi_r (\nabla \times \boldsymbol{\omega}). \quad (2)$$

Internal angular momentum equation

$$\rho_0 I \left[\frac{\partial \boldsymbol{\omega}}{\partial t} + (\mathbf{q} \cdot \nabla) \boldsymbol{\omega} \right] = 2\xi_r [(\nabla \times \mathbf{q}) - 2\boldsymbol{\omega}] + \mu_0 (\mathbf{M} \times \mathbf{H}) + \nabla (\nabla \cdot \boldsymbol{\omega}) + \eta' (\nabla^2 \boldsymbol{\omega}). \quad (3)$$

Energy equation

$$\left[\rho_0 C_{v,H} - \mu_0 \mathbf{H} \cdot \left(\frac{\partial \mathbf{M}}{\partial T} \right)_{v,H} \right] \frac{DT}{Dt} + \mu_0 T \left(\frac{\partial \mathbf{M}}{\partial T} \right)_{v,H} \cdot \frac{D\mathbf{H}}{Dt} = k_1 \nabla^2 T + \delta (\nabla \times \boldsymbol{\omega}) \cdot \nabla T. \quad (4)$$

Equation of state

$$\rho = \rho_0 [1 - \alpha (T - T_0)]. \quad (5)$$

Maxwell's equation in the magnetostatic limit

$$\nabla \cdot \mathbf{B} = 0, \quad \nabla \times \mathbf{H} = 0 \quad \text{or} \quad \mathbf{H} = \nabla \phi \quad (6a,b)$$

$$\mathbf{B} = \mu_0 (\mathbf{M} + \mathbf{H}). \quad (7)$$

It is considered that the magnetization is aligned with the magnetic field and is taken as a function of both magnetic field and temperature in the form

$$\mathbf{M} = \frac{\mathbf{H}}{H} M(H, T). \quad (8)$$

The magnetic equation of state is given by

$$M = M_0 + \chi (H - H_0) - K (T - T_0). \quad (9)$$

In the above equations, $\mathbf{q} = (u, v, w)$ is the velocity of the fluid, p the pressure, ρ the density, η the shear kinematic viscosity co-efficient, ξ_r the vortex (rotational) viscosity, $\boldsymbol{\omega} = (\Omega_1, \Omega_2, \Omega_3)$ the angular (average spin) velocity of colloidal particles along z -axis, I the moment of inertia, ρ_0 the reference density, μ_0 the free space magnetic permeability, η' the shear spin viscosity co-efficient, k_1 the thermal conductivity, T the temperature, α the thermal expansion co-efficient, δ the micropolar heat conduction coefficient, $C_{v,H}$ the specific heat at constant volume and magnetic field, \mathbf{B} the magnetic induction field, \mathbf{H} the magnetic field, H the magnitude of \mathbf{H} , H_0 the constant applied magnetic field, $K = -(\partial M / \partial T)_{H_0, T_0}$ the pyromagnetic co-efficient, \mathbf{M} the magnetization, M the magnitude of \mathbf{M} , $M_0 = M(H_0, T_0)$ the constant mean value of magnetization, $\chi = (\partial M / \partial H)_{H_0, T_0}$ the magnetic susceptibility, ϕ the magnetic potential and

$\nabla^2 = \partial^2 / \partial x^2 + \partial^2 / \partial y^2 + \partial^2 / \partial z^2$ is the Laplacian operator.

The basic state is quiescent and is given by

$$\begin{aligned} p_b(z) &= p_0 - \rho_0 g z - \frac{\rho_0 \alpha \beta g z^2}{2} \\ &\quad - \frac{\mu_0 M_0 K \beta z}{(1 + \chi)} - \frac{\mu_0 K^2 \beta^2 z^2}{2(1 + \chi)^2} \\ T_b(z) &= T_0 - \beta z \\ \rho_b &= \rho_0 [1 - \alpha (T_b - T_0)] \\ \mathbf{H}_b(z) &= \left[H_0 - \frac{K \beta z}{(1 + \chi)} \right] \hat{k} \\ \mathbf{M}_b(z) &= \left[M_0 + \frac{K \beta z}{(1 + \chi)} \right] \hat{k} \end{aligned} \quad (10)$$

where, $\beta = \Delta T / d$ is the temperature gradient and the subscript b denotes the basic state.

To study the stability of the system, the variables are perturbed in the form

$$\begin{aligned} \mathbf{q} &= q', \boldsymbol{\omega} = \boldsymbol{\omega}', p = p_b(z) + p', T = T_b(z) + T', \\ \mathbf{H} &= \mathbf{H}_b(z) + \mathbf{H}', \mathbf{M} = \mathbf{M}_b + \mathbf{M}' \end{aligned} \quad (11)$$

where, $q', \boldsymbol{\omega}', \rho', p', T', \mathbf{H}'$ and \mathbf{M}' are the perturbed quantities whose magnitude is assumed to be very small.

Substituting Equation (11) in Equation (6a) and using Equations (8) and (9) and assuming $K\beta z \ll (1 + \chi)H_0$ as propounded by Finlayson [6], we obtain (after dropping the primes)

$$M_x + H_x = \left(1 + \frac{M_0}{H_0}\right) H_x, M_y + H_y = \left(1 + \frac{M_0}{H_0}\right) H_y, \quad (12)$$

$$M_z + H_z = (1 + \chi)H_z - KT$$

where (H_x, H_y, H_z) and (M_x, M_y, M_z) are the (x, y, z) components of the magnetic field and magnetization respectively.

Using Equation (11) in Equation (2) and linearizing, we obtain (after dropping primes)

$$\begin{aligned} \rho_0 \frac{\partial u}{\partial t} &= -\left(\frac{\partial p}{\partial x}\right) + (\eta + \xi_r) \nabla^2 u + 2\xi_r \Omega_1 \\ &+ \mu_0 (M_0 + H_0) \frac{\partial H_1}{\partial z} \end{aligned} \quad (13)$$

$$\begin{aligned} \rho_0 \frac{\partial v}{\partial t} &= -\left(\frac{\partial p}{\partial y}\right) + (\eta + \xi_r) \nabla^2 v + 2\xi_r \Omega_2 \\ &+ \mu_0 (M_0 + H_0) \frac{\partial H_2}{\partial z} \end{aligned} \quad (14)$$

$$\begin{aligned} \rho_0 \frac{\partial w}{\partial t} &= -\left(\frac{\partial p}{\partial z}\right) + (\eta + \xi_r) \nabla^2 w + 2\xi_r \Omega_3 \\ &+ \mu_0 (M_0 + H_0) \frac{\partial H_3}{\partial z} + \rho_0 \alpha g T \\ &- \mu_0 K \beta H_3 + \frac{\mu_0 \beta K^2 T}{(1 + \chi)}. \end{aligned} \quad (15)$$

Differentiating Equations (13)-(15) partially with respect to x, y and z respectively and adding, we get

$$\begin{aligned} \nabla^2 p &= \mu_0 (M_0 + H_0) \nabla^2 \left(\frac{\partial \phi}{\partial z}\right) \\ &+ \left[\rho_0 \alpha g + \frac{\mu_0 \beta K^2}{(1 + \chi)}\right] \frac{\partial T}{\partial z} - \mu_0 \beta K \left(\frac{\partial^2 \phi}{\partial z^2}\right) \end{aligned} \quad (16)$$

Eliminating the pressure term p from Equation (15), using Equation (16) we get

$$\begin{aligned} \left[\rho_0 \frac{\partial}{\partial t} - (\eta + \xi_r) \nabla^2\right] \nabla^2 w &= -\mu_0 \beta K \nabla_h^2 \left(\frac{\partial \phi}{\partial z}\right) \\ &+ \left[\rho_0 \alpha g + \frac{\mu_0 \beta K^2}{(1 + \chi)}\right] \nabla_h^2 T + 2\xi_r \nabla^2 \Omega_3 \end{aligned} \quad (17)$$

where, $\nabla_h^2 = \partial^2/\partial x^2 + \partial^2/\partial y^2$ is the horizontal Laplacian operator.

Substituting Equation (11) into Equation (3) and linearizing, we obtain (after dropping primes)

$$\rho_0 I \frac{\partial \Omega_3}{\partial t} = -2\xi_r [\nabla^2 w + 2\Omega_3] + \eta \nabla^2 \Omega_3. \quad (18)$$

As before, substituting Equation (11) into Equation (4) and linearizing, we obtain (after dropping primes)

$$\begin{aligned} \left[\rho_0 C_0 \frac{\partial}{\partial t} - k_1 \nabla^2\right] T &= \left[\rho_0 C_0 \beta - \frac{\mu_0 T_0 \beta K^2}{(1 + \chi)}\right] w \\ &+ \mu_0 T_0 K \frac{\partial}{\partial t} \left(\frac{\partial \phi}{\partial z}\right) - \beta \delta \Omega_3 \end{aligned} \quad (19)$$

where, $\rho_0 C_0 = \rho_0 C_{v,H} + \mu_0 K \mathbf{H}_b$. Finally Equations (6), after using Equation (12), yield (after dropping primes)

$$(1 + \chi) \frac{\partial^2 \phi}{\partial z^2} + \left(1 + \frac{M_0}{H_0}\right) \nabla_h^2 \phi - K \frac{\partial T}{\partial z} = 0. \quad (20)$$

The principle of exchange of stability is assumed and the normal mode expansion of the dependent variables is taken in the form

$$\begin{aligned} \{w, T, \phi, \Omega_3\} &= \{W(z), \Theta(z), \Phi(z), \Omega_3(z)\} \\ &\cdot \exp[i(lx + my)] \end{aligned} \quad (21)$$

where, l and m are the wave numbers in the x and y directions, respectively.

Let us non-dimensionalize the variables by setting

$$\begin{aligned} (x^*, y^*, z^*) &= \left(\frac{x}{d}, \frac{y}{d}, \frac{z}{d}\right), \quad D^* = Dd, \quad a^* = ad, \\ W^* &= \frac{d}{\nu} W, \quad \Theta^* = \frac{\kappa}{\beta vd} \Theta, \\ \Phi^* &= \frac{(1 + \chi)\kappa}{K_2 \beta vd^2} \Phi, \quad \Omega_3^* = \frac{d^3}{\nu} \Omega_3, \quad I^* = \frac{1}{d^2} I \end{aligned} \quad (22)$$

where, $\nu = \eta/\rho_0$ is the kinematic viscosity and $\kappa = k_1/\rho_0 C_0$ is the thermal diffusivity. Equation (21) is substituted into Equations (17)-(20) and then Equation (22) is used to obtain the stability equations in the following form:

$$\begin{aligned} (1 + N_1) (D^2 - a^2)^2 W + a^2 R_t [M_1 D \Phi - (1 + M_1) \Theta] \\ + 2N_1 (D^2 - a^2) \Omega_3 = 0 \end{aligned} \quad (23)$$

$$2N_1 [(D^2 - a^2)W + 2\Omega_3] - N_3 (D^2 - a^2) \Omega_3 = 0 \quad (24)$$

$$(D^2 - a^2) \Theta + (1 - M_2)W - N_5 \Omega_3 = 0 \quad (25)$$

$$D^2 \Phi - a^2 M_3 \Phi - D \Theta = 0 \quad (26)$$

where $D = d/dz$ is the differential operator,

$a = \sqrt{\ell^2 + m^2}$ is the horizontal wave number,
 $R_t = \alpha\beta g d^4 / \nu\kappa$ is the thermal Rayleigh number,
 $M_1 = \mu_0 K^2 \beta / (1 + \chi) \rho_0 \alpha g$ is the magnetic number,
 $M_2 = \mu_0 T_0 K^2 / (1 + \chi) \rho_0 C_0$ is the magnetic parameter,
 $M_3 = (1 + M_0 / H_0) / (1 + \chi)$ is the non-linearity of magnetization, $N_1 = \xi_r / \eta$ is the coupling parameter,
 $N_3 = \eta' / \eta d^2$ is the spin diffusion (couple stress) parameter and $N_5 = \delta / \rho_0 C_0 d^2$ is the micropolar heat conduction parameter. The typical value of M_2 for magnetic fluids with different carrier liquids turns out to be of the order of 10^{-6} and hence its effect is neglected when compared to unity.

Equations (23)-(26) are solved using the following boundary conditions:

i) Both boundaries rigid-isothermal and paramagnetic

$$W = 0 = DW, \Omega_3 = 0, \Theta = 0 \text{ at } z = 0, 1 \quad (27a)$$

$$D\Phi = \begin{cases} a\Phi / (1 + \chi), & \text{at } z = 0 \\ -a\Phi / (1 + \chi), & \text{at } z = 1. \end{cases} \quad (27b)$$

ii) Both boundaries rigid-isothermal and ferromagnetic

$$W = 0 = DW, \Omega_3 = 0, \Theta = 0, \Phi = 0 \text{ at } z = 0, 1. \quad (27c)$$

3. Numerical Solution

Equations (23)-(26) together with the boundary conditions (27a,b) or (27c) constitute an eigenvalue problem with the thermal Rayleigh number R_t as the eigenvalue. For the boundary conditions considered, it is not possible to obtain the solution to the eigenvalue problem in closed form and hence it is solved numerically using the Galerkin-type weighted residuals method. Accordingly, the variables are written in a series of basis functions as

$$W(z) = \sum_{i=1}^N A_i W_i(z), \Omega_3 = \sum_{i=1}^N C_i \Omega_{3i}(z), \quad (28)$$

$$\Theta(z) = \sum_{i=1}^N D_i \Theta_i(z), \Phi(z) = \sum_{i=1}^N E_i \Phi_i(z)$$

where, A_i, C_i, D_i and E_i are the unknown constants to be determined. The basis functions $W_i(z), \Omega_{3i}(z), \Theta_i(z)$ and $\Phi_i(z)$ are generally chosen such that they satisfy the corresponding boundary conditions but not the differential equations. Substituting Equation (28) into Equations (23)-(26), multiplying the resulting momentum equation by $W_j(z)$, angular momentum equation by $\Omega_{3j}(z)$, temperature equation by $\Theta_j(z)$ and the magnetic potential equation by $\Phi_j(z)$; performing the integration by parts with respect to z between $z = 0$ and $z = 1$ and using the boundary conditions (27a,b) or (27c), we obtain the following system of $4n$ linear homogeneous algebraic equations in the $4n$ unknowns

A_i, C_i, D_i and $E_i; i = 1, 2, \dots, n$:

$$C_{ji} A_i + D_{ji} C_i + E_{ji} D_i + F_{ji} E_i = 0 \quad (29)$$

$$G_{ji} A_i + H_{ji} E_i = 0 \quad (30)$$

$$I_{ji} A_i + J_{ji} C_i + K_{ji} E_i = 0 \quad (31)$$

$$L_{ji} C_i + P_{ji} D_i = 0. \quad (32)$$

The coefficients $C_{ji} - P_{ji}$ involve the inner products of the basis functions and are given by

$$C_{ji} = (1 + N_1) \left[\langle D^2 W_j D^2 W_i \rangle + 2a^2 \langle DW_j DW_i \rangle + a^4 \langle W_j W_i \rangle \right]$$

$$D_{ji} = -a^2 R_t (1 + M_1) \langle W_j \Theta_i \rangle$$

$$E_{ji} = a^2 R_t M_1 \langle W_j D\Phi_i \rangle$$

$$F_{ji} = -2N_1 \left[\langle DW_j D\Omega_{3i} \rangle + a^2 \langle W_j \Omega_{3i} \rangle \right]$$

$$G_{ji} = 2N_1 \left[\langle D\Omega_{3j} DW_i \rangle + a^2 \langle \Omega_{3j} W_i \rangle \right]$$

$$H_{ji} = - \left[4N_1 \langle \Omega_{3j} \Omega_{3i} \rangle + N_3 \left\{ \langle D\Omega_{3j} D\Omega_{3i} \rangle + a^2 \langle \Omega_{3j} \Omega_{3i} \rangle \right\} \right]$$

$$I_{ji} = (1 - M_2) \langle \Theta_j W_i \rangle$$

$$J_{ji} = - \left[\langle D\Theta_j D\Theta_i \rangle + a^2 \langle \Theta_j \Theta_i \rangle \right]$$

$$K_{ji} = -N_5 \langle \Theta_j \Omega_{3i} \rangle$$

$$L_{ji} = \langle \Phi_j D\Theta_i \rangle$$

$$P_{ji} = \frac{a}{2(1 + \chi)} + \langle D\Phi_j D\Phi_i \rangle + a^2 M_3 \langle \Phi_j \Phi_i \rangle \quad (33)$$

where the inner product is defined as $\langle \cdot \rangle = \int_0^1 (\cdot) dz$.

The above set of homogeneous algebraic equations can have a non-trivial solution if and only if

$$\begin{vmatrix} C_{ji} & D_{ji} & E_{ji} & F_{ji} \\ G_{ji} & 0 & 0 & H_{ji} \\ I_{ji} & J_{ji} & 0 & K_{ji} \\ 0 & L_{ji} & P_{ji} & 0 \end{vmatrix} = 0. \quad (34)$$

The eigenvalue has to be extracted from the above characteristic equation. For this, we select the trial functions as follows:

Case i): Rigid-paramagnetic boundaries

$$W_i = (z^4 - 2z^3 + z^2) T_{i-1}^*, \Omega_{3i} = (z^2 - z) T_{i-1}^*, \quad (35)$$

$$\Theta_i = (z^2 - z) T_{i-1}^*, \Phi_i = (z - 1/2) T_{i-1}^*$$

Case ii): Rigid-ferromagnetic boundaries

$$\begin{aligned}
 W_i &= (z^4 - 2z^3 + z^2)T_{i-1}^*, \Omega_{3i} = (z^2 - z)T_{i-1}^*, \\
 \Theta_i &= (z^2 - z)T_{i-1}^*, \Phi_i = (z^2 - z)T_{i-1}^*
 \end{aligned}
 \tag{36}$$

where T_i^* 's are the modified Chebyshev polynomials. It may be noted that the trial function Φ_i does not satisfy the corresponding boundary conditions in the case of paramagnetic boundaries but the residual technique is used for the function Φ_i (see [6]) and the first term on the right hand side of P_{ji} represents the residual term. In the case of ferromagnetic boundaries, Φ_i satisfies the corresponding boundary conditions and hence prevents the use of residual technique. Then the coefficient P_{ji} is given by

$$P_{ji} = \langle D\Phi_j D\Phi_i \rangle + a^2 M_3 \langle \Phi_j \Phi_i \rangle. \tag{37}$$

The characteristic Equation (34) is solved numerically for different values of physical parameters using the Newton-Raphson method to obtain the Rayleigh number R_i as a function of wave number a and the bisection method is built-in to locate the critical stability parameters (R_{ic}, a_c) to the desired degree of accuracy.

4. Results and Discussion

The classical linear stability analysis has been carried out to investigate the onset of ferromagnetic convection in a horizontal micropolar ferrofluid layer. The lower and upper boundaries are considered to be rigid-isothermal which are either paramagnetic or ferromagnetic. The critical thermal Rayleigh number (R_{ic}) and the corresponding wave number (a_c) are used to characterize the stability of the system. The critical stability parameters computed numerically by the Galerkin method as explained above, are found to converge by considering nine terms in the Galerkin expansion. To validate the numerical solution procedure used, a new magnetic parameter S , independent of the temperature gradient, was introduced in the form $R_m = R_i^2/S$, where $S = (1 + \chi)\rho_0 g^2 \alpha^2 d^4 / \mu_0 K^2 \kappa \nu$. The critical thermal Rayleigh number (R_{ic}), critical magnetic Rayleigh number (R_{mc}) and the corresponding wave number (a_c) computed numerically in the absence of micropolar effects ($N_1 = N_3 = N_5 = 0$) are compared in **Table 1** with the previously published results of Blennerhassett *et al.* [8]. It is seen that our results for different values of S are in good agreement. Also, it is instructive to know the processes of convergence of results as the number of terms in the Galerkin approximation increases for the problem considered. Hence, various levels of the approximations to the critical thermal Rayleigh number R_{ic} and the corresponding wave number are also obtained for different values of N_1 when $M_3 = 1$, $R_m = R_i M_1 = 100$,

Table 1. Comparison of R_{ic} and R_{mc} for different values of S with $N_1 = N_3 = N_5 = 0$ (i.e., in the absence of micropolar effect). (a) When heated from below; (b) When heated from above.

(a)						
S	Blennerhassett <i>et al.</i> [10]			Present Analysis		
	R_{ic}	a_c	R_{mc}	R_{ic}	a_c	R_{mc}
0	0	3.6088	2568.47	0	3.60874	2568.76
10^{-2}	5.06	3.6075	2561.11	5.06102	3.60743	2561.39
10^{-1}	15.95	3.6047	2545.24	15.9547	3.60462	2545.53
1	49.96	3.5958	2495.69	49.9597	3.59579	2495.97
10	153.13	3.5688	2344.99	153.142	3.56877	2345.26
10^2	438.75	3.4920	1925.02	438.777	3.49195	1925.26
10^3	1024.48	3.3252	1049.56	1024.55	3.32519	1049.71
10^4	1552.74	3.1649	241.10	1552.88	3.16488	241.136
10^5	1689.47	3.1221	28.54	1689.63	3.12208	28.5409
∞	1707.76	3.1163	0	1707.73	3.11638	0.0

(b)						
S	Blennerhassett <i>et al.</i> [10]			Present Analysis		
	R_{ic}	a_c	R_{mc}	R_{ic}	a_c	R_{mc}
0	0	3.6088	2568.47	0	3.60874	2568.76
10^{-2}	-5.08	3.6101	2575.9	-5.08	3.61005	2576.15
10^{-1}	-16.10	3.6129	2591.9	-16.10	3.61289	2592.19
1	-51.41	3.6220	2643.3	-51.41	3.62197	2643.54
10	-167.69	3.6516	2811.9	-167.69	3.65154	2812.22
10^2	-584.04	3.7536	3411.0	-584.04	3.75355	3411.34
10^3	-2455.05	4.1464	6027.3	-2455.05	4.1463	6027.65
10^4	-14797.1	5.5105	21895	-14797.1	5.51039	21895.8
10^5	-119091	8.2382	141827	-119091	8.23459	141816

$N_3 = 2$, $N_5 = 1$ and the results are tabulated in **Table 2** for different types of magnetic boundary conditions. It is seen that with an increase in the number of terms in the Galerkin approximation, R_{ic} goes on decreasing and finally for the order $i = j = 9$ the results converge. This clearly demonstrates the accuracy of the numerical procedure employed in solving the problem. The critical values obtained for different values of N_1 and S as well as for two values of $N_3 = 2$ and 6 are exhibited in **Table 3**. It may be noted that as S increases the magnetic Rayleigh number R_m decreases, while the value of the critical Rayleigh number R_{ic} increases. This implies that, in some favorable circumstances it is possible for the magnetic mechanism alone to induce convection.

The neutral stability curves (R_i against a) for different values of M_1, N_1, N_3 and N_5 are shown respectively in **Figures 2-5** for paramagnetic/ferromagnetic boundaries. The neutral curves exhibit single but

Table 2. Critical values of R_{ic} and a_c for different values of N_1 when $M_3 = 1, R_m = 100, N_3 = 2$ and $N_5 = 1$: (a) Paramagnetic boundaries when $1 + \chi = 8$; (b) Paramagnetic boundaries when $\chi = 0$; (c) Ferromagnetic boundaries.

(a)										
N_1	$i = j = 1$		$i = j = 3$		$i = j = 5$		$i = j = 8$		$i = j = 9$	
	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c
0	1692.812	3.14012	1658.586	3.14784	1658.084	3.14792	1658.083	3.14792	1658.083	3.14792
0.2	2529.982	3.11900	2495.969	3.13195	2495.065	3.13204	2495.064	3.13205	2495.064	3.13205
0.4	3821.487	3.08148	3813.226	3.10318	3811.682	3.10335	3811.681	3.10336	3811.681	3.10336
0.6	6049.422	3.00816	6166.736	3.04365	6164.059	3.04397	6164.060	3.04397	6164.060	3.04397
0.8	10707.379	2.84549	11477.222	2.89729	11472.309	2.89794	11472.317	2.89794	11472.317	2.89794

(b)										
N_1	$i = j = 1$		$i = j = 3$		$i = j = 5$		$i = j = 8$		$i = j = 9$	
	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c
0	1673.024	3.12985	1644.147	3.13635	1643.612	3.13648	1643.611	3.13649	1643.611	3.13649
0.2	2510.090	3.11210	2481.449	3.12425	2480.512	3.12438	2480.511	3.12439	2480.511	3.12439
0.4	3801.401	3.07695	3798.544	3.09814	3796.967	3.09833	3796.966	3.09834	3796.966	3.09834
0.6	6028.949	3.00539	6151.699	3.04056	6148.990	3.04090	6148.991	3.04090	6148.991	3.04090
0.8	10686.048	2.84409	11461.278	2.89572	11456.336	2.89637	11456.344	2.89637	11456.344	2.89637

(c)										
N_1	$i = j = 1$		$i = j = 3$		$i = j = 5$		$i = j = 8$		$i = j = 9$	
	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c	R_{ic}	a_c
0	1649.975	3.11652	1628.295	3.12105	1627.728	3.12124	1627.727	3.12124	1627.727	3.12124
0.2	2486.932	3.10307	2465.523	3.11397	2464.554	3.11414	2464.553	3.11415	2464.553	3.11415
0.4	3778.005	3.07093	3782.424	3.09135	3780.815	3.09157	3780.815	3.09157	3780.815	3.09157
0.6	6005.043	3.00158	6135.118	3.03633	6132.378	3.03668	6132.380	3.03668	6132.380	3.03668
0.8	10660.918	2.84198	11443.449	2.89346	11438.477	2.89411	11438.485	2.89411	11438.485	2.89411

Table 3. Critical values of R_{ic} and R_{mc} for different values of N_1 with $M_3 = 1$ and $N_5 = 1$.

N_3	N_1	$S = 10^{-2}$			$S = 10^2$		
		R_{ic}	a_c	R_{mc}	R_{ic}	a_c	R_{mc}
2	0	5.06079	3.60743	2561.15669	438.754	3.49195	1925.05399
	0.2	5.53993	3.60708	3069.08746	486.25	3.50052	2364.39091
	0.4	5.97264	3.60614	3567.24704	529.19448	3.50662	2800.46800
	0.6	6.36872	3.60496	4056.06846	568.53897	3.51117	3232.36568
	0.8	6.73495	3.60373	4535.95975	604.94257	3.51473	3659.55514
6	0	5.06079	3.60743	2561.15669	438.754	3.49195	1925.05453
	0.2	5.54297	3.60738	3072.44943	486.554	3.50085	2367.34421
	0.4	5.98366	3.60709	3580.41825	530.297	3.50763	2812.15115
	0.6	6.39148	3.60665	4085.10372	570.816	3.51299	3258.31489
	0.8	6.77241	3.60614	4586.54893	608.691	3.51732	3705.04294

different minimum with respect to the wave number and their shape is identical in the form to that of Benard problem in a micropolar fluid layer. For increasing M_1 (see **Figure 2**), N_1 (see **Figure 3**), N_5 (see **Figure 4**) and decreasing N_3 (see **Figure 5**), the neutral curves are slanted towards the higher wave number region. From the figures, it is also seen that increasing χ is to

shift the neutral curves towards the higher wave number region. Moreover, the effect of increasing M_1 and N_3 as well as decreasing N_1 , N_5 and χ is to decrease the region of stability.

Figure 6(a) represents the variation of critical Rayleigh number R_c as a function of N_1 for different values of M_1 and χ for $M_3 = 5$, $N_3 = 2$ and

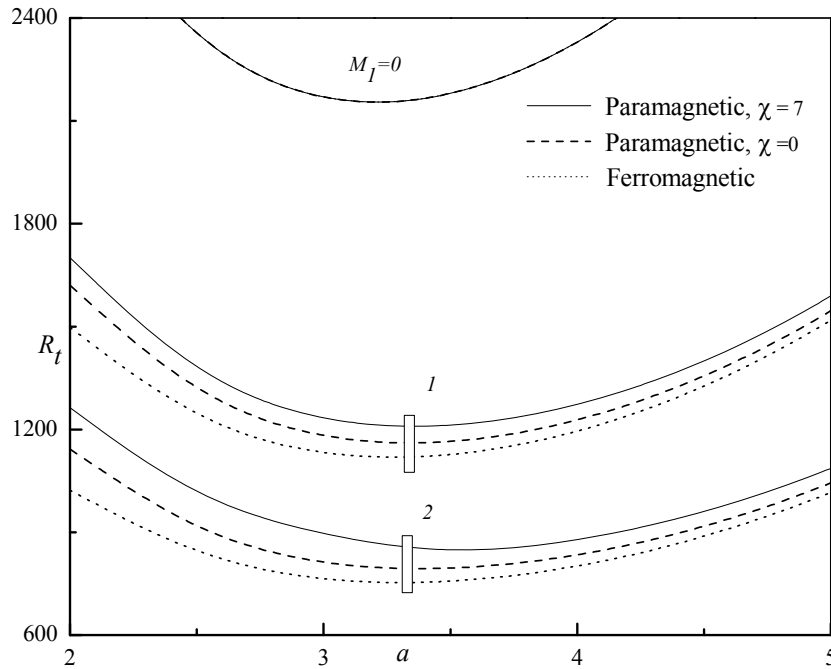


Figure 2. Neutral curves for different values of M_1 when $M_3 = 5$, $N_1 = 0.2$, $N_3 = 2$ and $N_5 = 0.5$.

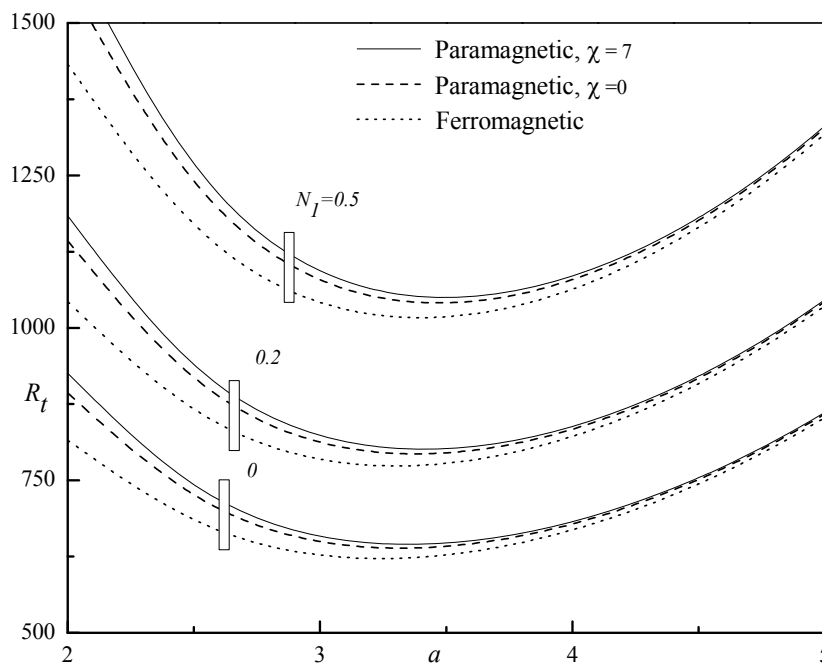


Figure 3. Neutral curves for different values of N_1 when $M_1 = 2$, $M_3 = 5$, $N_3 = 2$ and $N_5 = 0.5$.

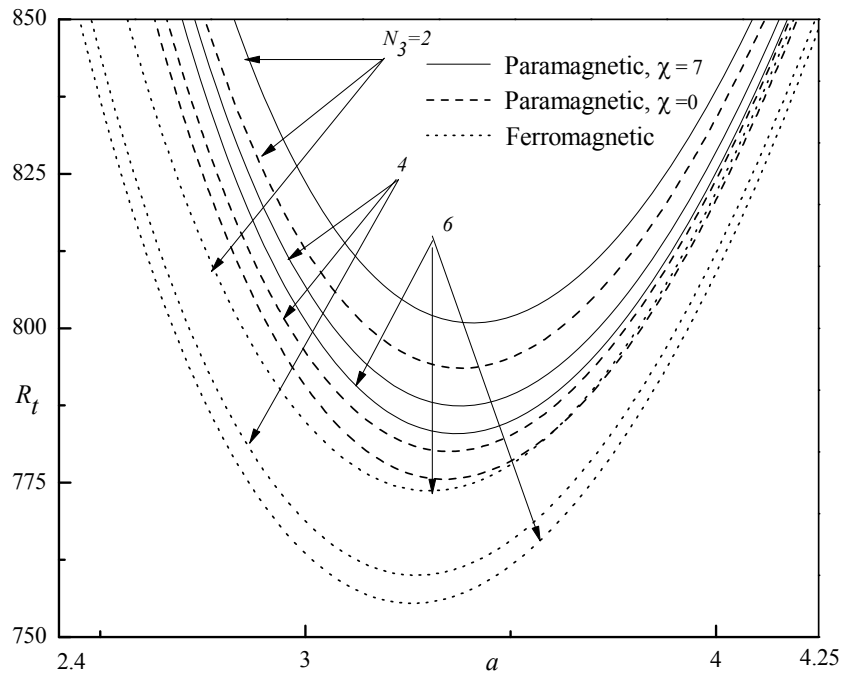


Figure 4. Neutral curves for different values of N_3 when $M_1 = 2$, $M_3 = 5$, $N_1 = 0.2$ and $N_5 = 0.5$.

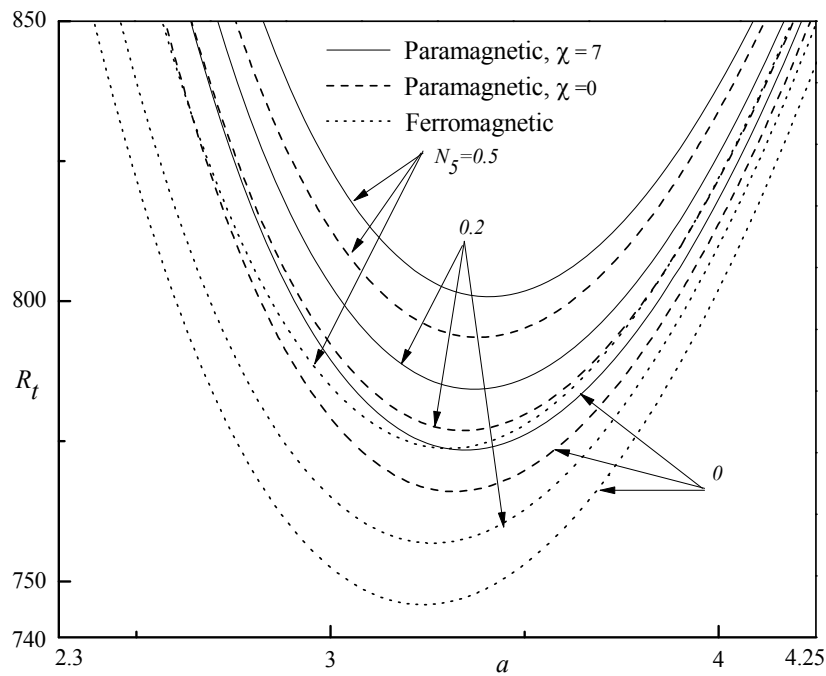


Figure 5. Neutral curves for different values of N_5 when $M_1 = 2$, $M_3 = 5$, $N_1 = 0.2$ and $N_3 = 2$.

$N_5 = 0.5$ for both ferromagnetic and paramagnetic boundary conditions. It is seen that R_{ic} decreases with an increase in the value of M_1 and hence its effect is to hasten the onset of ferroconvection due to an increase in the destabilizing magnetic force and the curve for $M_1 = 0$ corresponds to non-magnetic micropolar fluid case. In other words, heat is transported more efficiently

in magnetic fluids as compared to ordinary micropolar fluids. Also observed that R_{ic} increases with increasing N_1 . This is because, as N_1 increases the concentration of microelements also increases and as a result a greater part of the energy of the system is consumed by these elements in developing gyration velocities in the fluid which ultimately leads to delay in the onset of ferromag-

netic convection. Moreover, the system is found to be more stable if the boundaries are paramagnetic with $\chi = 7$ as compared to the case of $\chi = 0$ and the system is least stable if the boundaries are ferromagnetic. A closer inspection of the figure further depicts that the deviation in the R_{tc} values for different magnetic boundary conditions is more pronounced with increasing coupling parameter. In **Figure 6(b)** plotted the critical wave

number a_c as a function of N_1 . It is evident that increasing N_1 , χ and M_1 is to increase the value of a_c and thus their effect is to reduce the dimension of the convection cells.

In **Figure 7(a)** plotted R_{tc} as a function of N_1 for different values of spin diffusion (couple stress) parameter N_3 when $M_1 = 2$, $M_3 = 5$ and $N_3 = 0.5$. Here, it is observed that R_{tc} curves for different N_3 coalesce

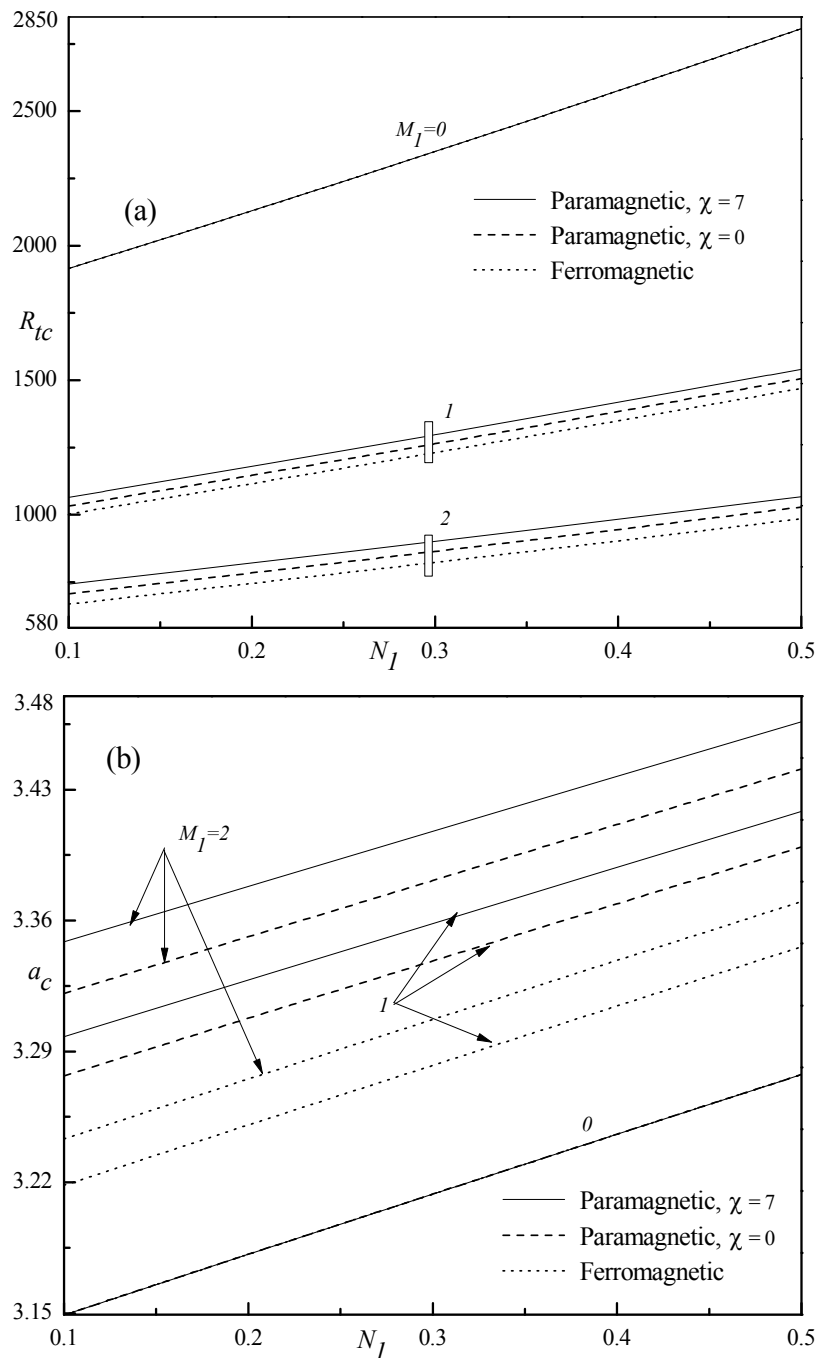


Figure 6. Variation of (a) R_{tc} and (b) a_c as a function of N_1 for different values of M_1 when $M_3 = 5$, $N_3 = 2$ and $N_5 = 0.5$.

when $N_1 = 0$. The impact of N_3 on the stability characteristics of the system is noticeable clearly with increasing N_1 and then it is seen that the critical Rayleigh number decreases with increasing N_3 indicating the spin diffusion (couple stress) parameter N_3 has a destabilizing effect on the system. This may be attributed to the fact that as N_3 increases, the couple stress of the fluid increases, which leads to a decrease in microrotation and hence the system becomes more unstable. **Figure 7(b)** illustrates that increase in N_1 and decrease in N_3 for non-zero values of N_1 is to increase a_c and hence their effect is to decrease the size of convection cells.

The variation of critical thermal Rayleigh number R_{tc}

as a function of N_1 for different values of N_5 for $M_1 = 2$, $M_3 = 5$ and $N_3 = 2$ is shown in **Figure 8(a)**. It is observed that increasing micropolar heat conduction parameter N_5 always has a stabilizing effect for nonzero values of N_1 . When N_5 increases, the heat induced into microelements of the fluid is also increased, thus decreasing the heat transfer from the bottom to the top. This decrease in heat transfer is responsible for delaying the onset of ferromagnetic convection. **Figure 8(b)** illustrates that increase in N_1 and N_5 is to increase a_c and hence their effect is to decrease the size of convection cells.

Figure 9 shows the locus of the critical thermal Rayleigh number R_c and the critical magnetic Rayleigh

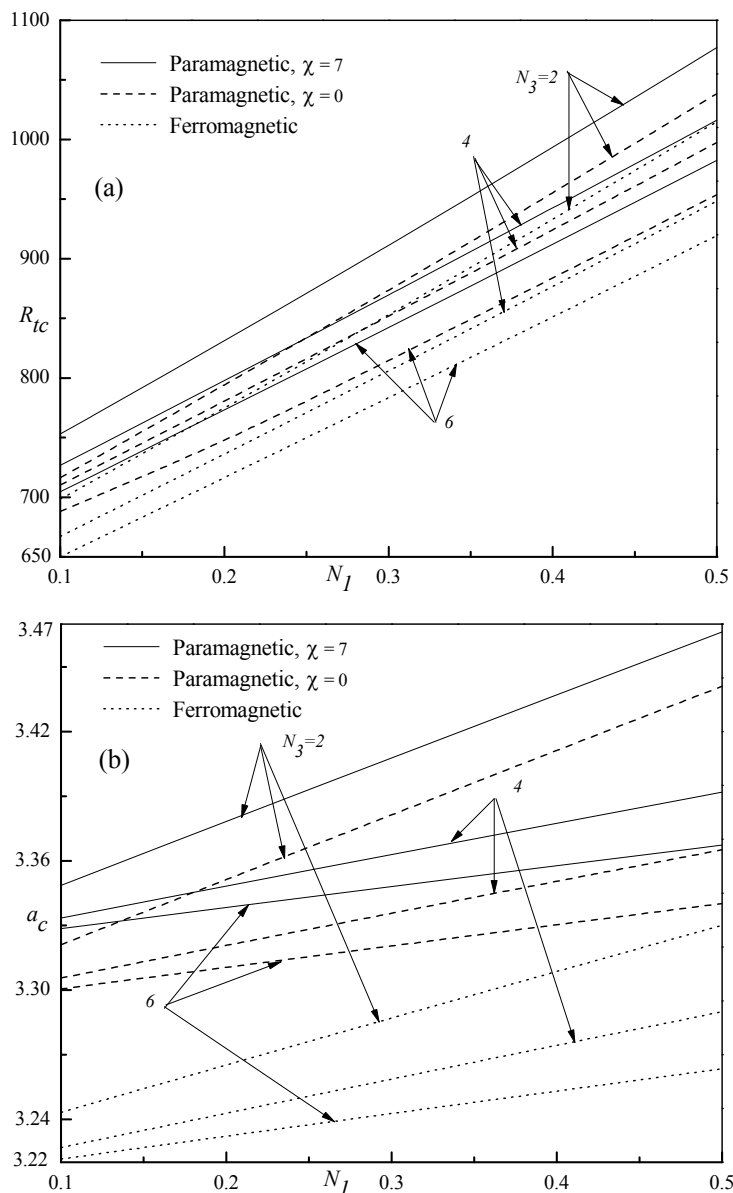


Figure 7. Variation of (a) R_{tc} and (b) a_c as a function of N_1 for different values of N_3 when $M_1 = 2$, $M_3 = 5$ and $N_5 = 0.5$.

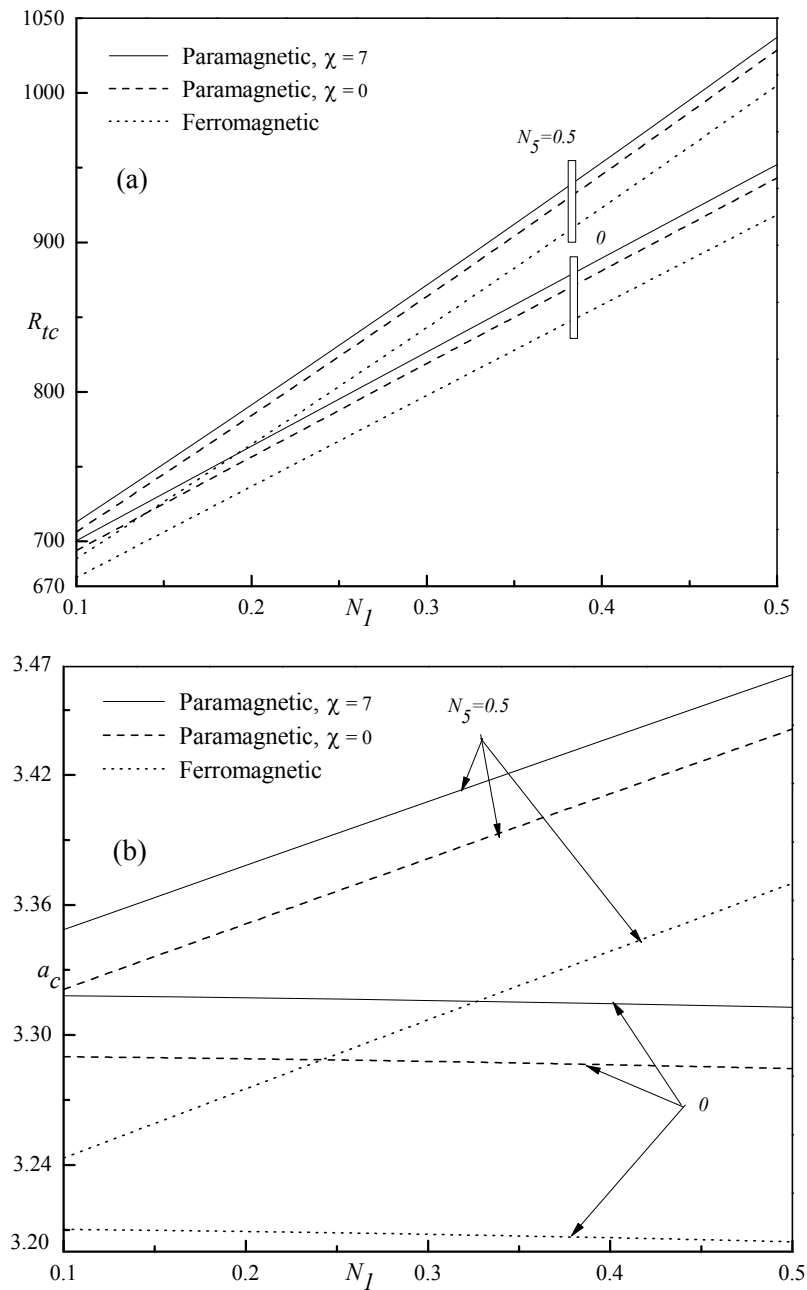


Figure 8. Variation of (a) R_{tc} and (b) a_c as a function of N_1 for different values of N_5 for $M_1 = 2$, $M_3 = 5$ and $N_3 = 2$.

R_{mc} for $M_3 = 5$, $N_1 = 0.2$, $N_3 = 2$ and $N_5 = 0.5$. In the figure, the regions above and below the curves, correspond, respectively, to unstable and stable ones. It is observed that there is a strong coupling between the critical thermal Rayleigh and the magnetic Rayleigh numbers such that an increase in the one decreases the other. Thus, when the buoyancy force is predominant, the magnetic force becomes negligible and vice-versa. The stability curves are slightly convex and in the absence of buoyancy forces ($R_{tc} = 0$), the instability sets in at higher values of

R_{mc} indicating the system is more stable when the magnetic forces alone are present. The stability region increases with increasing χ and also for paramagnetic boundaries when compared to ferromagnetic boundaries.

5. Conclusions

The linear stability theory is used to investigate the onset of ferromagnetic convection in a micropolar ferromagnetic fluid layer heated from below in the presence of a

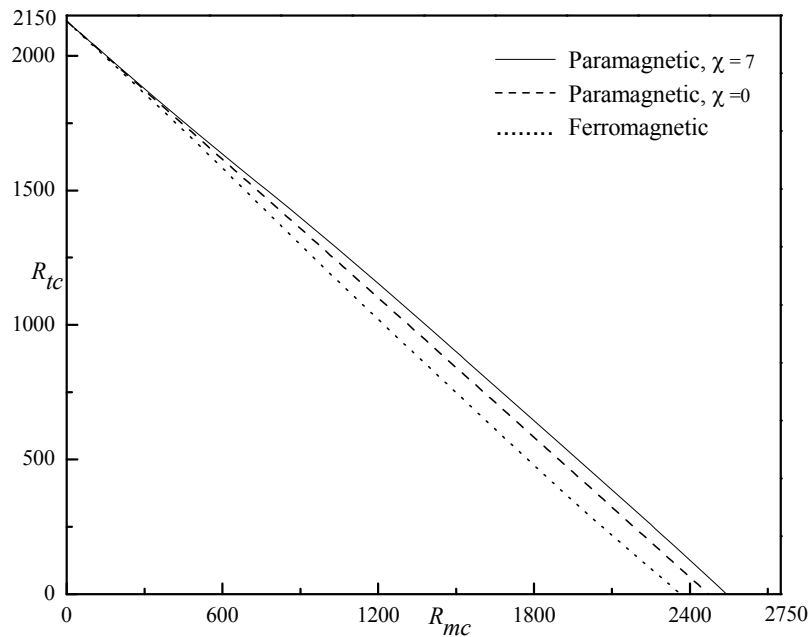


Figure 9. Locus of R_{tc} and R_{mc} for $M_3 = 5$, $N_1 = 0.2$, $N_3 = 2$ and $N_5 = 0.5$.

uniform applied vertical magnetic field for more realistic rigid boundary conditions which are considered to be either paramagnetic or ferromagnetic. The resulting eigenvalue problem is solved numerically by employing the Galerkin method.

From the foregoing study, the following conclusions may be drawn:

i) The neutral stability curves for various values of physical parameters exhibit that the onset of ferromagnetic convection retains its unimodal shape with one distinct minimum which defines the critical thermal Rayleigh number and the corresponding wave number.

ii) The system is more stabilizing against the ferromagnetic convection if the boundaries are paramagnetic with high magnetic susceptibility and least stable if the boundaries are ferromagnetic. It is observed that

$$\begin{aligned} (R_{tc} \text{ and } a_c)_{\chi \neq 0} &> (R_{tc} \text{ and } a_c)_{\chi = 0} \\ &> (R_{tc} \text{ and } a_c)_{\text{rigid-ferromagnetic}} \end{aligned}$$

iii) The effect of increasing the value of magnetic number M_1 is to hasten the onset of ferromagnetic convection.

iv) The effect of increasing the value of coupling parameter N_1 and micropolar heat conduction parameter N_5 is to delay, while increasing the spin diffusion (couple stress) parameter N_3 is to hasten the onset of ferromagnetic convection.

v) The effect of increasing N_1 , N_5 , χ and M_1 as well as decrease in N_3 is to increase the critical wave number.

vi) The magnetic and buoyancy forces are comple-

mentary with each other and the system is more stabilizing when the magnetic forces alone are present.

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