

Razumikhin-Type Theorems on General Decay Stability of Impulsive Stochastic Functional Differential Systems with Markovian Switching

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Abstract

In this paper, the Razumikhin approach is applied to the study of both p -th moment and almost sure stability on a general decay for a class of impulsive stochastic functional differential systems with Markovian switching. Based on the Lyapunov-Razumikhin methods, some sufficient conditions are derived to check the stability of impulsive stochastic functional differential systems with Markovian switching. One numerical example is provided to demonstrate the effectiveness of the results.

Keywords

Impulsive Stochastic Functional Differential System, p -th Moment Stability, Almost Sure Stability, Lyapunov-Razumikhin Approach

1. Introduction

Impulsive stochastic systems with Markovian switching is a class of hybrid dynamical systems, which is composed of both the logical switching rule of continuous-time finite-state Markovian process and the state represented by a stochastic differential system [1]. Because of the presence of both continuous dynamics and discrete events, these types of models are capable of describing many practical systems in many areas, including social science, physical science, finance, control engineering, mechanical and industry. So this kind of systems have received much attention, recently (for instance, see [2]-[5]).

It is well-known that stability is the major issue in the study of control theory, one of the most important

techniques applied in the investigation of stability for various classes of stochastic differential systems is based on a stochastic version of the Lyapunov direct method. However, the so-called Razumikhin technique combined with Lyapunov functions has also been a powerful and effective method in the study of stability. Recalled that Razumikhin developed this technique to study the stability of deterministic systems with delay in [6] [7], then, Mao extended this technique to stochastic functional differential systems [8]. This technique has become very popular in recent years since it is extensively applied to investigate many phenomena in physics, biology, finance, etc.

Mao incorporated the Razumikhin approach in stochastic functional differential equations [9] and in neutral stochastic functional differential equations [10] to investigate both p -th moment and almost sure exponential stability of these systems (see also [11]-[13], for instance). Later, this technique was appropriately developed and extended to some other stochastic functional differential systems, especially important in applications, such as stochastic functional differential systems with infinite delay [14]-[16], hybrid stochastic delay interval systems [17] and impulsive stochastic delay differential systems [18]-[20]. Recently, some researchers have introduced ψ -type function and extended the stability results to the general decay stability, including the exponential stability as a special case in [21]-[23], which has a wide applicability.

In the above cited papers, both the p -th moment and almost sure stability on a general decay are investigated, but mostly used in stochastic differential equations. And As far as I know, a little work has been done on the impulsive stochastic differential equations or systems. In this paper, we will close this gap by extending the general decay stability to the impulsive stochastic differential systems. To the best of our knowledge, there are no results based on the general decay stability of impulsive stochastic delay differential systems with Markovian switching. And the main aim of the present paper is attempt to investigate the p -th moment and almost sure stability on a general decay of impulsive stochastic delay differential systems with Markovian switching. Since the delay phenomenon and the Markovian switching exists among impulsive stochastic systems, the whole systems become more complex and may oscillate or be not stable, we introduce Razumikhin-type theorems and Lyapunov methods to give the conditions that make the systems stable. By the aid of Lyapunov-Razumikhin approach, we obtain the p -th moment general decay stability of impulsive stochastic delay differential systems with Markovian. In order to establish the criterion on almost surely general decay stability of impulsive stochastic delay differential systems with Markovian, the Holder inequality, Burkholder-Davis-Gundy inequality and Borel-Cantelli's lemma are utilized in this paper.

The paper is organized as follows. Firstly, the problem formulations, definitions of general decay stability and some lemmas are given in Section 2. In Section 3, the main results on p -th moment and almost sure stability on a general decay of impulsive stochastic delay differential systems with Markovian switching are obtained with Lyapunov-Razumikhin methods. An example is presented to illustrate the main results in Section 4. In the last section the conclusions are given.

2. Preliminaries

Throughout this paper, let (Ω, \mathcal{F}, P) be a complete probability space with some filtration $\{\mathcal{F}_t\}_{t \geq 0}$ satisfying the usual condition (*i.e.*, the filtration is increasing and right continuous while \mathcal{F}_0 contain all P-null sets). Let $B = (B(t), t \geq 0)$ be an m -dimensional \mathcal{F}_t -adapted Brownian motion.

Let \mathbb{R}^n be the n -dimensional Euclidean space; $\mathbb{R}^{n \times m}$ denotes the $n \times m$ real matrix space; \mathbb{R}_+ is the set of all non-negative real numbers; $PC([- \tau, 0]; \mathbb{R}^n)$ denotes the family of continuous functions $\varphi: [- \tau, 0] \rightarrow \mathbb{R}^n$ with the norm $\|\varphi\| = \sup_{\theta \in [- \tau, 0]} |\varphi(\theta)|$; $|\cdot|$ denotes the standard Euclidean norm for vectors; let $p \geq 1, t \geq 0, PC_{\mathcal{F}_t}^p([- \tau, 0]; \mathbb{R}^n)$ denotes the family of \mathcal{F}_t -measurable $PC([- \tau, 0]; \mathbb{R}^n)$ -valued random variables $\varphi = \{\varphi(\theta) : -\tau \leq \theta \leq 0\}$ such that $\sup_{\theta \in [- \tau, 0]} E|\varphi(\theta)|^p < \infty$ and $PC_{\mathcal{F}_0}^b([- \tau, 0]; \mathbb{R}^n)$ be the \mathcal{F}_0 -measurable $PC([- \tau, 0]; \mathbb{R}^n)$ -valued random variables; $E[\cdot]$ means the expectation of a stochastic process; $\mathbb{N} = 1, 2, \dots, N$ is a discrete index set, where N is a finite positive integer.

Let $r(t), t \geq 0$ be a right-continuous Markov chain on the probability space taking values in a finite state space $\Gamma = 1, 2, \dots, N$ with generator $\Pi = (\pi_{ij}), i, j \in \Gamma$ given by

$$P\{r(t + \Delta) = j \mid r(t) = i\} = \begin{cases} \pi_{ij}\Delta + o(\Delta) & i \neq j \\ 1 + \pi_{ij}\Delta + o(\Delta) & i = j \end{cases}$$

where $\Delta > 0$, $\lim_{\Delta \rightarrow 0} \frac{o(\Delta)}{\Delta} = 0$ and $\pi_{ij} \geq 0$ is the transition rate from i to j if $i \neq j$ while $\pi_{ij} = -\sum_{j \neq i} \pi_{ij}$.

We assume that the Markov chain $r(\cdot)$ is independent of the Brownian motion $B(\cdot)$. It is well known that almost every sample path of $r(t)$ is a right-continuous step function with a finite number of simple in any subinterval if $[0, \infty)$. In other words, there exist a sequence of stopping times $0 = t_0 < t_1 < \dots < t_k \rightarrow \infty$ almost surely such that $r(t)$ is a constant in every interval $[t_{k-1}, t_k)$ for any $k \geq 1$, i.e.

$$r(t) = r(t_{k-1}), \quad \forall t \in [t_{k-1}, t_k), k \geq 1.$$

In this paper, we consider the following impulsive stochastic delay differential systems with Markovian switching

$$\begin{cases} dx(t) = f(t, x_t, r(t))dt + g(t, x_t, r(t))dB(t), & t \neq t_k, t \geq t_0 \\ \Delta x(t_k) = I_k(x(t_k^-), t_k), & k \in \mathbb{N} \\ x_{t_0} = \xi \end{cases} \tag{1}$$

where the initial value $\xi \in PC^b([-\tau, 0]; \mathbb{R}^n)$, $x(t) = (x_1(t), \dots, x_n(t))^T$, $x_t = x(t + \theta) \in PC_{\mathcal{F}_t}^p([-\tau, 0]; \mathbb{R}^n)$, $f : PC_{\mathcal{F}_t}^p([-\tau, 0]; \mathbb{R}^n) \times \mathbb{R}_+ \rightarrow \mathbb{R}^n$, $g : PC_{\mathcal{F}_t}^p([-\tau, 0]; \mathbb{R}^n) \times \mathbb{R}_+ \rightarrow \mathbb{R}^{n \times d}$, $I_k(x(t_k^-), t_k) : \mathbb{R}^n \times \mathbb{R}_+ \rightarrow \mathbb{R}^n$ represents the impulsive perturbation of x at time t_k . The fixed moments of impulse times t_k satisfy $0 \leq t_0 < t_1 < \dots < t_k < \dots, t_k \rightarrow \infty$ (as $k \rightarrow \infty$), $\Delta x(t_k) = x(t_k) - x(t_k^-)$.

For the existence and uniqueness of the solution we impose a hypothesis:

Assumption (H): For $f(\varphi, t)$ and $g(\varphi, t)$ satisfy the local Lipschitz condition and the linear growth condition. That is, there exist a constant $L > 0$ such that

$$|f(\varphi, t) - f(\phi, t)|^2 \vee |g(\varphi, t) - g(\phi, t)|^2 \leq L \|\varphi - \phi\|^2$$

For all $t \geq 0$, and $\varphi, \phi \in PC([-\tau, 0]; \mathbb{R}^n)$, and, moreover, there are a constant $K > 0$ such that

$$|f(\varphi, t)|^2 \vee |g(\varphi, t)|^2 \leq K(1 + \|\varphi\|^2)$$

For all $t \geq 0$, and $\varphi \in PC([-\tau, 0]; \mathbb{R}^n)$.

Definition 1 $\psi(t) : \psi(t) \in C^1([-\tau, \infty); \mathbb{R}_+)$ is said to be ψ -type function, if it satisfies the following conditions:

- (1) It is continuous, monotone increasing and differentiable;
- (2) $\psi(0) = 1$ and $\psi(\infty) = \infty$;
- (3) $\psi_1(t) = \psi'(t)/\psi(t) > 0$.
- (4) for any $t, s \geq 0, \psi(t) \leq \psi(s)\psi(t-s)$.

Definition 2 For $p > 0$, impulsive stochastic delay differential systems with Markovian switching (1) is said to be p -th moment stable with decay $\psi(t)$ of order γ , if there exist positive constants γ and function $\psi(\cdot)$, such that

$$\limsup_{t \rightarrow \infty} \frac{\ln E|x(t, \xi)|^p}{\ln \psi(t)} \leq -\gamma. \tag{2}$$

when $p = 2$, we say that it is ψ^γ stable in mean square, when $\psi(t) = e^t$, we say that it is p -th moment exponential stable, when $\psi(t) = 1 + t$, we say that it is p -th moment polynomial stable.

Definition 3 impulsive stochastic delay differential systems with Markovian switching (1) is said to be almost surely stable with decay $\psi(t)$ of order γ , if there exist positive constant γ and function $\psi(\cdot)$, such that

$$\limsup_{t \rightarrow \infty} \frac{\ln |x(t, \xi)|}{\ln \psi(t)} \leq -\gamma, \quad a.s. \tag{3}$$

when $\psi(t) = e^t$, we say that it is almost surely exponential stable, when $\psi(t) = 1 + t$, we say that it is almost surely polynomial stable.

Let $\mathcal{C}^{1,2}(\mathbb{R}^n \times [t_0 - \tau, \infty) \times \Gamma)$ denote the family of all nonnegative functions $V(x, t, i)$ on $\mathbb{R}^n \times [t_0 - \tau, \infty) \times \Gamma$ that are continuously once differentiable in t and twice in x . For each $V \in \mathcal{C}^{1,2}$ define an operator $\mathcal{L}V : PC_{\mathcal{F}_t}^p([- \tau, 0]; \mathbb{R}^n) \times [t_0 - \tau, \infty) \times \Gamma \rightarrow \mathbb{R}^+$ for system (1) by

$$\mathcal{L}V(x, t, i) = V_t(x, t, i) + V_x(x, t, i)f(x, t, i) + \frac{1}{2} \text{trace} [g^T(x, t, i)V_{xx}(x, t, i)g(x, t, i)] + \sum_{j=1}^N \pi_{ij}V(x, t, j)$$

where

$$V_t(x, t, i) = \frac{\partial V(x, t, i)}{\partial t}, V_x(x, t, i) = \left(\frac{\partial V(x, t, i)}{\partial x_1}, \dots, \frac{\partial V(x, t, i)}{\partial x_n} \right), V_{xx}(x, t, i) = \left(\frac{\partial^2 V(x, t, i)}{\partial x_i \partial x_j} \right)_{n \times n}$$

Lemma 1 (Burkholder-Davis-Cundy inequality) *Let $g \in L^2([0, T]; \mathbb{R}^{n \times m})$, $0 < p < \infty$, there exist positive constants c_p and C_p , such that*

$$c_p E \left[\int_0^T |g(t)|^2 dt \right]^{\frac{p}{2}} \leq E \left[\sup_{0 \leq t \leq T} \left| \int_0^t g(s) dw(s) \right|^p \right] \leq C_p E \left[\int_0^T |g(t)|^2 dt \right]^{\frac{p}{2}}$$

where

$$c_p = \left(\frac{p}{2} \right)^p, C_p = \left(\frac{32}{p} \right)^{\frac{p}{2}}, \text{ if } p \in (0, 2);$$

$$c_p = 1, C_p = 4, \text{ if } p = 2;$$

$$c_p = (2p)^{\frac{p}{2}}, C_p = \left[\frac{p^{p+1}}{2(p-1)^{p-1}} \right]^{\frac{p}{2}}, \text{ if } p > 2.$$

Lemma 2 (Borel-Cantelli's lemma)

(1) If $\{A_k\} \subset \mathcal{F}$ and $\sum_{k=1}^{\infty} P(A_k) < \infty$, then

$$P \left(\limsup_{t \rightarrow \infty} A_k \right) = 0.$$

That is, there exist a set $\Omega_o \in \mathcal{F}$ with $P(\Omega_o) = 1$ and an integer valued random variable k_o such that for every $\omega \in \Omega_o$ we have $\omega \notin A_k$ whenever $k \geq k_o(\omega)$.

(2) If the sequence $\{A_k\} \subset \mathcal{F}$ is independent and $\sum_{k=1}^{\infty} P(A_k) = \infty$, then

$$P \left(\limsup_{t \rightarrow \infty} A_k \right) = 1.$$

That is, there exists a set $\Omega_\theta \in \mathcal{F}$ with $P(\Omega_\theta) = 1$, such that for every $\omega \in \Omega_\theta$, there exists a sub-sequence $\{A_{k_i}\}$ such that the ω belongs to every A_{k_i} .

3. Main Results

In this section, we shall establish some criteria on the p -th moment exponential stability and almost exponential stability for system (1) by using the Razumikhin technique and Lyapunov functions.

Theorem 1 *For systems (1), let (H) hold, and ψ is a ψ -type function, Assume that there exist a function $V \in \mathcal{C}^{1,2}(\mathbb{R}^n \times [t_0 - \tau, \infty); \mathbb{R}_+)$, positive constants $c_1, c_2, \gamma > 0, \mu \geq \gamma$ and $\lambda > 1$ such that*

(H₁) For all $(x, t, i) \in \mathbb{R}^n \times [-\tau, \infty) \times \Gamma$

$$c_1 |x|^p \leq V(x, t, i) \leq c_2 |x|^p \tag{4}$$

(H₂) For all $t \in [t_k - 1, t_k), k \in \mathbb{N}$

$$E \left[\max_{i \in \Gamma} \mathcal{L}V(\varphi, t, i) \right] \leq -\mu \psi_1(t) E \left[\min_{i \in \Gamma} V(\varphi(0), t, i) \right] \tag{5}$$

For all $t \geq 0, \theta \in [-\tau, 0]$ and those $\varphi \in PC_{\mathcal{F}_t}^p([-\tau, 0]; \mathbb{R}^n)$ satisfying

$$E \left[\min_{i \in \Gamma} V(\varphi(t + \theta), t + \theta, i) \right] \leq q E \left[\max_{i \in \Gamma} V(\varphi(0), t, i) \right] \tag{6}$$

where $q \geq \lambda \psi^\gamma(-\theta)$.

(H₃) For all $k \in \mathbb{N}$ and $x \in PC_{\mathcal{F}_t}^p(\omega; \mathbb{R}^n)$

$$EV(x + I_k(x, t_k), t_k, r(t_k)) \leq \beta_k EV(x(t_k^-), t_k^-, r(t_k^-)) \tag{7}$$

where $0 \leq \beta_k \leq \psi^{-\gamma}(t_{k+1} - t_k)$ and $\lambda \beta_k \geq 1$.

Then, for any initial $\xi \in PC_{\mathcal{F}_0}^p([-\tau, 0]; \mathbb{R}^n)$, there exists a solution $x(t) = x(t, \xi)$ on $[t_0, \infty]$ to system (1). Moreover, the system (1) is p -th moment exponentially stable with decay $\psi(t)$ of order γ .

Proof. Fix the initial data $\xi \in PC_{\mathcal{F}_0}^p([-\tau, 0]; \mathbb{R}^n)$ arbitrarily and write $x(t, \xi) = x(t)$ simply. When μ is replaced by γ , if we can prove that the system (1) is p -th moment exponentially stable with decay $\psi(t)$ of order γ for all $\gamma \in (0, \mu)$, then the desired result is obtained. Choose $M > 0$ satisfying $0 < c_2 \psi^\gamma(t_1 - t_0) \leq M < c_2 \lambda \psi^\gamma(-\theta)$, and thus we can have the following fact:

$$0 < c_2 \|\xi\|^p \leq M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0).$$

Then it follows from condition (H₁) that

$$EV(x(t), t, r(t)) \leq c_2 \|\xi\|^p \leq M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0), \quad t \in [t_0 - \tau, t_0].$$

In the following, we will use the mathematical induction method to show that

$$EV(x(t), t, r(t)) \leq M \|\xi\|^p \psi^{-\gamma}(t_k - t_0), \quad t \in [t_{k-1}, t_k], k \in \mathbb{N}. \tag{8}$$

In order to do so, we first prove that

$$EV(x(t), t, r(t)) \leq M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0), \quad t \in [t_0, t_1]. \tag{9}$$

This can be verified by a contradiction. Hence, suppose that inequality (9) is not true, then there exist some $t \in [t_0, t_1)$ such that $EV(x(t), t, r(t)) > M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0)$. Set

$t^* = \inf \{t \in [t_0, t_1) : EV(x(t), t, r(t)) > M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0)\}$. By using the continuity of $EV(x(t), t, r(t))$ in the interval $[t_0, t_1)$, then $t^* \in (t_0, t_1)$ and

$$EV(x(t^*), t^*, r(t^*)) = M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0) \tag{10}$$

$$EV(x(t), t, r(t)) < M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0), \quad t \in [t_0 - \tau, t^*). \tag{11}$$

Define $t^{**} = \sup \{t \in [t_0 - \tau, t^*] : EV(x(t), t, r(t)) \leq c_2 \|\xi\|^p\}$, then $t^{**} \in [t_0, t^*)$ and

$$EV(x(t^{**}), t^{**}, r(t^{**})) = c_2 \|\xi\|^p \tag{12}$$

$$EV(x(t), t, r(t)) > c_2 \|\xi\|^p, \quad t \in (t^{**}, t^*]. \tag{13}$$

Consequently, for all $t \in [t^{**}, t^*]$, we have

$$\begin{aligned} &EV(x(t + \theta), t + \theta, r(t + \theta)) \\ &\leq M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0) < c_2 \lambda \psi^\gamma(-\theta) \|\xi\|^p \psi^{-\gamma}(t_1 - t_0) < c_2 \lambda \psi^\gamma(-\theta) \|\xi\|^p \\ &= \lambda \psi^\gamma(-\theta) EV(x(t^{**}), t^{**}, r(t^{**})) \leq q EV(x(t^{**}), t^{**}, r(t^{**})) \leq q EV(x(t), t, r(t)), \end{aligned}$$

And so

$$E \left[\min_{i \in \Gamma} V(\varphi(\theta), t + \theta, i) \right] < qE \left[\max_{i \in \Gamma} V(\varphi(0), t, i) \right].$$

By condition (H₂) we have

$$E \left[\max_{i \in \Gamma} \mathcal{L}V(\varphi, t, i) \right] \leq -\mu\psi_1(t) E \left[\min_{i \in \Gamma} V(\varphi(0), t, i) \right], \quad t \in [t^{**}, t^*].$$

Consequently,

$$E\mathcal{L}V(\varphi, t, i) \leq -\mu\psi_1(t) EV(\varphi(0), t, i), \quad t \in [t^{**}, t^*]. \tag{14}$$

Applying the *Itô* formula to $\psi^\gamma(t)EV(x(t), t, r(t))$ yields

$$\begin{aligned} & \psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) - \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})) \\ &= \int_{t^{**}}^{t^*} E\mathcal{L}[\psi^\gamma(t)V(x(t), t, r(t))] dt \\ &= \int_{t^{**}}^{t^*} \gamma\psi^{\gamma-1}(t)(\psi^\gamma(t))' EV(x(t), t, r(t)) + \psi^\gamma(t)E\mathcal{L}LV(x(t), t, r(t)) \\ &= \int_{t^{**}}^{t^*} \psi^\gamma(t) [\gamma\psi_1(t)EV(x(t), t, r(t)) + E\mathcal{L}V(x(t), t, r(t))] dt. \end{aligned} \tag{15}$$

By condition (14), we obtain

$$\psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) - \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})) < 0. \tag{16}$$

On the other hand, a direct computation yields

$$\begin{aligned} & \psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) = \psi^\gamma(t^*)M \|\xi\|^p \psi^{-\gamma}(t_1 - t_0) \\ & \geq c_2\psi^\gamma(t_1 - t_0)\psi^\gamma(t^{**})\|\xi\|^p \psi^{-\gamma}(t_1 - t_0) \\ & = c_2\psi^\gamma(t^{**})\|\xi\|^p = \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})), \end{aligned}$$

that is

$$\psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) - \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})) > 0,$$

which is a contradiction. So inequality (9) holds and (8) is true for $k = 1$. Now we assume that (8) is satisfied for $k = 1, 2, \dots, m (m \geq 1)$, *i.e.* for every $t \in [t_{k-1}, t_k], k = 1, 2, \dots, m$,

$$EV(x(t), t, r(t)) \leq M \|\xi\|^p \psi^{-\gamma}(t_k - t_0). \tag{17}$$

Then, we will prove that (8) holds for $k = m + 1$,

$$EV(x(t), t, r(t)) \leq M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0). \tag{18}$$

Suppose (18) is not true, *i.e.* there exist some $t \in [t_m, t_{m+1})$ such that

$$EV(x(t), t, r(t)) > M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0). \tag{19}$$

Then, it follows from the condition (H₃) and (17) that

$$\begin{aligned} EV(x(t_m), t_m, r(t_m)) &= EV(x + I_m(x(t_m^-)), t_m, r(t_m)) \leq \beta_m EV(x(t_m^-), t_m^-, r(t_m^-)) \\ &\leq \psi^{-\gamma}(t_{m+1} - t_m)M \|\xi\|^p \psi^{-\gamma}(t_m - t_0) \\ &\leq M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_m + t_m - t_0) = M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0), \end{aligned}$$

which implies that the t_m dose not satisfy the inequality (19). And from this, set

$t^* = \inf \{t \in (t_m, t_{m+1}): EV(x(t), t, r(t)) > M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0)\}$. By the continuity of $EV(x(t), t, r(t))$ in the

interval (t_m, t_{m+1}) , we know that $t^* \in (t_m, t_{m+1})$ and

$$EV(x(t^*), t^*, r(t^*)) = M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0), \tag{20}$$

$$EV(x(t), t, r(t)) < M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0), \quad t \in [t_m, t^*]. \tag{21}$$

Define $t^{**} = \sup\{t \in [t_m - \tau, t^*] : EV(x(t), t, r(t)) \leq \beta_m M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0)\}$, then $t^{**} \in [t_m, t^*]$ and

$$EV(x(t^{**}), t^{**}, r(t^{**})) = \beta_m M \|\xi\|^p \psi^{-\gamma}(t_m - t_0), \tag{22}$$

$$EV(x(t), t, r(t)) > \beta_m M \|\xi\|^p \psi^{-\gamma}(t_m - t_0), \quad t \in (t^{**}, t^*]. \tag{23}$$

Fix any $t \in [t^{**}, t^*]$, when $t + \theta \geq t_m$ for all $\theta \in [-\tau, 0]$, then (20)-(22) imply that

$$\begin{aligned} &EV(x(t + \theta), t + \theta, r(t + \theta)) \\ &\leq M \|\xi\|^p \psi^{-\gamma}(t_{m+1} - t_0) < M \|\xi\|^p \psi^{-\gamma}(t + \theta - t_0) \\ &\leq \lambda \beta_m M \|\xi\|^p \psi^{-\gamma}(t + \theta - t_0) \leq \lambda \beta_m \|\xi\|^p \psi^{-\gamma}(-\theta) \psi^{-\gamma}(t_m - t_0) \\ &\leq qEV(x(t^{**}), t^{**}, r(t^{**})) \leq qEV(x(t), t, r(t)) \end{aligned}$$

If $t + \theta < t_m$ for some $\theta \in [-\tau, 0)$, we assume that, without loss of generality, $t + \theta \in [t_{s-1}, t_s)$, for some $s \in \mathbb{N}, s < m$, then from (17) and (20)-(22), we obtain

$$\begin{aligned} &EV(x(t + \theta), t + \theta, r(t + \theta)) \\ &\leq M \|\xi\|^p \psi^{-\gamma}(t_s - t_0) < M \|\xi\|^p \psi^{-\gamma}(t + \theta - t_0) \leq M \|\xi\|^p \psi^{-\gamma}(t - t_0) \psi^{-\gamma}(-\theta) \\ &\leq M \|\xi\|^p \psi^{-\gamma}(t_m - t_0) \psi^{-\gamma}(\alpha) \leq \lambda \beta_m \psi^{-\gamma}(-\theta) M \|\xi\|^p \psi^{-\gamma}(t_m - t_0) \\ &= \lambda \psi^{-\gamma}(-\theta) EV(x(t^{**}), t^{**}, r(t^{**})) \leq qEV(x(t^{**}), t^{**}, r(t^{**})) \leq qEV(x(t), t, r(t)) \end{aligned} \tag{24}$$

Therefore,

$$E\left[\min_{i \in \Gamma} V(\varphi(\theta), t + \theta, i)\right] < qE\left[\max_{i \in \Gamma} V(\varphi(0), t, i)\right], \quad t \in [t^{**}, t^*], \theta \in [-\tau, 0],$$

by condition (H₂) we have

$$E\left[\max_{i \in \Gamma} \mathcal{L}V(\varphi, t, i)\right] \leq -\mu \psi_1(t) E\left[\min_{i \in \Gamma} V(\varphi(0), t, i)\right], \quad t \in [t^{**}, t^*], \theta \in [-\tau, 0].$$

Consequently,

$$E\mathcal{L}V(\varphi, t, i) \leq -\mu \psi_1(t) EV(\varphi(0), t, i), \quad t \in [t^{**}, t^*]. \tag{25}$$

Similar to (15), applying the *Itô* formula to $\psi^\gamma(t)EV(x(t), t, r(t))$ yields

$$\begin{aligned} &\psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) - \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})) \\ &= \int_{t^{**}}^{t^*} \psi^\gamma(t) [\gamma \psi_1(t)EV(x(t), t, r(t)) + E\mathcal{L}V(x(t), t, r(t))] dt. \end{aligned}$$

By condition (25), we obtain

$$\psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) - \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})) < 0.$$

On the other hand, by (20) and (22), we have

$$\begin{aligned} & \psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) \\ &= \psi^\gamma(t^*)M \|\xi\|^p \psi^{-\gamma}(t_{m+1}-t_0) \geq \psi^\gamma(t^*)M \|\xi\|^p \psi^{-\gamma}(t_{m+1}-t_m) \psi^{-\gamma}(t_m-t_0) \\ &\geq \psi^\gamma(t^*)M \|\xi\|^p \psi^{-\gamma}(\alpha) \psi^{-\gamma}(t_m-t_0) \geq \beta_m \psi^\gamma(t^{**})M \|\xi\|^p \psi^{-\gamma}(t_m-t_0) \\ &= \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})), \end{aligned}$$

that is

$$\psi^\gamma(t^*)EV(x(t^*), t^*, r(t^*)) - \psi^\gamma(t^{**})EV(x(t^{**}), t^{**}, r(t^{**})) > 0.$$

which is a contradiction. So inequality (18) holds. Therefore, by mathematical induction, we obtain (8) holds for all $k \in \mathbb{N}$. Then from condition (H₁), we have

$$E|x(t)|^p \leq \frac{c_2}{c_1} M \|\xi\|^p \psi^{-\gamma}(t_k-t_0) \leq \frac{c_2}{c_1} M \|\xi\|^p \psi^{-\gamma}(t-t_0), \quad t \in [t_{k-1}, t_k], k \in \mathbb{N},$$

which implies

$$E|x(t)|^p \leq \frac{c_2}{c_1} M \|\xi\|^p \psi^{-\gamma}(t-t_0), \quad t \geq t_0$$

i.e., system (1) is p th moment exponentially stable with decay $\psi(t)$ of order γ . The proof is complete. \square

Theorem 2 For system (1), suppose all of the conditions of Theorem 1 are satisfied. Let $p \geq 1$, assume that there exist constants $K > 0$, such that for all $t \geq 0$ and $\varphi \in PC_{\mathcal{F}_t}^p([-\tau, 0]; \mathbb{R}^n)$,

$$E|f(t, \varphi)|^p + E|g(t, \varphi)|^p \leq K \sup_{\theta \leq 0} \psi^{-\mu}(-\theta) E|\varphi(\theta)|^p. \tag{26}$$

Then, for any initial $\xi \in PC_{\mathcal{F}_0}^b([-\tau, 0]; \mathbb{R}^n)$ and for any $\gamma \in (0, \mu)$, there exists a solution $x(t) = x(t, \xi)$ on $[t_0, \infty)$ to stochastic delay nonlinear system (1). Moreover, the system (1) is almost surely stable with decay $\psi(t)$ of order γ and

$$\limsup_{t \rightarrow \infty} \frac{\ln|x(t, \xi)|}{\ln \psi(t)} \leq -\frac{\gamma}{p}. \quad a.s. \tag{27}$$

Proof. Fix the initial data $\xi \in PC_{\mathcal{F}_0}^b([-\tau, 0]; \mathbb{R}^n)$ arbitrarily and write $x(t, \xi) = x(t)$ simply. We claim that

$$E \left[\sup_{t_{k-1} \leq t \leq t_k} |x(t)|^p \right] \leq H \psi^\gamma(t_{k-1}), \quad k \in \mathbb{N} \tag{28}$$

where

$$H = 3^{p-1} (k_\delta + 1) \left(M \frac{c_2}{c_1} + \frac{K(c_1 + Mc_2)(1 + C_p)}{c_1} \right) \|\xi\|^p.$$

Choose δ sufficiently small and $0 < \delta < 1 \wedge t_k - t_{k-1}$, for the fixed δ , let $k_\delta = \left\lfloor \frac{t_k - t_{k-1}}{\delta} \right\rfloor \in \mathbb{N}$, where $\lfloor x \rfloor$ is the maximum integer not more than x . Then for any $t \in [t_{k-1}, t_k)$, there exist positive integer i , $1 \leq i \leq k_\delta + 1$, such that $t_{k-1} + (i-1)\delta \leq t \leq t_{k-1} + i\delta$. So, for any $t \in [t_{k-1}, t_k)$, $k \in \mathbb{N}$, we obtain

$$E \left[\sup_{t_{k-1} \leq t \leq t_k} |x(t)|^p \right] \leq \sum_{i=1}^{k_\delta+1} E \left[\sup_{t_{k-1}+(i-1)\delta \leq t \leq t_{k-1}+i\delta} |x(t)|^p \right] \tag{29}$$

For each i when $1 \leq i \leq k_\delta + 1$, $k \in \mathbb{N}$, we obtain

$$\begin{aligned}
 & E \left[\sup_{t_{k-1}+(i-1)\delta \leq t \leq t_{k-1}+i\delta} |x(t)|^p \right] \\
 & \leq 3^{p-1} E |x(t_{k-1} + (i-1)\delta)|^p + 3^{p-1} E \left| \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} f(x_s, s, r(s)) ds \right|^p \\
 & \quad + 3^{p-1} E \left[\sup_{t_{k-1}+(i-1)\delta \leq t \leq t_{k-1}+i\delta} \left| \int_{t_{k-1}+(i-1)\delta}^t g(x_s, s, r(s)) dB(s) \right|^p \right].
 \end{aligned} \tag{30}$$

By Theorem 1, we have

$$E |x(t_{k-1} + (i-1)\delta)|^p \leq \frac{C_2}{c_1} M \|\xi\|^p \psi^{-\mu}(t_{k-1} + (i-1)\delta) \tag{31}$$

By Holder inequality, condition (26) and Theorem 1, we derives that

$$\begin{aligned}
 & E \left| \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} f(x_s, s, r(s)) ds \right|^p \leq \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} E |f(x_s, s, r(s))|^p ds \\
 & \leq K \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} \sup_{\theta \leq 0} \psi^{-\mu}(-\theta) E |x(s+\theta)|^p ds \\
 & \leq K \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} \left[\sup_{\theta \leq -s} \psi^{-\mu}(-\theta) E |x(s+\theta)|^p + \sup_{-s \leq \theta \leq 0} \psi^{-\mu}(-\theta) E |x(s+\theta)|^p \right] ds \\
 & \leq K \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} \left[\psi^{-\mu}(s) \|\xi\|^p + \sup_{-s \leq \theta \leq 0} \psi^{-\mu}(-\theta) \psi^{-\mu}(s+\theta) \frac{C_2}{c_1} \|\xi\|^p \right] ds \\
 & \leq K \left(1 + M \frac{C_2}{c_1} \right) \|\xi\|^p \int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} \psi^{-\mu}(s) ds \\
 & \leq \delta K \left(1 + M \frac{C_2}{c_1} \right) \|\xi\|^p \psi^{-\mu}(t_{k-1} + (i-1)\delta) \\
 & \leq K \left(1 + M \frac{C_2}{c_1} \right) \|\xi\|^p \psi^{-\mu}(t_{k-1} + (i-1)\delta).
 \end{aligned} \tag{32}$$

Similarly, by the Lemma 1 and (32), we obtain

$$\begin{aligned}
 & E \left[\sup_{t_{k-1}+(i-1)\delta \leq t \leq t_{k-1}+i\delta} \left| \int_{t_{k-1}+(i-1)\delta}^t (x_s, s, r(s)) dB(s) \right|^p \right] \\
 & \leq C_p E \left[\int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} |g(x_s, s, r(s))|^2 ds \right]^{\frac{p}{2}} \\
 & \leq C_p E \left[\int_{t_{k-1}+(i-1)\delta}^{t_{k-1}+i\delta} |g(x_s, s, r(s))|^p ds \right] \\
 & \leq C_p K \left(1 + M \frac{C_2}{c_1} \right) \|\xi\|^p \psi^{-\mu}(t_{k-1} + (i-1)\delta),
 \end{aligned} \tag{33}$$

where C_p is a positive constant dependent on p only.

Substituting (31), (32) and (33) into (30) yields

$$E \left[\sup_{t_{k-1}+(i-1)\delta \leq t \leq t_{k-1}+i\delta} |x(t)|^p \right] \leq 3^{p-1} \left[M \frac{C_2}{c_1} + (1 + C_p) K \left(1 + M \frac{C_2}{c_1} \right) \right] \|\xi\|^p \psi^{-\mu}(t_{k-1} + (i-1)\delta). \tag{34}$$

Thus, it follows from (29) and (34), we obtain

$$E \left[\sup_{t_{k-1} \leq t \leq t_k} |x(t)|^p \right] \leq 3^{p-1} (k_\delta + 1) \left[M \frac{c_2}{c_1} + (1 + C_p) K \left(1 + M \frac{c_2}{c_1} \right) \right] \|\xi\|^p \psi^{-\mu}(t_{k-1}) = H \psi^{-\mu}(t_{k-1}).$$

Using Chebyshev inequality, we have

$$P \left\{ \sup_{t_{k-1} \leq t \leq t_k} |x(t)|^p \geq \psi^{-\gamma}(t_k) \right\} \leq \psi^\gamma(t_k) E \left[\sup_{t_{k-1} \leq t \leq t_k} |x(t)|^p \right] \leq \psi^\gamma(t_k) H \psi^{-\mu}(t_{k-1}) \\ \leq H \psi^\gamma(t_k - t_{k-1}) \psi^{-(\mu-\gamma)}(t_{k-1})$$

Since $\sum_{k=1}^\infty \psi^{-(\mu-\gamma)}(t_k - t_{k-1}) < \infty$, by Lemma 2, when $t_k \rightarrow \infty$, $t_{k-1} \leq t \leq t_k$, we obtain

$$|x(t)|^p \leq \psi^{-\gamma}(t_k) \leq \psi^{-\gamma}(t), \quad a.s.$$

That is

$$\limsup_{t \rightarrow \infty} \frac{\ln |x(t, \xi)|}{\ln \psi(t)} \leq -\frac{\gamma}{p}. \quad a.s.$$

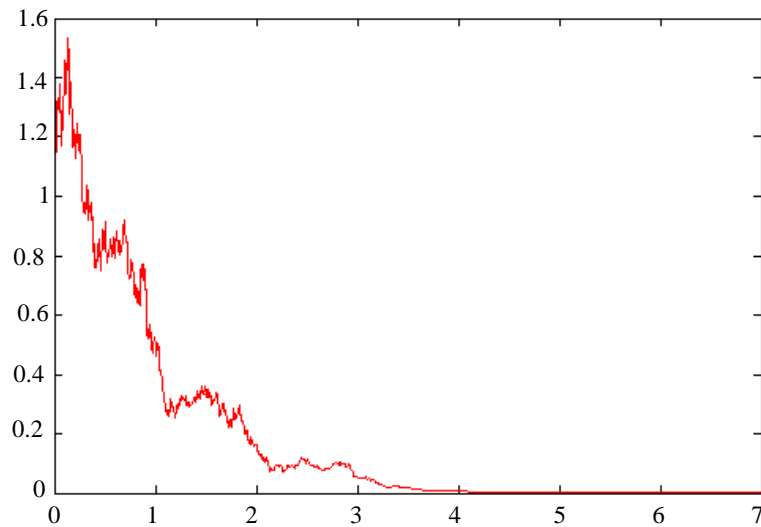


Figure 1. State of the example.

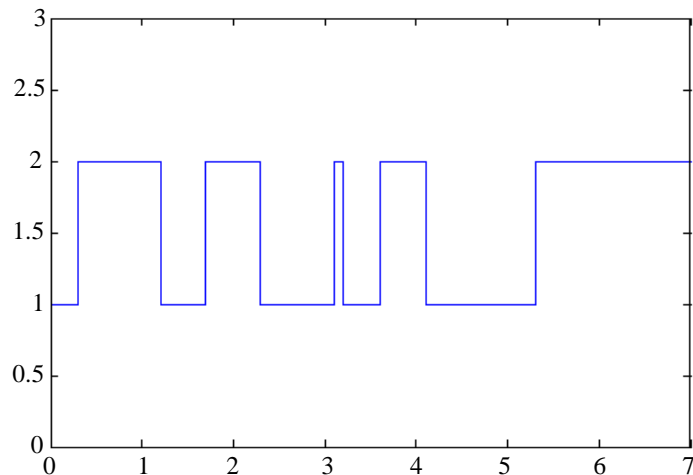


Figure 2. Markovian switching of the example.

Thus, the system (1) is almost surely stable with decay $\psi(t)$ of order γ .

4. Examples

In this section, a numerical example is given to illustrate the effectiveness of the main results established in Section 3 as follows. Consider an impulsive stochastic delay system with Markovian switching as follows

$$\begin{cases} dx(t) = f(t, x_t, r(t))dt + g(t, x_t, r(t))dB(t), & t \neq t_k, t \geq t_0 \\ \Delta x(t_k) = \frac{1}{k^2}x(t_k^-), & k \in \mathbb{N} \end{cases} \tag{35}$$

where $r(t)$ is a right-continuous Markov chain taking values in $\{1, 2\}$ with generator

$$\Pi = \begin{bmatrix} -1.5 & 1.5 \\ 1 & -1 \end{bmatrix}$$

And independent of the scalar Brownian motion $B(t)$, $f(x_t, t, 1) = -5x(t) + 0.5x(t - 0.2)$,
 $f(x_t, t, 2) = -8x(t) + 6x(t - 0.2)$, $g(x_t, t, 1) = \frac{\sqrt{10}}{4}x(t - 0.2)$, $g(x_t, t, 2) = 0.5x(t - 0.2)$, $t_k - t_{k-1} = 0.4, k \in \mathbb{N}$.

Choosing $p = 2, V(t, x, 1) = V(t, x, 2) = x^2, \tau = 0.2, q = 1.9, \gamma = 2, \max\{t_{k+1} - t_k\} \leq 0.4, k \in \mathbb{N}$,
 $\psi(t) = e^{t^2}(1 + 0.5t^2), t > 0$, then $\psi(0) = 1, \psi(\infty) = \infty, \psi'(t) = te^{t^2}(3 + t^2)$,
 $\psi_1(t) = \frac{\psi'(t)}{\psi(t)} = 2 + \frac{2}{2 + t^2}, 2 \leq \psi_1(t) \leq 3$, then we have

$$\begin{aligned} ELV_1(x_t, t, r(t)) &= -10Ex|t|^2 + Ex(t)x(t - 0.2) + 1.25E|x(t - 0.2)|^2 \\ &\leq -10E|x(t)|^2 + 0.5E|x(t)|^2 + 0.5E|x(t - 0.2)|^2 + 1.25E|x(t - 0.2)|^2 \\ &\leq -10E|x(t)|^2 + 0.5E|x(t)|^2 + 1.75qE|x(t)|^2 \\ &\leq -9E|x(t)|^2 + 3E|x(t)|^2 \leq -2\psi_1(t) \end{aligned}$$

and

$$\begin{aligned} ELV_1((x_t, t, r(t))) &= -16Ex|t|^2 + 3Ex(t)x(t - 0.2) + 0.5E|x(t - 0.2)|^2 \\ &\leq -16E|x(t)|^2 + 3E|x(t)|^2 + 3E|x(t - 0.2)|^2 + 3.5E|x(t - 0.2)|^2 \\ &\leq -16E|x(t)|^2 + 3E|x(t)|^2 + 3.5qE|x(t)|^2 \\ &\leq -16E|x(t)|^2 + 10E|x(t)|^2 \leq -2\psi_1(t) \end{aligned}$$

By Theorem 1, we know that $E[\max_{i \in \Gamma} \mathcal{L}V(\varphi, t, i)] \leq -\gamma\psi_1(t)E[\min_{i \in \Gamma} V(\varphi(0), t, i)]$, which means that the conditions of Theorem 1 are satisfied. So the impulsive stochastic delay system with Markovian switching is p -th moment stable with decay $e^{t^2}(1 + 0.5t^2)$ of order 2. The simulation result of system (35) is shown in **Figure 1**, and the Markovian switching of system (35) is described in **Figure 2**.

5. Conclusion

In this paper, p -th moment and almost surely stability on a general decay have been investigated for a class of impulsive stochastic delay systems with Markovian switching. Some sufficient conditions have been derived to check the stability criteria by using the Lyapunov-Razumikhin methods. A numerical example is provided to verify the effectiveness of the main results.

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