

# Solving of Klein-Gordon by Two Methods of Numerical Analysis

**Joseph Bonazebi Yindoula<sup>1\*</sup>, Alphonse Massamba<sup>2</sup>, Gabriel Bissanga<sup>1</sup>**

<sup>1</sup>Laboratory of Numerical Analysis, Kibernetics and Applications, University Marien NGOUABI, Brazzaville, Congo

<sup>2</sup>Division of Physics, Brazzaville Institute of Technology, Brazzaville, Congo

Email: \*bonayindoula@yahoo.fr

**How to cite this paper:** Yindoula, J.B., Massamba, A. and Bissanga, G. (2016) Solving of Klein-Gordon by Two Methods of Numerical Analysis. *Journal of Applied Mathematics and Physics*, **4**, 1916-1929.

<http://dx.doi.org/10.4236/jamp.2016.410194>

**Received:** August 15, 2016

**Accepted:** October 23, 2016

**Published:** October 27, 2016

Copyright © 2016 by authors and Scientific Research Publishing Inc.  
This work is licensed under the Creative Commons Attribution International License (CC BY 4.0).  
<http://creativecommons.org/licenses/by/4.0/>



Open Access

## Abstract

In this paper, the Decomposition Laplace-Adomian method and He-Laplace method are used to construct the solution of Klein-Gordon equation.

## Keywords

Laplace-Adomian Method, He-Laplace Method, Klein-Gordon Equation

## 1. Introduction

In field theory, the description of the free particle for the wave function in quantum physics obeys to Klein-Gordon equation [1]. In addition, it also appears in nonlinear optics and plasma physics.

In sum, the Klein-Gordon equation rises in physics in linear and non linear forms. In this paper we examine the Klein-Gordon equation, using the Laplace-Adomian decomposition method and He-Laplace method to get the exact solution. The Klein-Gordon equation is described as:

$$u_{tt}(x,t) = u_{xx}(x,t) + \alpha u(x,t) + \beta N(u(x,t)) + h(x,t) \quad (1)$$

where  $\alpha, \beta$  are constants (spin zero) charged field,  $h(x,t)$  is a source term and  $N(u(x,t))$  is a nonlinear function of  $u(x,t)$ .

## 2. Describing of Both Method

### 2.1. The Laplace Transform [2]

Let's note the laplace transform by

$$U(x,s) = (u(x,t)) = \int_0^{\infty} u(x,t) e^{-st} dt \quad (2)$$

From (1), we have:

$$\begin{cases} \left( \frac{\partial u(x,t)}{\partial t} \right) = \int_0^\infty e^{-st} \frac{\partial u}{\partial t} dt = s(u(x,t)) - u(x,0) \\ \left( \frac{\partial^2 u(x,t)}{\partial t^2} \right) = s^2(u(x,t)) - su(x,0) - \frac{\partial u(x,0)}{\partial t} \\ \left( \frac{\partial u(x,t)}{\partial x} \right) = \int_0^\infty e^{-st} \frac{\partial u}{\partial x} dt = \frac{dU}{dx} \\ \left( \frac{\partial^2 u(x,t)}{\partial x^2} \right) = \frac{d^2 U}{dx^2} \end{cases} \quad (3)$$

## 2.2. Laplace-Adomian Decomposition Method (LADM) [3]-[6]

Suppose that we need to solve the following equation:

$$u_{tt}(x,t) - u_{xx}(x,t) + \alpha u(x,t) + \beta N(u(x,t)) = h(x,t) \quad (4)$$

subject to initial conditions:

$$u(x,0) = f(x); u_t(x,0) = g(x) \quad (5)$$

$E$  is a Banach space, where  $F : E \rightarrow E$  is a linear or a nonlinear operator,  $h \in E$  and  $u$  is the unknown function.

Let's suppose that operator  $F$  can be decomposed under the following form:

$$F = L + R + N \quad (6)$$

where  $L + R$  is linear,  $N$  nonlinear. Let's suppose that  $L$  is invertible to the sense of Adomian with  $L^{-1}$  as inverse.

From above, by applying the Laplace transform to both sides of Equation (4), we have:

$$[u_{tt}(x,t)] - [u_{xx}(x,t) - \alpha u(x,t)] + \beta [N(u(x,t))] = (h(x,t)) \quad (7)$$

From the Equation (7), it follows:

$$s^2(u(x,t)) - su(x,0) - u_t(x,0) - [u_{xx}(x,t) - \alpha u(x,t)] + \beta [N(u(x,t))] = (h(x,t)) \quad (8)$$

and this equation gives

$$s^2(u(x,t)) = su(x,0) + u_t(x,0) + (h(x,t)) + [u_{xx}(x,t) - \alpha u(x,t)] - \beta [N(u(x,t))] \quad (9)$$

So, from the above Equation (9), we can write:

$$(u(x,t)) = \frac{1}{s}u(x,0) + \frac{1}{s^2}u_t(x,0) + \frac{1}{s^2}(h(x,t)) + \frac{1}{s^2}[u_{xx}(x,t) - \alpha u(x,t)] - \frac{1}{s^2}\beta[N(u(x,t))] \quad (10)$$

We have now  $u(x,t)$ :

$$\begin{aligned} u(x,t) &= \mathcal{L}^{-1}\left(\frac{1}{s}f(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}g(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(h(x,t))\right) \\ &\quad + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}[u_{xx}(x,t) - \alpha u(x,t)]\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2}\beta\mathcal{L}[N(u(x,t))]\right) \end{aligned} \quad (11)$$

We research solution of (4) in the following series expansion form

$$u(x, t) = \sum_{n=0}^{+\infty} u_n(x, t) \quad (12)$$

and we consider

$$Nu(x, t) = \sum_{n=0}^{+\infty} A_n \quad (13)$$

where  $A_n$  are the Adomian polynomials of  $u_0, u_1, \dots, u_n$  and it can be calculated by formula given below.

$$A_n = \frac{1}{n!} \frac{d^n}{dp^n} \left[ N \sum_{i=0}^{\infty} \lambda^i u_i \right]_{\lambda=0}, n = 0, 1, 2, 3, \dots \quad (14)$$

Using Equation (12) and Equation (13) in Equation (11) we have:

$$\begin{aligned} \sum_{n=0}^{+\infty} u_n(x, t) &= \mathcal{L}^{-1} \left( \frac{1}{s} f(x) \right) + \mathcal{L}^{-1} \left( \frac{1}{s^2} g(x) \right) + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L}(h(x, t)) \right) \\ &\quad + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \sum_{n=0}^{+\infty} \left( \frac{\partial^2 (u_n(x, t))}{\partial x^2} \right) - \alpha \sum_{n=0}^{+\infty} u_n(x, t) \right] \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \beta \mathcal{L} \left( \sum_{n=0}^{+\infty} A_n \right) \right) \end{aligned} \quad (15)$$

From (15), we have the following Adomian algorithm:

$$\begin{cases} u_0(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s} f(x) \right) + \mathcal{L}^{-1} \left( \frac{1}{s^2} g(x) \right) + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L}(h(x, t)) \right) = K(x, t) \\ u_{n+1}(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2 (u_n(x, t))}{\partial x^2} \right) - \alpha u_n(x, t) \right] \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \beta \mathcal{L}(A_n) \right), n \geq 0 \end{cases} \quad (16)$$

and we obtain the Adomian algorithm:

$$\begin{cases} u_0(x, t) = K(x, t) \\ u_{n+1}(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2 (u_n(x, t))}{\partial x^2} \right) - \alpha u_n(x, t) \right] \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \beta \mathcal{L}(A_n) \right), n \geq 0 \end{cases} \quad (17)$$

### Remark

In order overcome the short coming, we assume that  $K(x, t)$  can be divided into the sum of two parts namely  $K_0(x, t)$  and  $K_1(x, t)$ . Therefore, we get:

$$K(x, t) = K_0(x, t) + K_1(x, t) \quad (18)$$

Instead of the iteration procedure Equation (17) we suggest the following modification

$$\begin{cases} u_0(x, t) = K_0(x, t) \\ u_1(x, t) = K_1(x, t) + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2 (u_0(x, t))}{\partial x^2} \right) - \alpha u_0(x, t) \right] \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \beta \mathcal{L}(A_0) \right) \\ u_{n+1}(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2 (u_n(x, t))}{\partial x^2} \right) - \alpha u_n(x, t) \right] \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \beta \mathcal{L}(A_n) \right), n \geq 1 \end{cases} \quad (19)$$

The solution through the modified Laplace decomposition method highly depends upon the choice of  $K_0(x, t)$  and  $K_1(x, t)$ .

### 2.3. He-Laplace Method [7]

We consider a general nonlinear non homogeneous partial differential equation with initial conditions of the form

$$\begin{cases} u_{tt}(x, t) - u_{xx}(x, t) + \alpha u(x, t) + \beta N(u(x, t)) = h(x, t) \\ u(x, 0) = f(x) \\ u_t(x, 0) = g(x) \end{cases} \quad (20)$$

$N$  represents the general nonlinear differential operator and  $h(x, t)$  is the source term.

Taking the Laplace transform on both sides of (20), we obtain:

$$\mathcal{L}[u_{tt}(x, t)] - \mathcal{L}[u_{xx}(x, t) - \alpha u(x, t)] + \beta \mathcal{L}[N(u(x, t))] = \mathcal{L}(h(x, t)) \quad (21)$$

$\Leftrightarrow$

$$s^2(u(x, t)) = su(x, 0) + u_t(x, 0) + (h(x, t)) + [u_{xx}(x, t) - \alpha u(x, t)] - \beta [N(u(x, t))] \quad (22)$$

Applying the initial conditions given in (22), we have:

$$\mathcal{L}(u(x, t)) = \frac{1}{s}f(x) + \frac{1}{s^2}g(x) + \frac{1}{s^2}\mathcal{L}(h(x, t)) + \frac{1}{s^2}\mathcal{L}[u_{xx}(x, t) - \alpha u(x, t)] - \frac{1}{s^2}\beta\mathcal{L}[N(u(x, t))] \quad (23)$$

Operating the inverse Laplace transform on both sides of (23), we have

$$\begin{aligned} u(x, t) &= \mathcal{L}^{-1}\left(\frac{1}{s}f(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}g(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(h(x, t))\right) \\ &\quad + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}[u_{xx}(x, t) - \alpha u(x, t)]\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2}\beta\mathcal{L}[N(u(x, t))]\right) \end{aligned} \quad (24)$$

Now, we apply the homotopy perturbation method

$$u(x, t) = \sum_{n=0}^{\infty} p^n u_n(x, t) \quad (25)$$

and the non linear term can be decomposed as

$$Nu(x, t) = \sum_{n=0}^{\infty} p^n H_n(u) \quad (26)$$

for some He's polynomials  $H_n(u)$  that are given by

$$H_n(u) = \frac{1}{n!} \frac{\partial^n}{\partial p^n} \left[ N \sum_{n=0}^{\infty} p^i u_i \right]_{p=0}, \quad n = 0, 1, 2, 3, \dots \quad (27)$$

Sustituting Equation (25) and Equation (26) in Equation (24), we get

$$\begin{aligned} \sum_{n=0}^{\infty} p^n u_n(x, t) &= \mathcal{L}^{-1}\left(\frac{1}{s}f(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}g(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}(h(x, t))\right) \\ &\quad + p \left( \sum_{n=0}^{\infty} \mathcal{L}^{-1}\left(\frac{1}{s^2} \mathcal{L} \left[ \frac{\partial^2(p^n u_n(x, t))}{\partial x^2} - \alpha p^n u_n(x, t) \right] \right) \right) - \sum_{n=0}^{\infty} \beta \mathcal{L}^{-1}\left(\frac{1}{s^2} \mathcal{L}[p^n H_n(u)]\right) \end{aligned} \quad (28)$$

Comparing the coefficients of like powers of  $p$ , we have the following approximations:

$$\begin{cases} p^0 : u_0(x, t) = \mathcal{L}^{-1}\left(\frac{1}{s}f(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}g(x)\right) + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(h(x, t))\right) \\ p^1 : u_1(x, t) = \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left[\frac{\partial^2(u_0(x, t))}{\partial x^2} - \alpha u_0(x, t)\right]\right) - \beta \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}[H_0(u)]\right) \\ p^2 : u_2(x, t) = \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left[\frac{\partial^2(u_1(x, t))}{\partial x^2} - \alpha u_1(x, t)\right]\right) - \beta \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}[H_1(u)]\right) \\ \vdots \end{cases} \quad (29)$$

### 3. Illustrative Examples

To demonstrate the applicability of the above-presented method, we have applied it to two linear and two non linear partial differential equations. These examples have been chosen because they have been widely discussed in literature.

#### 3.1. Example 1

Consider the following linear Klein-Gordon equation

$$\begin{cases} u_{tt}(x, t) - u_{xx}(x, t) - u(x, t) = -\cos x \sin t \\ u(x, 0) = 0 \\ u_t(x, 0) = \cos x \end{cases} \quad (30)$$

##### 3.1.1. Application of the LADM

Applying the Laplace transform on both side of Equation (30) with the initial conditions, we have:

$$\mathcal{L}(u(x, t)) = \frac{1}{s^2} \cos x - \left( \frac{1}{s^2(s^2+1)} \right) \cos x + \frac{1}{s^2} \mathcal{L}[u_{xx}(x, t) + u(x, t)] \quad (31)$$

The inverse Laplace transform give us:

$$u(x, t) = \mathcal{L}^{-1}\left(\frac{1}{s^2}\right) \cos x - \mathcal{L}^{-1}\left(\frac{1}{s^2(s^2+1)}\right) \cos x + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(u_{xx}(x, t) + u(x, t))\right) \quad (32)$$

$\Leftrightarrow$

$$u(x, t) = \sin t \cos x + \mathcal{L}^{-1}\left(\frac{1}{s^2}(u_{xx}(x, t) + u(x, t))\right) \quad (33)$$

We suppose that solution of (30) has the following form:

$$u(x, t) = \sum_{n=0}^{+\infty} u_n(x, t) \quad (34)$$

From (34) and (33), we have:

$$\sum_{n=0}^{+\infty} u_n(x, t) = \sin t \cos x + \sum_{n=0}^{+\infty} \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left(\frac{\partial^2(u_n(x, t))}{\partial x^2} + u_n(x, t)\right)\right) \quad (35)$$

This result guarantee that the following Adomian algorithm is:

$$\begin{cases} u_0(x, t) = \sin t \cos x \\ u_{n+1}(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 (u_n(x, t))}{\partial x^2} + u_n(x, t) \right) \right), \forall n \geq 0 \end{cases} \quad (36)$$

Consequently, we obtain:

$$\begin{cases} u_0(x, t) = \sin t \cos x \\ u_n(x, t) = 0, \forall n \geq 1 \end{cases} \quad (37)$$

So that the solution of (30) is given by

$$u(x, t) = \sum_{n=0}^{+\infty} u_n(x, t) = u_0(x, t) = \sin t \cos x \quad (38)$$

which is the exact solution of problem.

### 3.1.2. Application of the He-Laplace Method

Applying the Laplace transform on both side of Equation (30) with the initial conditions, we obtain:

$$\mathcal{L}(u(x, t)) = \frac{1}{s^2} \cos x - \left( \frac{1}{s^2(s^2 + 1)} \right) \cos x + \frac{1}{s^2} \mathcal{L}[u_{xx}(x, t) + u(x, t)] \quad (39)$$

By applying inverse Laplace transform, we have:

$$u(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \right) \cos x - \mathcal{L}^{-1} \left( \frac{1}{s^2(s^2 + 1)} \right) \cos x + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L}(u_{xx}(x, t) + u(x, t)) \right) \quad (40)$$

$$u(x, t) = \sin t \cos x + \mathcal{L}^{-1} \left( \frac{1}{s^2} (u_{xx}(x, t) + u(x, t)) \right) \quad (41)$$

Now applying the homotopy perturbation method, we have:

$$\sum_{n=0}^{\infty} p^n u_n(x, t) = \sin t \cos x + p \sum_{n=0}^{\infty} \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ p^n \left( \frac{\partial^2}{\partial x^2} (u_n(x, t)) + u_n(x, t) \right) \right] \right) \quad (42)$$

Comparing the coefficient of like powers of  $p$ , we have

$$\begin{cases} p^0 : u_0(x, t) = \sin t \cos x \\ p^1 : u_1(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2}{\partial x^2} (u_0(x, t)) + u_0(x, t) \right) \right] \right) \\ p^2 : u_2(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2}{\partial x^2} (u_1(x, t)) + u_1(x, t) \right) \right] \right) \\ \vdots \\ p^n : u_n(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left[ \left( \frac{\partial^2}{\partial x^2} (u_{n-1}(x, t)) + u_{n-1}(x, t) \right) \right] \right) \end{cases} \quad (43)$$

which gives us

$$\begin{cases} p^0 : u_0(x, t) = \sin t \cos x \\ p^n : u_n(x, t) = 0, \forall n \geq 1 \end{cases} \quad (44)$$

So that, the solution  $u(x, t)$  is given by:

$$u(x, t) = \lim_{p \rightarrow 1} \left( \sum_{n=0}^{\infty} p^n u_n(x, t) \right) = u_0(x, t) = \sin t \cos x \quad (45)$$

### 3.2. Exemple 2

Consider the following nonlinear Klein-Gordon equation

$$\begin{cases} u_{tt}(x, t) - u_{xx}(x, t) + N(u(x, t)) = 2x + t^4 \\ u(x, 0) = 0 \\ u_t(x, 0) = 2 \end{cases} \quad (46)$$

where  $N(u) = [u_x(x, t)]^2$ .

#### 3.2.1. Laplace-Adomian Method

Using the Laplace transform, we have

$$s^2 \mathcal{L}(u(x, t)) - su(x, 0) - \frac{\partial u(x, 0)}{\partial t} = \frac{2}{s}x + \frac{24}{s^5} + \mathcal{L}\left(\frac{\partial^2 u(x, t)}{\partial x^2}\right) - \mathcal{L}\left[\left(\frac{\partial u(x, t)}{\partial x}\right)^2\right] \quad (47)$$

$\Leftrightarrow$

$$\mathcal{L}(u(x, t)) = \frac{2}{s^2} + \frac{2}{s^3}x + \frac{24}{s^7} + \frac{1}{s^2} \mathcal{L}\left(\frac{\partial^2 u(x, t)}{\partial x^2}\right) - \frac{1}{s^2} \mathcal{L}\left[\left(\frac{\partial u(x, t)}{\partial x}\right)^2\right] \quad (48)$$

by applying inverse Laplace transformation to Equation (48), we have

$$u(x, t) = 2t + xt^2 + \frac{1}{30}t^6 + \mathcal{L}^{-1}\left(\frac{1}{s^2} \mathcal{L}\left(\frac{\partial^2 u(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2} \mathcal{L}\left[\left(\frac{\partial u(x, t)}{\partial x}\right)^2\right]\right) \quad (49)$$

Supposing that the solution of (46) has the following form:

$$u(x, t) = \sum_{n=0}^{+\infty} u_n(x, t) \quad (50)$$

and

$$Nu(x, t) = \sum_{n=0}^{+\infty} A_n \quad (51)$$

Taking (50) and (51) into (49), we obtain:

$$\sum_{n=0}^{+\infty} u_n(x, t) = 2t + xt^2 + \frac{1}{30}t^6 + \sum_{n=0}^{+\infty} \left( \mathcal{L}^{-1}\left(\frac{1}{s^2} \mathcal{L}\left(\frac{\partial^2 u_n(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2} \mathcal{L}(A_n)\right) \right) \quad (52)$$

According to the standard Adomian algorithm (52), we need to choose

$u_0(x, t) = 2t + xt^2 + \frac{1}{30}t^6$ . Here, we choose by convenience  $u_0(x, t) = 2t + xt^2$ . So, we

have the following Adomian algorithm

$$\begin{cases} u_0(x,t) = xt^2 + 2t \\ u_1(x,t) = \frac{1}{30}t^6 + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left(\frac{\partial^2 u_0(x,t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(A_0)\right) \\ u_{n+1}(x,t) = \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left(\frac{\partial^2 u_n(x,t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(A_n)\right) \end{cases} \quad (53)$$

then guarantee that:

$$\begin{cases} u_0(x,t) = xt^2 + 2t \\ A_0 = N(u_0(x,t)) = t^4 \\ u_1(x,t) = \frac{1}{30}t^6 - \frac{1}{30}t^6 = 0 \\ A_n = 0, \forall n \geq 1 \Rightarrow u_n = 0, \forall n \geq 1 \end{cases} \quad (54)$$

So the exact solution of (46) is

$$u(x,t) = xt^2 + 2t \quad (55)$$

### 3.2.2. He-Laplace Method

Using the Laplace transform, we have:

$$\mathcal{L}(u(x,t)) = \frac{2}{s^2} + \frac{2}{s^3}x + \frac{24}{s^7} + \frac{1}{s^2}\mathcal{L}\left(\frac{\partial^2 u(x,t)}{\partial x^2}\right) - \frac{1}{s^2}\mathcal{L}\left(\left[\frac{\partial u(x,t)}{\partial x}\right]^2\right) \quad (56)$$

Now, we apply the inverse Laplace transformation to Equation (46), we have:

$$u(x,t) = 2t + xt^2 + \frac{1}{30}t^6 + \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left(\frac{\partial^2 u(x,t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left(\left[\frac{\partial u(x,t)}{\partial x}\right]^2\right)\right) \quad (57)$$

Applying the homotopy perturbation method, we have:

$$\sum_{n=0}^{+\infty} p^n u_n(x,t) = 2t + xt^2 + \frac{1}{30}t^6 + p^{n+1} \sum_{n=0}^{+\infty} \left( \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}\left(\frac{\partial^2 u_n(x,t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2}\mathcal{L}(H_n(u))\right) \right) \quad (58)$$

where  $H_n(u)$  are He's polynomials. The first few components of He's polynomials are given by

$$\begin{cases} H_0(u) = \left(\frac{\partial u_0(x,t)}{\partial x}\right)^2 = t^4 \\ H_1(u) = 2\left(\frac{\partial u_0(x,t)}{\partial x}\right)\left(\frac{\partial u_1(x,t)}{\partial x}\right) = 0 \\ H_2(u) = \left(\frac{\partial u_1(x,t)}{\partial x}\right)^2 + 2\left(\frac{\partial u_0(x,t)}{\partial x}\right)\left(\frac{\partial u_2(x,t)}{\partial x}\right) = 0 \\ \vdots \end{cases} \quad (59)$$

Comparing the coefficients of the like powers of  $p$ , we have:

$$p^0 : u_0(x,t) = 2t + xt^2 + \frac{1}{30}t^6 \quad (60)$$

$$p^1 : u_1(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u_0(x, t)}{\partial x^2} \right) \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L}(H_0(u)) \right) = -\frac{1}{30} t^6 \quad (61)$$

$$p^n : u_n(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u_{n-1}(x, t)}{\partial x^2} \right) \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L}(H_{n-1}(u)) \right) = 0, \forall n \geq 2 \quad (62)$$

So that, the exact solution  $u(x, t)$  is given by:

$$\begin{aligned} u(x, t) &= \lim_{p \rightarrow 1} \left( \sum_{n=0}^{\infty} p^n u_n(x, t) \right) \\ &= u_0(x, t) + u_1(x, t) + u_2(x, t) + u_3(x, t) + \dots \\ &= 2t + xt^2 + \frac{1}{30}t^6 - \frac{1}{30}t^6 + 0 + 0 + \dots \\ &= 2t + xt^2 \end{aligned} \quad (63)$$

## 4. Applications

### 4.1. Problem 1

Consider the following linear Klein-Gordon equation

$$\begin{cases} \frac{\partial^2 u(x, t)}{\partial t^2} = \frac{\partial^2 u(x, t)}{\partial x^2} + 3u(x, t) - 3 \sin x \sin t \\ u(x, 0) = 0 \\ u_t(x, 0) = \sin x \end{cases} \quad (64)$$

#### Application of the LADM

Using the Laplace transform, we have

$$s^2(u(x, t)) - su(x, 0) - \frac{\partial u(x, 0)}{\partial t} = \left( \frac{\partial^2 u(x, t)}{\partial x^2} + 3u(x, t) \right) - 3 \sin x (\sin t) \quad (65)$$

$\Leftrightarrow$

$$\mathcal{L}(u(x, t)) = \frac{1}{s}u(x, 0) + \frac{1}{s^2} \frac{\partial u(x, 0)}{\partial t} - 3 \left( \frac{1}{s^2} \right) \left( \frac{1}{s^2 + 1} \right) \sin x + \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u(x, t)}{\partial x^2} + 3u(x, t) \right) \quad (66)$$

By applying the inverse Laplace transform, we have:

$$\begin{aligned} u(x, t) &= \mathcal{L}^{-1} \left( \frac{1}{s}u(x, 0) \right) + \mathcal{L}^{-1} \left( \frac{1}{s^2} \frac{\partial u(x, 0)}{\partial t} \right) - (3 \sin x) \mathcal{L}^{-1} \left( \frac{1}{s^2(s^2 + 1)} \right) \\ &\quad + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u(x, t)}{\partial x^2} + 3u(x, t) \right) \right) \end{aligned} \quad (67)$$

$\Leftrightarrow$

$$u(x, t) = (\sin x) \mathcal{L}^{-1} \left( \frac{1}{s^2} \right) - (3 \sin x) \mathcal{L}^{-1} \left( \frac{1}{s^2(s^2 + 1)} \right) + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u(x, t)}{\partial x^2} + 3u(x, t) \right) \right)$$

$\Leftrightarrow$

$$u(x, t) = 3 \sin t \sin x - 2t \sin x + \mathcal{L}^{-1} \left( \frac{1}{s^2} \left( \frac{\partial^2 u(x, t)}{\partial x^2} + 3u(x, t) \right) \right) \quad (68)$$

From above equation, we have the following modified Adomian allgorithm:

$$\begin{cases} u_0(x, t) = \sin t \sin x \\ u_1(x, t) = 2 \sin t \sin x - 2t \sin x + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u_0(x, t)}{\partial x^2} + 3u_0(x, t) \right) \right) \\ u_{n+1}(x, t) = \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u_n(x, t)}{\partial x^2} + 3u_n(x, t) \right) \right), \forall n \geq 1 \end{cases} \quad (69)$$

Equation (69) give us:

$$\begin{aligned} u_1(x, t) &= 2 \sin t \sin x - 2t \sin x + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} \left( \frac{\partial^2 u_0(x, t)}{\partial x^2} + 3u_0(x, t) \right) \right) \\ &= 2 \sin t \sin x - 2t \sin x + \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} (2 \sin t \sin x) \right) \\ &= 2 \sin t \sin x - 2t \sin x + (2 \sin x) \mathcal{L}^{-1} \left( \frac{1}{s^2} \mathcal{L} (\sin t) \right) \\ &= 2 \sin t \sin x - 2t \sin x + 2t \sin x - 2 \sin x \sin t = 0 \end{aligned} \quad (70)$$

Thus

$$\begin{cases} u_0(x, t) = \sin x \sin t \\ u_n(x, t) = 0, \forall n \geq 1 \end{cases} \quad (71)$$

and the exact solution of Equation (64) is

$$u(x, t) = \sin x \sin t \quad (72)$$

## 4.2. Problem 2

Consider the following nonlinear Klein-Gordon equation

$$\begin{cases} \frac{\partial^2 u(x, t)}{\partial t^2} = \frac{\partial^2 u(x, t)}{\partial x^2} + u(x, t) - u^2(x, t) + xt + x^2 t^2 \\ u(x, 0) = 1 \\ \frac{\partial u(x, 0)}{\partial x} = x \end{cases} \quad (73)$$

### Application of the LADM

Using the Laplace transform from (73), we have:

$$\begin{aligned} \mathcal{L}(u(x, t)) &= \frac{s}{s^2 - 1} \left( \frac{1 + s^2}{s^2(s^2 - 1)} \right) x + \frac{2}{s^3(s^2 - 1)} x^2 \\ &\quad + \frac{1}{s^2 - 1} \mathcal{L} \left( \frac{\partial^2 u(x, t)}{\partial x^2} \right) - \frac{1}{s^2 - 1} \mathcal{L}[u^2(x, t)] \end{aligned} \quad (74)$$

Now, we apply the inverse Laplace transform, we have:

$$\begin{aligned} u(x, t) &= \mathcal{L}^{-1}\left(\frac{s}{s^2-1}\right) + \mathcal{L}^{-1}\left(\frac{1+s^2}{s^2(s^2-1)}\right)x + \mathcal{L}^{-1}\left(\frac{2}{s^3(s^2-1)}\right)x^2 \\ &\quad + \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}\left(\frac{\partial^2 u(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}[u^2(x, t)]\right) \end{aligned} \quad (75)$$

Thus

$$\begin{aligned} u(x, t) &= 1 + xt + e^t x - 2xt - e^{-t}x + e^t x^2 + e^{-t}x^2 - t^2 x^2 - 2x^2 + \frac{e^t}{2} + \frac{e^{-t}}{2} - 1 \\ &\quad + \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}\left(\frac{\partial^2 u(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}[u^2(x, t)]\right) \end{aligned} \quad (76)$$

Denoting that the solution of (73) has the following form:

$$u(x, t) = \sum_{n=0}^{+\infty} u_n(x, t) \quad (77)$$

$$u^2(x, t) = \sum_{n=0}^{+\infty} A_n \quad (78)$$

Taking (77) and (78) into (76), we have:

$$\begin{aligned} \sum_{n=0}^{+\infty} u_n(x, t) &= 1 + xt + e^t x - 2xt - e^{-t}x + e^t x^2 + e^{-t}x^2 - t^2 x^2 - 2x^2 + \frac{e^t}{2} + \frac{e^{-t}}{2} - 1 \\ &\quad + \sum_{n=0}^{+\infty} \left( \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}\left(\frac{\partial^2 u_n(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\mathcal{L}\left(\frac{1}{s^2-1}(A_n)\right) \right) \end{aligned} \quad (79)$$

and we obtain the following Adomian algorithm:

$$\left\{ \begin{array}{l} u_0(x, t) = 1 + xt \\ u_1(x, t) = e^t x - 2xt - e^{-t}x + e^t x^2 + e^{-t}x^2 - t^2 x^2 - 2x^2 + \frac{e^t}{2} + \frac{e^{-t}}{2} - 1 \\ \quad + \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}\left(\frac{\partial^2 u_0(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}(A_0)\right) \\ u_{n+1}(x, t) = \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}\left(\frac{\partial^2 u_n(x, t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}(A_n)\right), \forall n \geq 1 \end{array} \right. \quad (80)$$

Calculation  $u_1(x, t)$

$$\left\{ \begin{array}{l} A_0 = N(u_0) = u_0^2(x, t) = 1 + 2xt + x^2 t^2 \\ u_1(x, t) = e^t x - 2xt - e^{-t}x + e^t x^2 + e^{-t}x^2 - t^2 x^2 - 2x^2 + \frac{e^t}{2} + \frac{e^{-t}}{2} - 1 \\ \quad + \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}\left(\frac{\partial^2}{\partial x^2}(1+xt)\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2-1}\mathcal{L}(1+2xt+x^2t^2)\right) \\ = e^t x - xe^t - 2xt + 2tx - xe^{-t} + xe^{-t} + e^t x^2 - e^t x^2 + e^{-t}x^2 - e^{-t}x^2 \\ \quad - 2x^2 + 2x^2 + \frac{1}{2}e^t - \frac{1}{2}e^t + \frac{1}{2}e^{-t} - \frac{1}{2}e^{-t} + t^2 x^2 - t^2 x^2 + 1 - 1 \\ = 0 \end{array} \right. \quad (81)$$

Thus

$$\begin{cases} u_0(x,t) = 1 + xt \\ A_n = 0, \quad \forall n \geq 1 \\ u_n(x,t) = 0, \quad \forall n \geq 1 \end{cases} \quad (82)$$

So that, the solution  $u(x,t)$  is given by:

$$\begin{aligned} u(x,t) &= u_0(x,t) + u_1(x,t) + u_2(x,t) + \dots \\ &= 1 + xt + 0 + 0 + \dots = 1 + xt \end{aligned} \quad (83)$$

which is the exact solution of the problem.

### 4.3. Problem 3

Consider the following nonlinear Klein-Gordon equation

$$\begin{cases} \frac{\partial^2 u(x,t)}{\partial t^2} = \frac{\partial^2 u(x,t)}{\partial x^2} - u(x,t) - u^2(x,t) + x^2 \cos^2 t \\ u(x,0) = x \\ \frac{\partial u(x,0)}{\partial t} = 0 \end{cases} \quad (84)$$

#### Application of the LADM

Using the Laplace transform, we have:

$$\mathcal{L}(u(x,t)) = \frac{s}{s^2+1}x + \left( \frac{s^2+2}{s(s^2+1)(s^2+4)} \right)x^2 + \frac{1}{(s^2+1)}\mathcal{L}\left(\frac{\partial^2 u(x,t)}{\partial x^2}\right) - \frac{1}{s^2+1}\mathcal{L}[u^2(x,t)] \quad (85)$$

The inverse Laplace transformation is applied to Equation (85) we get

$$\begin{aligned} u(x,t) &= x^{-1}\left(\frac{s}{s^2+1}\right) + x^2\mathcal{L}^{-1}\left(\frac{s^2+2}{s(s^2+1)(s^2+4)}\right) \\ &\quad + \mathcal{L}^{-1}\left[\frac{1}{(s^2+1)}\mathcal{L}\left(\frac{\partial^2 u(x,t)}{\partial x^2}\right)\right] - \mathcal{L}^{-1}\left(\frac{1}{s^2+1}\mathcal{L}[u^2(x,t)]\right) \\ &= x \cos t + \frac{1}{2}x^2 - \frac{1}{6}x^2 \cos 2t - \frac{1}{3}x^2 \cos t \\ &\quad + \mathcal{L}^{-1}\left(\frac{1}{(s^2+1)}\mathcal{L}\left(\frac{\partial^2 u(x,t)}{\partial x^2}\right)\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2+1}\mathcal{L}[u^2(x,t)]\right) \end{aligned} \quad (86)$$

As before, we defines the solution  $u(x,t)$  by the series

$$u(x,t) = \sum_{n=0}^{+\infty} u_n(x,t) \quad (87)$$

and  $u_{xx}$  can be defined by an infinite series

$$\frac{\partial^2 u(x,t)}{\partial x^2} = \sum_{n=0}^{+\infty} \frac{\partial^2 u_n(x,t)}{\partial x^2} \quad (88)$$

The nonlinear term  $N(u) = u^2$  is decomposed in term of Adomian polynomials

$$N(u(x,t)) = \sum_{n=0}^{+\infty} A_n \quad (89)$$

Substituting (87), (88) and (89) into both sides of Equation (86) we obtain

$$\begin{aligned} \sum_{n=0}^{+\infty} u_n(x,t) &= x \cos t + \frac{1}{2} x^2 - \frac{1}{6} x^2 \cos 2t - \frac{1}{3} x^2 \cos t \\ &+ \sum_{n=0}^{+\infty} \mathcal{L}^{-1} \left( \frac{1}{(s^2+1)} \mathcal{L} \left( \frac{\partial^2 u_n(x,t)}{\partial x^2} \right) \right) - \sum_{n=0}^{+\infty} \mathcal{L}^{-1} \left( \frac{1}{s^2+1} \mathcal{L}(A_n) \right) \end{aligned} \quad (90)$$

The recursive relation is defined by

$$\begin{cases} u_0(x,t) = x \cos t \\ u_1(x,t) = \frac{1}{2} x^2 - \frac{1}{6} x^2 \cos 2t - \frac{1}{3} x^2 \cos t + \mathcal{L}^{-1} \left( \frac{1}{(s^2+1)} \mathcal{L} \left( \frac{\partial^2 u_0(x,t)}{\partial x^2} \right) \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2+1} \mathcal{L}(A_0) \right) \\ u_{n+1}(x,t) = \mathcal{L}^{-1} \left( \frac{1}{(s^2+1)} \mathcal{L} \left( \frac{\partial^2 u_n(x,t)}{\partial x^2} \right) \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2+1} \mathcal{L}(A_n) \right); \forall n \geq 1 \end{cases} \quad (91)$$

(91) give us

$$\begin{cases} A_0 = u_0^2 = x^2 \cos^2 t \\ u_1(x,t) = \frac{1}{2} x^2 - \frac{1}{6} x^2 \cos 2t - \frac{1}{3} x^2 \cos t \\ \quad + \mathcal{L}^{-1} \left( \frac{1}{(s^2+1)} \mathcal{L} \left( \frac{\partial^2}{\partial x^2} (x \cos t) \right) \right) - \mathcal{L}^{-1} \left( \frac{1}{s^2+1} \mathcal{L}(A_0) \right) \\ = \frac{1}{2} x^2 - \frac{1}{2} x^2 - \frac{1}{6} x^2 \cos 2t + \frac{1}{6} x^2 \cos 2t - \frac{1}{3} x^2 \cos t + \frac{1}{3} x^2 \cos t \\ = 0 \end{cases} \quad (92)$$

Thus

$$\begin{cases} u_0(x,t) = x \cos t \\ A_0 = x^2 \cos^2 t \\ u_n(x,t) = 0, \forall n \geq 1 \\ A_n = 0, \forall n \geq 1 \end{cases} \quad (93)$$

and the exact solution of Equation (84) is

$$u(x,t) = x \cos t \quad (94)$$

## 5. Conclusion

Through these examples, we showed again the usefulness of Laplace-Adomian Decomposition method and the He-Laplace method, in the search of an approximate solution of Klein-Gordon equation holds for the accepted forms of strong interaction of antiparticles in modern physics.

## References

- [1] Behe, H.A. (2002) Modern Quantum Theory. 4th Edition, Freeman and Co., San Francisco.

- [2] Fadaei, J. (2011) Application of Laplace-Adomian Decomposition Method on Linear and Nonlinear System of PDEs. *Applied Mathematical Sciences*, **5**, 1307-1315.
- [3] Abbaoui, K. (1995) Les fondements de la méthode décompositionnelle d'Adomian et application à la résolution de problèmes issus de la biologie et de la médecine. Thèse de doctorat de l'Université Paris VI.
- [4] Abbaoui, K. and Cherruault, Y. (1994) Convergence of Adomian Method Applied to Differential Equations. *Mathematical and Computer Modellings*, **28**, 103-109.
- [5] Abbaoui, K. and Cherruault, Y. (1994) Convergence of Adomian's Method Applied to Non Linear Equations. *Mathematical and Computer Modelling*, **20**, 60-73.
- [6] Abbaoui, K. and Cherruault, Y. (1999) The Decomposition Method Applied to the Cauchy Problem. *Kybernetes*, **28**, 68-74. <http://dx.doi.org/10.1108/03684929910253261>
- [7] He, J.H. (2005) Application of Homotopy Perturbation Method to Nonlinear Wave Equation. *Chaos, Solitons, Fractals*, **26**, 295-300. <http://dx.doi.org/10.1016/j.chaos.2005.03.006>



Scientific Research Publishing

**Submit or recommend next manuscript to SCIRP and we will provide best service for you:**

Accepting pre-submission inquiries through Email, Facebook, LinkedIn, Twitter, etc.

A wide selection of journals (inclusive of 9 subjects, more than 200 journals)

Providing 24-hour high-quality service

User-friendly online submission system

Fair and swift peer-review system

Efficient typesetting and proofreading procedure

Display of the result of downloads and visits, as well as the number of cited articles

Maximum dissemination of your research work

Submit your manuscript at: <http://papersubmission.scirp.org/>

Or contact [jamp@scirp.org](mailto:jamp@scirp.org)