

# Nonlinear Super Integrable Couplings of Super Yang Hierarchy and Its Super Hamiltonian Structures

Sixing Tao, Yunling Ma

School of Mathematics and Statics, Shangqiu Normal University, Shangqiu, China  
Email: taosixing@163.com

**How to cite this paper:** Tao, S.X. and Ma, Y.L. (2017) Nonlinear Super Integrable Couplings of Super Yang Hierarchy and Its Super Hamiltonian Structures. *Journal of Applied Mathematics and Physics*, 5, 792-800.

<https://doi.org/10.4236/jamp.2017.54068>

**Received:** March 5, 2017

**Accepted:** April 9, 2017

**Published:** April 12, 2017

---

## Abstract

Nonlinear super integrable couplings of the super Yang hierarchy based upon an enlarged matrix Lie super algebra were constructed. Then its super Hamiltonian structures were established by using super trace identity. As its reduction, nonlinear integrable couplings of Yang hierarchy were obtained.

## Keywords

Lie Super Algebra, Nonlinear Super Integrable Couplings, Super Yang Hierarchy, Super Hamiltonian Structures

---

## 1. Introduction

With the development of soliton theory, super integrable systems associated with Lie superalgebra have aroused growing attentions by many mathematicians and physicists. It was known that super integrable systems contained the odd variables, which would provide more prolific fields for mathematical researchers and physical ones. Several super integrable systems including super AKNS hierarchy, super KdV hierarchy, super KP hierarchy etc., have been studied in [1] [2] [3] [4]. There are some interesting results on the super integrable systems, such as Darboux transformation [5], super Hamiltonian structures in [6] [7], binary nonlinearization [8] and reciprocal transformation [9] and so on.

There search of integrable couplings of the well known integrable hierarchy has received considerable attention [10] [11] [12]. A few approaches to construct linear integrable couplings of the classical soliton equation are presented by permutation, enlarging spectral problem, using matrix Lie algebra [12] constructing new loop Lie algebra and creating semi-direct sums of Lie algebra. Zhang [13] once employed two kinds of explicit Lie algebra  $F$  and  $G$  to obtain

the nonlinear integrable couplings of the GJ hierarchy and Yang hierarchy, respectively. Recently, You [14] presented a scheme for constructing nonlinear super integrable couplings for the super integrable hierarchy.

Inspired by Zhang [13] and You [14], we hope to construct nonlinear super integrable couplings of the super Yang hierarchy through enlarging matrix Lie super algebra. We take the Lie algebra  $sl(2|1)$  as an example to illustrate the approach for extending Lie super algebras. Based on the enlarged Lie super algebra  $sl(4|1)$ , we work out nonlinear super integrable Hamiltonian couplings of the super Yang hierarchy. Finally, we will reduce the nonlinear super Yang integrable Hamiltonian couplings to some special cases.

## 2. Enlargement of Lie Super Algebra

Consider the Lie super algebra  $sl(2|1)$ . Its basis is

$$E_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, E_2 = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, E_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, E_4 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix}, E_5 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}. \quad (1)$$

where  $E_1, E_2, E_3$  are even element and  $E_4, E_5$  are odd elements. Their non-zero (anti) commutation relations are

$$\begin{aligned} [E_1, E_2] &= -2E_3, [E_1, E_3] = -2E_2, [E_1, E_4] = E_5, [E_1, E_5] = E_4, [E_2, E_3] = -2E_1, \\ [E_2, E_4] &= -E_5, [E_2, E_5] = E_4, [E_3, E_4] = E_4, [E_3, E_5] = -E_5, [E_4, E_4] = -(E_1 + E_2), \\ [E_4, E_5] &= [E_5, E_4] = E_3, [E_5, E_5] = E_1 - E_2. \end{aligned} \quad (2)$$

Let us enlarge the Lie super algebra  $sl(2|1)$  to the Lie super algebra  $sl(4|1)$  with a basis

$$\begin{aligned} e_1 &= \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, e_3 = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, e_4 = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \\ e_5 &= \begin{pmatrix} 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, e_6 = \begin{pmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, e_7 = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 \end{pmatrix}, e_8 = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 \end{pmatrix}. \end{aligned} \quad (3)$$

where  $e_1, e_2, e_3, e_4, e_5, e_6$  are even, and  $e_7, e_8$  are odd.

The generator of Lie super algebra  $sl(4|1)$ ,  $e_i (1 \leq i \leq 8)$  satisfy the following (anti) commutation relations:

$$\begin{aligned} [e_1, e_2] &= -2e_3, [e_1, e_3] = -2e_2, [e_1, e_5] = -2e_6, [e_1, e_6] = -2e_5, [e_1, e_7] = e_8, [e_1, e_8] = e_7, [e_2, e_3] = -2e_1, [e_2, e_4] = 2e_6, \\ [e_2, e_6] &= -2e_4, [e_2, e_7] = -e_8, [e_2, e_8] = e_7, [e_3, e_4] = 2e_5, [e_3, e_5] = 2e_4, [e_3, e_7] = e_7, [e_3, e_8] = -e_8, [e_4, e_5] = -2e_6, \\ [e_4, e_6] &= -2e_5, [e_5, e_6] = -2e_4, [e_7, e_7] = -e_1 - e_2 + e_4 + e_5, [e_7, e_8] = [e_8, e_7] = e_3 - e_6, [e_8, e_8] = e_1 - e_2 - e_4 + e_5, \\ [e_1, e_4] &= [e_2, e_5] = [e_3, e_6] = [e_4, e_7] = [e_4, e_8] = [e_5, e_7] = [e_5, e_8] = [e_6, e_7] = [e_6, e_8] = 0. \end{aligned} \quad (4)$$

Define a loop super algebra corresponding to the Lie super algebra  $gl(6, 2)$ , denote by

$$\begin{aligned} \tilde{sl}(4|1) &= sl(4|1) \otimes \mathbb{C}[\lambda, \lambda^{-1}] \\ &= \{e_i \lambda^m, e_i \in sl(4|1), m = 0, \pm 1, \dots\}. \end{aligned} \tag{5}$$

The corresponding (anti) commutative relations are given as

$$[e_i \lambda^m, e_j \lambda^n] = [e_i, e_j] \lambda^{m+n}, \forall e_i, e_j \in sl(4|1). \tag{6}$$

### 3. Nonlinear Super Integrable Couplings of Super Yang Hierarchy

If Let us start from an enlarged spectral problem associated with  $sl(4|1)$ ,

$$\begin{aligned} \phi_x &= U(u, \lambda)\phi, U \\ &= e_2(1) + qe_2(0) + re_1(0) + se_3(0) + u_1e_5(0) + u_2e_4(0) \\ &\quad + u_3e_6(0) + \alpha e_7(0) + \beta e_8(0). \end{aligned} \tag{7}$$

where  $q, r, s, u_1, u_2, u_3$  are even potentials, but  $\alpha, \beta$  are odd ones.

In order to obtain super integrable couplings of super Yang hierarchy, we solve the adjoint representation of (7),

$$V_x = [U, V], \tag{8}$$

with

$$\begin{aligned} V &= Ae_1(0) + Be_2(0) + Ce_3(0) + Ee_4(0) + Fe_5(0) \\ &\quad + Ge_6(0) + \rho e_7(0) + \delta e_8(0). \end{aligned} \tag{9}$$

where  $A, B, C, E, F$  and  $G$  are commuting fields, and  $\rho, \delta$  are anti-commuting fields.

Substituting

$$\begin{aligned} A &= \sum_{m \geq 0} A_m \lambda^{-m}, B = \sum_{m \geq 0} B_m \lambda^{-m}, C = \sum_{m \geq 0} C_m \lambda^{-m}, E = \sum_{m \geq 0} E_m \lambda^{-m}, \\ F &= \sum_{m \geq 0} F_m \lambda^{-m}, G = \sum_{m \geq 0} G_m \lambda^{-m}, \rho = \sum_{m \geq 0} \rho_m \lambda^{-m}, \delta = \sum_{m \geq 0} \delta_m \lambda^{-m}. \end{aligned} \tag{10}$$

into previous equation gives the following recursive formulas

$$\begin{cases} A_{m,x} = -2rB_m + 2C_{m+1} + 2qC_m + \beta\rho_m + \alpha\delta_m, \\ B_{m,x} = -2rA_m + 2sC_m - \alpha\rho_m - \beta\delta_m, \\ C_{m,x} = -2qA_m - 2A_{m+1} + 2sB_m - \alpha\rho_m + \beta\delta_m, \\ E_{m,x} = -2u_2B_m + 2u_1C_m - 2rF_m - 2u_2F_m + 2G_{m+1} + 2qG_m + 2u_1G_m - \beta\rho_m - \alpha\delta_m, \\ F_{m,x} = -2u_2A_m + 2u_3C_m - 2rE_m - 2u_2E_m + 2sG_m + 2u_3G_m + \alpha\rho_m + \beta\delta_m, \\ G_{m,x} = -2u_1A_m + 2u_3B_m - 2E_{m+1} - 2qE_m - 2u_1E_m + 2sF_m + 2u_3F_m + \alpha\rho_m - \beta\delta_m, \\ \rho_{m,x} = -\alpha A_m - \beta B_m - \beta C_m + s\rho_m + \delta_{m+1} + q\delta_m + r\delta_m, \\ \delta_{m,x} = \beta A_m + \alpha B_m - \alpha C_m - \rho_{m+1} - q\rho_m + r\rho_m - s\delta_m. \end{cases} \tag{11}$$

From previous equations, we can successively deduce

$$\begin{aligned}
 B_0 &= 1, A_0 = C_0 = E_0 = G_0 = \rho_0 = \delta_0 = 0, F_0 = \varepsilon = \text{const.}, \\
 A_1 &= s, B_1 = 0, C_1 = r, E_1 = u_3 + \varepsilon s + \varepsilon u_3, F_1 = 0, \\
 G_1 &= \varepsilon r + u_2 + \varepsilon u_2, \rho_1 = \alpha, \delta_1 = \beta, A_2 = -\frac{1}{2}r_x - qs, \\
 B_2 &= \frac{1}{2}r^2 + \frac{1}{2}s^2 + \alpha\beta, C_2 = \frac{1}{2}s_x - qr, \\
 E_2 &= -\frac{1}{2}\varepsilon r_x - \frac{1}{2}u_{2x} - \frac{1}{2}\varepsilon u_{2x} - su_1 - qu_3 - \varepsilon qs, \\
 F_2 &= \frac{1}{2}\varepsilon r^2 + \frac{1}{2}\varepsilon s^2 + (1 + \varepsilon)\left(ru_2 + su_3 + \frac{1}{2}u_2^2 + \frac{1}{2}u_3^2\right) - \alpha\beta, \\
 G_2 &= \frac{1}{2}\varepsilon s_x - \varepsilon qr + (1 + \varepsilon)\left(\frac{1}{2}u_{3x} - ru_1 - qu_2 - u_1u_2\right), \\
 \rho_2 &= -\beta_x - q\alpha, \delta_2 = \alpha_x - q\beta.
 \end{aligned}$$

Equation (11) can be written as

$$\begin{aligned}
 &(-2B_{n+1} - F_{n+1}, 2C_{n+1} + G_{n+1}, 2A_{n+1} + E_{n+1}, -B_{n+1} - F_{n+1}, C_{n+1} + G_{n+1}, A_{n+1} + E_{n+1}, \delta_{n+1}, -\rho_{n+1})^T \\
 &= L(-2B_n - F_n, 2C_n + G_n, 2A_n + E_n, -B_n - F_n, C_n + G_n, A_n + E_n, \delta_n, -\rho_n)^T,
 \end{aligned} \tag{12}$$

where

$$L = \begin{pmatrix} 0 & -\partial^{-1}r\partial + 2\partial^{-1}qs & -\partial^{-1}s\partial - 2\partial^{-1}qr & 0 & -\partial^{-1}u_2\partial - 2\partial^{-1}(su_1 + qu_3 + u_1u_3) & -\partial^{-1}u_3\partial - 2\partial^{-1}(ru_1 + qu_2 + u_1u_2) & -\partial^{-1}\alpha\partial - \partial^{-1}q\beta & -\partial^{-1}\beta\partial + \partial^{-1}q\alpha \\ -r & -q & \frac{1}{2}\partial & -u_2 & -u_1 & 0 & -\frac{1}{2}\alpha & \frac{1}{2}\beta \\ -s & -\frac{1}{2}\partial & -q & -u_3 & 0 & -u_1 & \frac{1}{2}\partial & \frac{1}{2}\alpha \\ 0 & 0 & 0 & 0 & -\partial^{-1}r\partial - \partial^{-1}u_2\partial + 2\partial^{-1}(qs + su_1 + qu_3 + u_1u_3) & -\partial^{-1}s\partial - \partial^{-1}u_3\partial - 2\partial^{-1}(qr + ru_1 + qu_2 + u_1u_2) & 0 & 0 \\ 0 & 0 & 0 & -r - u_2 & -q - u_1 & \frac{1}{2}\partial & 0 & 0 \\ 0 & 0 & 0 & -s - u_3 & -\frac{1}{2}\partial & -q - u_1 & 0 & 0 \\ -\beta & \beta & \alpha & \beta & -\beta & -\alpha & -q - r & s - \partial \\ \alpha & \alpha & -\beta & -\alpha & -\alpha & \beta & s + \partial & -q + r \end{pmatrix}.$$

Then, let us consider the spectral problem (7) with the following auxiliary problem

$$\phi_{t_n} = V^{(n)}\phi \tag{13}$$

with

$$\begin{aligned}
 V^{(n)} &= \sum_{j=1}^n (A_j e_1(n-j) + B_j e_2(n-j) + C_j e_3(n-j) + E_j e_4(n-j) + F_j e_5(n-j) \\
 &+ G_j e_6(n-j) + \rho_j e_7(n-j) + \delta_j e_8(n-j)) + B_{n+1} e_2(0) + F_{n+1} e_5(0),
 \end{aligned} \tag{14}$$

From the compatible condition  $\phi_{x,t_n} = \phi_{t_n,x}$ , according to (7) and (13), we get the zero curvature equation

$$U_{t_n} - V_x^{(n)} + [U, V^{(n)}] = 0. \tag{15}$$

which gives a nonlinear Lax super integrable hierarchy

$$u_{t_n} = \begin{pmatrix} q \\ r \\ s \\ u_1 \\ u_2 \\ u_3 \\ \alpha \\ \beta \end{pmatrix}_{t_n} = \begin{pmatrix} B_{n+1,x} \\ -2A_{n+1} - 2sB_{n+1} \\ 2rB_{n+1} + 2B_{n+1} \\ F_{n+1,x} \\ -2u_3A_{n+1} - 2sF_{n+1} - 2u_3F_{n+1} \\ 2u_2B_{n+1} + 2rF_{n+1} + 2u_2F_{n+1} + 2G_{n+1} \\ \delta_{n+1} + \beta \\ -\rho_{n+1} - \alpha B_{n+1} \end{pmatrix}. \tag{16}$$

The super integrable hierarchy (16) is a nonlinear super integrable couplings for the Yang hierarchy in [15]

$$\begin{aligned} \tilde{u}_{t_n} &= (q, r, s, \alpha, \beta)_{t_n}^T \\ &= (B_{n+1,x}, -2A_{n+1} - 2sB_{n+1}, 2rB_{n+1} + 2B_{n+1}, \delta_{n+1} + \beta B_{n+1}, -\rho_{n+1} - \alpha B_{n+1})^T. \end{aligned} \tag{17}$$

### 4. Super Hamiltonian Structures

A direct calculation reads

$$\begin{aligned} Str(U_\lambda, V) &= -4B - 2F, Str(U_q, V) = -4B - 2F, \\ Str(U_r, V) &= 4C + 2G, Str(U_s, V) = 4A + 2E, \\ Str(U_{u_1}, V) &= -2B - 2F, Str(U_{u_2}, V) = 2C + 2G, \\ Str(U_{u_3}, V) &= 2A + 2E, Str(U_\alpha, V) = 2\delta, Str(U_\beta, V) = -2\rho. \end{aligned} \tag{18}$$

Substituting above results into the super trace identity [7]

$$\frac{\delta}{\delta u} \int Str \left( \frac{\delta U}{\delta \lambda} V \right) dx = \lambda^{-\gamma} \frac{\partial}{\partial \lambda} \lambda^\gamma Str \left( \frac{\delta U}{\delta u} V \right). \tag{19}$$

Comparing the coefficients of  $\lambda^{-n-1}$  on both side of (19). From the initial values in (11), we obtain  $\gamma = 0$ . Thus we have

$$\begin{cases} \frac{\delta H_n}{\delta u} = (-2B_n - F_n, 2C_n + G_n, 2A_n + E_n, -B_n - F_n, C_n + G_n, A_n + E_n, \delta_n, -\rho_n)^T, \\ H_n = \int \frac{2B_{n+1} + F_{n+1}}{n+1} dx, n \geq 0. \end{cases} \tag{20}$$

It then follows that the nonlinear super integrable couplings (16) possess the following super Hamiltonian form

$$u_{t_n} = K_n(u) = J \frac{\delta H_n}{\delta u}. \tag{21}$$

where

$$J = \begin{pmatrix} -\partial & -s & r & \partial & s & -r & \frac{1}{2}\beta & -\frac{1}{2}\alpha \\ s & 0 & -1 & -s & 0 & 1 & 0 & 0 \\ -r & 1 & 0 & r & -1 & 0 & 0 & 0 \\ \partial & s & -r & -2\partial & -2s - u_3 & 2r - u_2 & -\frac{1}{2}\beta & \frac{1}{2}\alpha \\ -s & 0 & 1 & 2s + u_3 & 0 & -2 & 0 & 0 \\ r & -1 & 0 & -2r + u_2 & 2 & 0 & 0 & 0 \\ -\frac{1}{2}\beta & 0 & 0 & \frac{1}{2}\beta & 0 & 0 & \frac{1}{2} & 0 \\ \frac{1}{2}\alpha & 0 & 0 & -\frac{1}{2}\alpha & 0 & 0 & 0 & \frac{1}{2} \end{pmatrix}. \tag{22}$$

is a super Hamiltonian operator and  $H_n (n \geq 0)$  are Hamiltonian functions.

### 5. Reductions

Taking  $\alpha = \beta = 0$ , (16) reduces to a nonlinear integrable couplings of the Yang

hierarchy in [13].

When  $n = 2$  in (16), we obtain the nonlinear super integrable couplings of the second order super Yang equations

$$\left\{ \begin{aligned}
 q_{t_2} &= -\frac{1}{2}r_{xx}s + \frac{1}{2}rs_{xx} - 2qqr_x - 2qss_x - q_xr^2 - q_xs^2 + \alpha\alpha_{xx} + \beta\beta_{xx} - 2(q\alpha\beta)_x, \\
 r_{t_2} &= \frac{1}{2}s_{xx} - q_xr - 2qr_x + r_xs^2 - rss_x - 2q^2s - r^2s - s^3 + 2qs^3 + 2qr^2s - 2s\alpha\alpha_x \\
 &\quad - 2s\beta\beta_x + 4qs\alpha\beta - 2s\alpha\beta - \alpha\beta_x + \alpha_x\beta, \\
 s_{t_2} &= -\frac{1}{2}r_{xx} - q_xs - 2qs_x - rr_xs + r^2s_x + 2q^2r - 2qrs^2 - 2qr^3 + r^3 + rs^2 + 2r\alpha\beta \\
 &\quad + 2r\alpha\alpha_x + 2r\beta\beta_x - 4qr\alpha\beta - \alpha\alpha_x + \beta\beta_x, \\
 u_{1,t_2} &= -\frac{1}{2}\varepsilon r_{xx}s + \frac{1}{2}\varepsilon rs_{xx} - 2\varepsilon qrr_x - 2\varepsilon qss_x - \varepsilon q_xr^2 - \varepsilon q_xs^2 + (\varepsilon + 1) \\
 &\quad \left( -\frac{1}{2}u_{2xx}u_3 + \frac{1}{2}ru_{3xx} + \frac{1}{2}u_2u_{3xx} - \frac{1}{2}su_{2xx} + \frac{1}{2}s_{2xx}u_2 - \frac{1}{2}r_{2xx}u_3 - 2u_1u_3u_{3x} \right. \\
 &\quad - 2rr_xu_1 - 2r_xu_1u_2 - 2qs_xu_3 - 2qru_{2x} - 2qr_xu_2 - 2qu_2u_{2x} - 2q_xru_2 - 2ru_1u_{2x} \\
 &\quad - 2u_1u_2u_{2x} - 2ss_xu_1 - 2qsu_{3x} - 2su_{1x}u_3 - 2su_1u_{3x} - 2s_xu_1u_3 - 2qu_3u_{3x} \\
 &\quad - 2q_xsu_3 - 2ru_{1x}u_2 - q_xu_3^2 - u_{1x}u_3^2 - r^2u_{1x} - q_xu_2^2 - u_{1x}u_2^2 - s^2u_{1x} \left. \right) \\
 &\quad - \alpha\alpha_{xx} - \beta\beta_{xx} + 2(q\alpha\beta)_x \\
 u_{2,t_2} &= \frac{1}{2}\varepsilon s_{xx} - \varepsilon q_xr - 2\varepsilon qr_x + \varepsilon r_xs^2 - \varepsilon rss_x - 2\varepsilon q^2s - \varepsilon r^2s - \varepsilon s^3 + 2\varepsilon qs^3 \\
 &\quad + 2\varepsilon qr^2s + (\varepsilon + 1) \left( \frac{1}{2}u_{3xx} + 4qrsu_2 + 4rsu_1u_2 + 4qru_2u_3 + 4ru_1u_2u_3 - 4qsu_1 \right. \\
 &\quad - 2rsu_2 - 4qu_1u_3 - 2ru_2u_3 - u_3^2 - r^2u_3 - 3s^2u_3 - 2q^2u_3 - 2su_1^2 - 2u_1^2u_3 - su_2^2 \\
 &\quad - 3su_3^2 - u_2^2u_3 - ru_{1x} - 2r_xu_1 - q_xu_2 - 2qu_{2x} - u_{1x}u_2 - 2u_1u_{2x} + r_xu_3^2 + 2s^3u_1 \\
 &\quad + s^2u_{2x} + 2u_1u_3^2 + 2qu_3^2 + u_{2x}u_3^2 + 6s^2u_1u_3 + 2qu_2^2u_3 + 2u_1u_2^2u_3 - su_2u_{3x} \\
 &\quad + 6qsu_3^2 - rs_xu_3 - ru_{3x}u_{3x} - s_xu_2u_3 + 2su_{2x}u_3 + 2r^2su_1 + 2su_1u_2^2 + 2qsu_2^2 \\
 &\quad + 6qs^2u_3 + 2qr^2u_3 - rsu_{3x} + 2r_xsu_3 + 6su_1u_3^2 + 2r^2u_1u_3 - u_2u_3u_{3x} - ss_xu_2 \left. \right) \\
 &\quad + 2s\alpha\alpha_x + 2s\beta\beta_x - 4qs\alpha\beta + 2s\alpha\beta + \alpha\beta_x - \alpha_x\beta, \\
 u_{3,t_2} &= -\frac{1}{2}\varepsilon r_{xx} - \varepsilon q_xs - 2\varepsilon qs_x - \varepsilon rr_xs + \varepsilon r^2s_x + 2\varepsilon q^2r - 2\varepsilon qrs^2 - 2\varepsilon qr^3 + \varepsilon r^3 \\
 &\quad + \varepsilon rs^2 + (\varepsilon + 1) \left( -\frac{1}{2}u_{2xx} - su_{1x} - 2s_xu_1 - q_xu_3 - 2qu_{3x} - u_{1x}u_3 - 2u_1u_{3x} \right. \\
 &\quad + 2ru_1^2 + 2u_1^2u_2 + 3ru_2^2 + ru_3^2 + u_2u_3^2 + 2q^2u_2 + 3r^2u_2 + s^2u_2 + u_2^3 - 4qrsu_3 \\
 &\quad - 4rsu_1u_3 - 4qsu_2u_3 - 4su_1u_2u_3 + 4qu_1u_2 + 4qru_1 + 2rsu_3 + 2su_2u_3 - 2rs^2u_1 \\
 &\quad - 6qru_2^2 - 2ru_1u_3^2 - r_xu_2u_3 - rsu_{2x} - 2s^2u_1u_2 - 6qr^2u_2 - 6r^2u_1u_2 + 2ru_2u_{3x} \\
 &\quad - 2qs^2u_2 - 6ru_1u_2^2 - u_2u_{2x}u_3 + 2rs_xu_2 - 2u_1u_2u_3^2 - ru_{2x}u_3 - su_2u_{2x} - 2qru_3^2 \\
 &\quad - r_xsu_2 - 2qu_2u_3^2 - rr_xu_3 - 2u_1u_3^2 - 2qu_2^3 + s_xu_2^2 + u_2^2u_{3x} + r^2u_{3x} - 2r^3u_1 \left. \right) \\
 &\quad - 2r\alpha\beta - 2r\alpha\alpha_x - 2r\beta\beta_x + 4qr\alpha\beta + \alpha\alpha_x - \beta\beta_x, \\
 \alpha_{t_2} &= -\beta_{xx} - q_x\alpha - 2q\alpha_x - \frac{1}{2}r_x\alpha - r\alpha_x + \frac{1}{2}r^2\beta + \frac{1}{2}s^2\beta + \frac{1}{2}s_x\beta + s\beta_x + q^2\beta \\
 &\quad - \frac{1}{2}r_xs\beta + \frac{1}{2}rs_x\beta - qr^2\beta - qs^2\beta + \alpha\alpha_x\beta, \\
 \beta_{t_2} &= \alpha_{xx} - q_x\beta - 2q\beta_x + \frac{1}{2}r_x\beta - \frac{1}{2}r^2\alpha - \frac{1}{2}s^2\alpha + \frac{1}{2}s_x\alpha - q^2\alpha + r\beta_x + s\alpha_x \\
 &\quad + \frac{1}{2}r_xs\alpha - \frac{1}{2}rs_x\alpha + qr^2\alpha + qs^2\alpha - \alpha\beta\beta_x.
 \end{aligned} \right. \tag{23}$$

Especially, taking  $\alpha = \beta = 0$  in (23), we can obtain the nonlinear integrable

couplings of the second order Yang equations in [13]

$$\left\{ \begin{aligned}
 q_{t_2} &= -\frac{1}{2}r_{xx}s + \frac{1}{2}rs_{xx} - 2qqr_x - 2qss_x - q_xr^2 - q_x s^2, \\
 r_{t_2} &= \frac{1}{2}s_{xx} - q_xr - 2qr_x + r_x s^2 - rss_x - 2q^2s - r^2s - s^3 + 2qs^3 + 2qr^2s, \\
 s_{t_2} &= -\frac{1}{2}r_{xx} - q_x s - 2qs_x - rr_x s + r^2s_x + 2q^2r - 2qrs^2 - 2qr^3 + r^3 + rs^2, \\
 u_{1,t_2} &= -\frac{1}{2}\varepsilon r_{xx}s + \frac{1}{2}\varepsilon rs_{xx} - 2\varepsilon qrr_x - 2\varepsilon qss_x - \varepsilon q_xr^2 - \varepsilon q_x s^2 + (\varepsilon + 1) \\
 &\quad \left( -\frac{1}{2}u_{2xx}u_3 + \frac{1}{2}ru_{3xx} + \frac{1}{2}u_2u_{3xx} - \frac{1}{2}su_{2xx} + \frac{1}{2}s_{2xx}u_2 - \frac{1}{2}r_{2xx}u_3 - 2u_1u_3u_{3x} \right. \\
 &\quad - 2rr_xu_1 - 2r_xu_1u_2 - 2qs_xu_3 - 2qru_{2x} - 2qr_xu_2 - 2qu_2u_{2x} - 2q_xru_2 \\
 &\quad - 2ru_1u_{2x} - 2u_1u_2u_{2x} - 2ss_xu_1 - 2qsu_{3x} - 2su_{1x}u_3 - 2su_1u_{3x} - 2s_xu_1u_3 \\
 &\quad \left. - 2qu_3u_{3x} - 2q_xsu_3 - 2ru_{1x}u_2 - q_xu_3^2 - u_{1x}u_3^2 - r^2u_{1x} - q_xu_2^2 - u_{1x}u_2^2 - s^2u_{1x} \right), \\
 u_{2,t_2} &= \frac{1}{2}\varepsilon s_{xx} - \varepsilon q_xr - 2\varepsilon qr_x + \varepsilon r_x s^2 - \varepsilon rss_x - 2\varepsilon q^2s - \varepsilon r^2s - \varepsilon s^3 + 2\varepsilon qs^3 \\
 &\quad + 2\varepsilon qr^2s + (\varepsilon + 1) \left( \frac{1}{2}u_{3xx} + 4qrsu_2 + 4rsu_1u_2 + 4qru_2u_3 + 4ru_1u_2u_3 - 4qsu_1 \right. \\
 &\quad - 2rsu_2 - 4qu_1u_3 - 2ru_2u_3 - u_3^2 - r^2u_3 - 3s^2u_3 - 2q^2u_3 - 2su_1^2 - 2u_1^2u_3 - su_2^2 \\
 &\quad - 3su_3^2 - u_2^2u_3 - ru_{1x} - 2r_xu_1 - q_xu_2 - 2qu_{2x} - u_{1x}u_2 - 2u_1u_{2x} + r_xu_2^2 + 2s^3u_1 \\
 &\quad + s^2u_{2x} + 2u_1u_3^2 + 2qu_3^2 + u_{2x}u_3^2 + 6s^2u_1u_3 + 2qu_2^2u_3 + 2u_1u_2^2u_3 - su_2u_{3x} \\
 &\quad + 6qsu_3^2 - rs_xu_3 - ru_3u_{3x} - s_xu_2u_3 + 2su_{2x}u_3 + 2r^2su_1 + 2su_1u_2^2 + 2qsu_2^2 \\
 &\quad \left. + 6qs^2u_3 + 2qr^2u_3 - rsu_{3x} + 2r_xsu_3 + 6su_1u_3^2 + 2r^2u_1u_3 - u_2u_3u_{3x} - ss_xu_2 \right), \\
 u_{3,t_2} &= -\frac{1}{2}\varepsilon r_{xx} - \varepsilon q_x s - 2\varepsilon qs_x - \varepsilon rr_x s + \varepsilon r^2s_x + 2\varepsilon q^2r - 2\varepsilon qrs^2 - 2\varepsilon qr^3 + \varepsilon r^3 \\
 &\quad + \varepsilon rs^2 + (\varepsilon + 1) \left( -\frac{1}{2}u_{2xx} - su_{1x} - 2s_xu_1 - q_xu_3 - 2qu_{3x} - u_{1x}u_3 - 2u_1u_{3x} \right. \\
 &\quad + 2ru_1^2 + 2u_1^2u_2 + 3ru_2^2 + ru_3^2 + u_2u_3^2 + 2q^2u_2 + 3r^2u_2 + s^2u_2 + u_3^2 - 4qrsu_3 \\
 &\quad - 4rsu_1u_3 - 4qsu_2u_3 - 4su_1u_2u_3 + 4qu_1u_2 + 4qru_1 + 2rsu_3 + 2su_2u_3 - 2rs^2u_1 \\
 &\quad - 6qru_2^2 - 2ru_1u_3^2 - r_xu_2u_3 - rsu_{2x} - 2s^2u_1u_2 - 6qr^2u_2 - 6r^2u_1u_2 + 2ru_2u_{3x} \\
 &\quad - 2qs^2u_2 - 6ru_1u_2^2 - u_2u_{2x}u_3 + 2rs_xu_2 - 2u_1u_2u_3^2 - ru_{2x}u_3 - su_2u_{2x} - 2qru_3^2 \\
 &\quad \left. - r_xsu_2 - 2qu_2u_3^2 - rr_xu_3 - 2u_1u_3^2 - 2qu_2^2 + s_xu_2^2 + u_2^2u_{3x} + r^2u_{3x} - 2r^3u_1 \right).
 \end{aligned} \right. \tag{24}$$

If setting  $\varepsilon = -1, u_1 = -q, u_2 = -r$  in (23), we obtain the second order super Yang equations of (17) in [15]

$$\left\{ \begin{aligned}
 q_{t_2} &= -\frac{1}{2}r_{xx}s + \frac{1}{2}rs_{xx} - 2qqr_x - 2qss_x - q_xr^2 - q_x s^2 + \alpha\alpha_{xx} + \beta\beta_{xx} - 2(q\alpha\beta)_x, \\
 r_{t_2} &= \frac{1}{2}s_{xx} - q_xr - 2qr_x + r_x s^2 - rss_x - 2q^2s - r^2s - s^3 + 2qs^3 + 2qr^2s - 2s\alpha\alpha_x \\
 &\quad - 2s\beta\beta_x + 4qs\alpha\beta - 2s\alpha\beta - \alpha\beta_x + \alpha_x\beta, \\
 s_{t_2} &= -\frac{1}{2}r_{xx} - q_x s - 2qs_x - rr_x s + r^2s_x + 2q^2r - 2qrs^2 - 2qr^3 + r^3 + rs^2 + 2r\alpha\beta \\
 &\quad + 2r\alpha\alpha_x + 2r\beta\beta_x - 4qr\alpha\beta - \alpha\alpha_x + \beta\beta_x, \\
 \alpha_{t_2} &= -\beta_{xx} - q_x\alpha - 2q\alpha_x - \frac{1}{2}r_x\alpha - r\alpha_x + \frac{1}{2}r^2\beta + \frac{1}{2}s^2\beta + \frac{1}{2}s_x\beta + s\beta_x + q^2\beta \\
 &\quad - \frac{1}{2}r_x s\beta + \frac{1}{2}rs_x\beta - qr^2\beta - qs^2\beta + \alpha\alpha_x\beta, \\
 \beta_{t_2} &= \alpha_{xx} - q_x\beta - 2q\beta_x + \frac{1}{2}r_x\beta - \frac{1}{2}r^2\alpha - \frac{1}{2}s^2\alpha + \frac{1}{2}s_x\alpha - q^2\alpha + r\beta_x + s\alpha_x \\
 &\quad + \frac{1}{2}r_x s\alpha - \frac{1}{2}rs_x\alpha + qr^2\alpha + qs^2\alpha - \alpha\beta\beta_x.
 \end{aligned} \right. \tag{25}$$

## 6. Remarks

In this paper, we introduced an approach for constructing nonlinear integrable couplings of super integrable hierarchy. The method in this paper can be applied to other super integrable systems for constructing their integrable couplings. How to obtain the soliton solutions about equations deduced in this paper is worth considering for our future work.

## Acknowledgements

This work was supported by the Natural Science Foundation of Henan Province (No. 162300410075), the Science and Technology Key Research Foundation of the Education Department of Henan Province (No.14A110010).

## References

- [1] Kupershmidt, B.A. (1985) Odd and Even Poisson Brackets In Dynamical Systems. *Letters in Mathematical Physics*, **9**, 323-330. <https://doi.org/10.1007/BF00397758>
- [2] Li, Y.S. and Zhang, L.N. (1988) A Note on the Super AKNS Equations. *Journal of Physics A: Mathematical and General*, **21**, 1549-1552. <https://doi.org/10.1088/0305-4470/21/7/017>
- [3] Tu, M.H. and Shaw, J.C. (1999) Hamiltonian Structures of Generalized Manin-Radul Super-KdV and Constrained Super KP Hierarchies. *Journal of Mathematical Physics*, **40**, 3021-3034. <https://doi.org/10.1063/1.532741>
- [4] Liu, Q.P. and Hu, X.B. (2005) Bilinearization of  $N = 1$  Supersymmetric Korteweg de Vries Equation Revisited. *Journal of Physics A: Mathematical and General*, **38**, 6371-6378. <https://doi.org/10.1088/0305-4470/38/28/009>
- [5] Aratyn, H., Nissimov, E. and Pacheva, S. (1999) Supersymmetric Kadomtsev-Petviashvili Hierarchy: "Ghost" Symmetry Structure, Reductions, and Darboux-Bäcklund Solutions. *Journal of Mathematical Physics*, **40**, 2922-2932. <https://doi.org/10.1063/1.532736>
- [6] Morosi, C. and Pizzocchero, L. (1993) On the bi Hamiltonian Structure of the Supersymmetric KdV Hierarchies. A Lie Superalgebraic Approach. *Communications in Mathematical Physics*, **158**, 267-288. <https://doi.org/10.1007/BF02108075>
- [7] Hu, X.B. (1997) An Approach to Generate Superextensions of Integrable Systems. *Journal of Physics A: Mathematical and General*, **30**, 619-632. <https://doi.org/10.1088/0305-4470/30/2/023>
- [8] He, J.S., Yu, J., Zhou, R.G. and Cheng, Y. (2008) Binary Nonlinearization of the Super AKNS System. *Modern Physics Letters B*, **22**, 275-288. <https://doi.org/10.1142/S0217984908014778>
- [9] Liu, Q.P., Popowicz, Z. and Tian, K. (2010) Supersymmetric Reciprocal Transformation and Its Applications. *Journal of Mathematical Physics*, **51**, 093511. <https://doi.org/10.1063/1.3481568>
- [10] Guo, F.K. and Zhang, Y.F. (2005) The Quadratic-Form Identity for Constructing the Hamiltonian Structure of Integrable Systems. *Journal of Physics A: Mathematical and General*, **38**, 8537-8548. <https://doi.org/10.1088/0305-4470/38/40/005>
- [11] Zhang, Y.F. and Tam, H.W. (2010) Four Lie Algebras Associated with  $R^6$  and Their Applications. *Journal of Mathematical Physics*, **51**, 093514. <https://doi.org/10.1063/1.3489126>
- [12] Ma, W.X. (2011) Nonlinear Continuous Integrable Hamiltonian Couplings. *Applied*



*Mathematics and Computation*, **217**, 7238-7244.

<https://doi.org/10.1016/j.amc.2011.02.014>

- [13] Zhang, Y.F. (2011) Lie Algebras for Constructing Nonlinear Integrable Couplings. *Communications in Theoretical Physics*, **56**, 805-812. <https://doi.org/10.1088/0253-6102/56/5/03>
- [14] You, F.C. (2011) Nonlinear Super Integrable Hamiltonian Couplings. *Journal of Mathematical Physics*, **52**, 123510. <https://doi.org/10.1063/1.3669484>
- [15] Tao, S.X. and Xia, T.C. (2011) Two Super-Integrable Hierarchies and Their Super-Hamiltonian Structures. *Communications in Nonlinear Science and Numerical Simulation*, **16**, 127-132. <https://doi.org/10.1016/j.cnsns.2010.04.009>.



Scientific Research Publishing

**Submit or recommend next manuscript to SCIRP and we will provide best service for you:**

Accepting pre-submission inquiries through Email, Facebook, LinkedIn, Twitter, etc.

A wide selection of journals (inclusive of 9 subjects, more than 200 journals)

Providing 24-hour high-quality service

User-friendly online submission system

Fair and swift peer-review system

Efficient typesetting and proofreading procedure

Display of the result of downloads and visits, as well as the number of cited articles

Maximum dissemination of your research work

Submit your manuscript at: <http://papersubmission.scirp.org/>

Or contact [jamp@scirp.org](mailto:jamp@scirp.org)

