# Mode Stresses for the Interaction between Straight and Curved Cracks Problem in Plane Elasticity 

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#### Abstract

In this paper, the complex variable function method is used to obtain the hypersingular integral equations for the interaction between straight and curved cracks problem in plane elasticity. The curved length coordinate method and suitable quadrature rule are used to solve the integrals for the unknown function, which are later used to evaluate the stress intensity factor, SIF. Three types of stress modes are presented for the numerical results.


## Keywords

## Hypersingular Integral Equation, Complex Variable Function Method, Stress Intensity Factor

## 1. Introduction

In order to predict the safety and stability of components, many researchers paid attention to the crack geometry. Several types of integral equations have been developed to formulate the single crack problem such as singular integral equation [1], Fredholm integral equation [2], hypersingular integral equation [3] and interaction integral equation [4]. Formulation for the multiple cracks problem are also obtained in terms of singular integral equation [5], Fredholm integral equation [6] and hypersingular integral equation [7] for various set of cracks positions.

These integral equations can be solved numerically using the polynomial approximation of the dislocation distribution. This approach was achieved by taken the crack opening displacement (COD) as the unknown and the resultant forces as the right term in the equations [8].

In this paper, the formulation for the interaction between straight and curved cracks in term of hypersingular integral equations is obtained using the complex potential method. Then, the cracks are mapped into a straight line using the curved length coordinate method. In order to solve the equations numerically, the quadrature rules are applied with $M+1$ collocation points. The obtained unknown coefficients will later be used in calculating the SIF. In this paper, we consider three types of loading modes: Mode I, Mode II and Mode III for the numerical computations.

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## 2. Complex Variable Function Method

Let $\Phi(z)=\phi^{\prime}(z)$ and $\Psi(z)=\psi^{\prime}(z)$ be two complex potentials. Then the stress ( $\left.\sigma_{x}, \sigma_{y}, \sigma_{z}\right)$, the resultant function $(X, Y)$ and the displacement $(u, v)$ are related to $\Phi(z)$ and $\Psi(z)$ as [9]

$$
\begin{gather*}
\sigma_{x}+\sigma_{y}=4 \operatorname{Re} \Phi(z)  \tag{1}\\
\sigma_{y}-\sigma_{x}+2 i \sigma_{x y}=2[\overline{z \Phi} \Phi(z)+\Psi(z)]  \tag{2}\\
f=-Y+i X=\phi(z)+z \overline{\phi^{\prime}(z)}+\overline{\psi(z)}+c  \tag{3}\\
2 G(u+i v)=K \phi(z)-z \overline{\phi^{\prime}(z)}+\psi(z) \tag{4}
\end{gather*}
$$

where $G$ is shear modulus of elasticity, $K=3-v$ for plane strain, $K=(3-v) /(1+v)$ for plane stress and $v$ is Poisson's ratio and $z=x+i y$. The derivative in a specified direction (DISD) is defined as

$$
\begin{equation*}
J\left(z, \bar{z}, \frac{d \bar{z}}{d z}\right)=\frac{d}{d z}\{-Y+i X\}=\Phi(z)+\overline{\Phi(z)}+\frac{d \bar{z}}{d z}\left(z \overline{\Phi^{\prime}(z)}+\overline{\Psi(z)}\right)=N+i T \tag{5}
\end{equation*}
$$

where $J$ denotes the normal and tangential tractions along the segment $\overline{z, z+d t}$. Note that the value of $J$ not only depends on the position of point $z$, but also on the direction of the segment $d \bar{z} / d z$ [3].

Let the complex potentials $\phi(z)$ and $\psi(z)$ be

$$
\begin{gathered}
\phi(z)=\frac{1}{2 \pi} \int_{L} \frac{g(t) d t}{t-z} \\
\psi(z)=\frac{1}{2 \pi}\left[\int_{L} \frac{g(t) d \bar{t}}{t-z}+\int_{L} \frac{\overline{g(t)} d t}{t-z}-\int_{L} \frac{\overline{\operatorname{tg}}(t) d t}{(t-z)^{2}}\right]
\end{gathered}
$$

where $L$ denotes the crack configuration and substitute into (4). By letting $z$ approaches $t_{0}^{+}$and $t_{0}^{-}$, which are located on the upper and lower sides of the crack faces (see Figure 1), then using the Plemelj equations [3], and rewriting $t_{0}$ as $t$, the following result is obtained [3]

$$
\begin{equation*}
2 G(u(t)+i v(t))=i(k+1) g(t),(t \in L) \tag{6}
\end{equation*}
$$

and

$$
(u(t)+i v(t))=(u(t)+i v(t))^{+}-(u(t)+i v(t))^{-}
$$

denotes the crack opening displacement (COD) for the curved crack. It is well known that the COD possesses the following properties:

$$
\begin{equation*}
g(t)=O\left[\left(t-t_{B_{j}}\right)^{1 / 2}\right] \text { at the crack tip } B_{j}, j=1,2 \tag{7}
\end{equation*}
$$

## 3. Hypersingular Integral Equation

The hypersingular integral equation for a curved crack problem is obtained by placing two point dislocations at point $z=t$ and $z=t+d t$. It is given by [3]


Figure 1. A crack configuration.

$$
\begin{equation*}
\frac{1}{\pi} h \cdot p \cdot \int_{L} \frac{g(t) d t}{\left(t-t_{0}\right)^{2}}+\frac{1}{2 \pi} \int_{L} K_{1}\left(t, t_{0}\right) g(t) d t+\frac{1}{2 \pi} \int_{L} K_{2}\left(t, t_{0}\right) \overline{g(t)} d t=N\left(t_{0}\right)+i T\left(t_{0}\right), t_{0} \in L \tag{8}
\end{equation*}
$$

where

$$
\begin{gathered}
K_{1}\left(t, t_{0}\right)=\frac{-1}{\left(t-t_{0}\right)^{2}}+\frac{1}{\left(\bar{t}-\bar{t}_{0}\right)^{2}} \frac{d \bar{t}_{0}}{d t_{0}} \frac{d \bar{t}}{d t}, \\
K_{2}\left(t, t_{0}\right)=\frac{-1}{\left(\bar{t}-\bar{t}_{0}\right)^{2}}\left(\frac{d \bar{t}}{d t}+\frac{d \bar{t}_{0}}{d t_{0}}\right)-\frac{2\left(t-t_{0}\right)}{\left(\bar{t}-\bar{t}_{0}\right)^{3}} \frac{d \bar{t}_{0}}{d t_{0}} \frac{d \bar{t}}{d t}
\end{gathered}
$$

and $g(t)$ is the dislocation distribution along the curved. In Equation (8), the first integral with h.p. denotes the hypersingular integral and should be defined in the sense of Hadamart finite part integral. It easy to see that for a straight crack, Equation (8) is reduced to

$$
\begin{equation*}
\frac{1}{\pi} h \cdot p \cdot \int_{L} \frac{g(t) d t}{\left(t-t_{0}\right)^{2}}=N\left(t_{0}\right)+i T\left(t_{0}\right), t_{0} \in L \tag{9}
\end{equation*}
$$

and it can be solved analytically. Now consider the interaction between straight and curved cracks problem (see Figure 2).

For the crack-1, if the point dislocation is placed at point $z=t_{10}$ and $d z=d t_{10}$ and $g_{1}\left(t_{1}\right)$ is the dislocation doublet distribution along crack- 1 , and the traction is applied on the $t_{10}$ then the hypersingular integral equation for crack- 1 is

$$
\begin{equation*}
\frac{1}{\pi} h \cdot p \cdot \int_{L_{1}} \frac{g_{1}\left(t_{1}\right) d t_{1}}{\left(t_{1}-t_{10}\right)^{2}}=N_{11}\left(t_{10}\right)+i T_{11}\left(t_{10}\right) \tag{10}
\end{equation*}
$$

where $N_{11}\left(t_{10}\right)+i T_{11}\left(t_{10}\right)$ denotes the traction influence on crack-1 caused by dislocation doublet distribution, $g_{1}\left(t_{1}\right)$, on crack-1. The influence from the dislocation doublet distribution on crack-2 gives

$$
\begin{equation*}
\frac{1}{\pi} \int_{L_{2}} \frac{g_{2}\left(t_{2}\right) d t_{2}}{\left(t_{2}-t_{10}\right)^{2}}+\frac{1}{2 \pi} \int_{L_{2}} K_{1}\left(t_{2}, t_{10}\right) g_{2}\left(t_{2}\right) d t_{2}+\frac{1}{2 \pi} \int_{L_{2}} K_{2}\left(t_{2}, t_{10}\right) \overline{g_{2}\left(t_{2}\right)} d t_{2}=N_{12}\left(t_{10}\right)+i T_{12}\left(t_{10}\right) \tag{11}
\end{equation*}
$$

where $N_{12}\left(t_{10}\right)+i T_{12}\left(t_{10}\right)$ denotes the traction influence on crack-1 caused by dislocation doublet distribution, $g_{2}\left(t_{2}\right)$, on crack-2 and

$$
K_{1}\left(t_{2}, t_{10}\right)=\frac{-1}{\left(t_{2}-t_{10}\right)^{2}}+\frac{1}{\left(\bar{t}_{2}-\bar{t}_{10}\right)^{2}} \frac{d \bar{t}_{10}}{d t_{10}} \frac{d \bar{t}_{2}}{d t_{2}},
$$



Figure 2. Straight and curved cracks in plane elasticity with configurations on a real axis-s. Cracks with length $2 a$ (straight) and $2 b$ (curved) are known as crack-1 and crack-2 respectively.

$$
K_{2}\left(t_{2}, t_{10}\right)=\frac{-1}{\left(\bar{t}_{2}-\bar{t}_{10}\right)^{2}}\left(\frac{d \bar{t}_{2}}{d t_{2}}+\frac{d \bar{t}_{10}}{d t_{10}}\right)-\frac{2\left(t_{2}-t_{10}\right)}{\left(\bar{t}_{2}-\bar{t}_{10}\right)^{3}} \frac{d \bar{t}_{10}}{d t_{10}} \frac{d \bar{t}_{2}}{d t_{2}} .
$$

Note that since $t_{2}-t_{10} \neq 0$, all three integrals in (11) are regular and that $g_{1}\left(t_{1}\right)$ and $g_{2}\left(t_{2}\right)$ satisfy (7). By superposition of the dislocation doublet distribution, $g_{1}\left(t_{1}\right)$ along the crack- 1 and dislocation doublet distribution, $g_{2}\left(t_{2}\right)$ along the crack-2, we obtained the following hypersingular integral equation for crack-1

$$
\begin{equation*}
\frac{1}{\pi} h . p \cdot \int_{L_{1}} \frac{g_{1}\left(t_{1}\right) d t_{1}}{\left(t_{1}-t_{10}\right)^{2}}+\frac{1}{\pi} \int_{L_{2}} \frac{g_{2}\left(t_{2}\right) d t_{2}}{\left(t_{2}-t_{10}\right)^{2}}+\frac{1}{2 \pi}\left[\int_{L_{2}}\left(K_{1}\left(t_{2}, t_{10}\right) g_{2}\left(t_{2}\right)+K_{2}\left(t_{2}, t_{10}\right) \overline{g_{2}\left(t_{2}\right)}\right) d t_{2}\right]=N_{1}\left(t_{10}\right)+i T_{1}\left(t_{10}\right) \tag{12}
\end{equation*}
$$

where

$$
N_{1}\left(t_{10}\right)+i T_{1}\left(t_{10}\right)=N_{11}\left(t_{10}\right)+N_{12}\left(t_{10}\right)+i\left(T_{11}\left(t_{10}\right)+i T_{12}\left(t_{10}\right)\right)
$$

is the traction applied at point $t_{10}$ of crack-1, which is derived from the boundary condition. The first integrals represents the effect on crack- 1 caused by the dislocation on the crack- 1 itself, whereas the second three integrals represent the effect of the dislocations on crack-2.

Similarly, the hypersingular integral equation for crack-2 is

$$
\begin{equation*}
\frac{1}{\pi} h . p \cdot \int_{L_{2}} \frac{g_{2}\left(t_{2}\right) d t_{2}}{\left(t_{2}-t_{20}\right)^{2}}+\frac{1}{2 \pi} \int_{L_{2}} K_{1}\left(t_{2}, t_{20}\right) g_{2}\left(t_{2}\right) d t_{2}+\frac{1}{2 \pi} \int_{L_{2}} K_{2}\left(t_{2}, t_{20}\right) \overline{g_{2}\left(t_{2}\right)} d t_{2}+\frac{1}{\pi} \int_{L_{1}} \frac{g_{1}\left(t_{1}\right) d t_{1}}{\left(t_{1}-t_{20}\right)^{2}}=N_{2}\left(t_{20}\right)+i T_{2}\left(t_{20}\right) \tag{13}
\end{equation*}
$$

where

$$
N_{2}\left(t_{20}\right)+i T_{2}\left(t_{20}\right)=N_{21}\left(t_{20}\right)+N_{22}\left(t_{20}\right)+i\left(T_{21}\left(t_{20}\right)+i T_{22}\left(t_{20}\right)\right)
$$

is the traction applied at point $t_{20}$ of crack-2 and

$$
\begin{gathered}
K_{1}\left(t_{2}, t_{20}\right)=\frac{-1}{\left(t_{2}-t_{20}\right)^{2}}+\frac{1}{\left(\bar{t}_{2}-\bar{t}_{20}\right)^{2}} \frac{d \bar{t}_{20}}{d t_{20}} \frac{d \bar{t}_{2}}{d t_{2}}, \\
K_{2}\left(t_{2}, t_{20}\right)=\frac{-1}{\left(\overline{t_{2}}-\bar{t}_{20}\right)^{2}}\left(\frac{d \bar{t}_{2}}{d t_{2}}+\frac{d \bar{t}_{20}}{d t_{20}}\right)-\frac{2\left(t_{2}-t_{20}\right)}{\left(\bar{t}_{2}-\bar{t}_{20}\right)^{3}} \frac{d \bar{t}_{20}}{d t_{20}} \frac{d \bar{t}_{2}}{d t_{2}} .
\end{gathered}
$$

The first three integrals in (13) represent the effect on crack-2 caused by the dislocation on crack-2 itself, and the fourth integral represents the effect of the dislocation on crack-1. Equations (12) and (13) are to be solved for $g_{1}\left(t_{1}\right)$ and $g_{2}\left(t_{2}\right)$. It is obvious that if the two cracks are far apart, the last three integrals in Equation (12) and the fourth integral in Equation (13) vanish. Then the solutions for Equations (12) and (13) approach the solution for a single crack problem, and a closed form solution is available [10].

By mapping the two cracks configurations on a real axis $s$ with an interval $2 a$ and $2 b$ respectively, the mapping functions $t_{1}\left(s_{1}\right)$ and $t_{2}\left(s_{2}\right)$ are expressed as

$$
\begin{align*}
& \left.g_{1}\left(t_{1}\right)\right|_{t_{1}=t_{1}\left(s_{1}\right)}=\sqrt{a^{2}-s_{1}^{2}} H_{1}\left(s_{1}\right)  \tag{14}\\
& \left.g_{2}\left(t_{2}\right)\right|_{t_{2}=t_{2}\left(s_{2}\right)}=\sqrt{b^{2}-s_{2}^{2}} H_{2}\left(s_{2}\right) \tag{15}
\end{align*}
$$

where $H_{1}\left(s_{1}\right)=H_{11}\left(s_{1}\right)+i H_{12}\left(s_{1}\right)$ and $H_{2}\left(s_{2}\right)=H_{21}\left(s_{2}\right)+i H_{22}\left(s_{2}\right)$.
In solving the integral equations, we used the following integration rules [11], for the hypersingular and regular integrals, respectively,

$$
\begin{gather*}
\frac{1}{\pi} \int_{-a}^{a} \frac{\sqrt{a^{2}-s^{2}} G(s)}{\left(s-s_{0}\right)^{2}} d s=\sum_{j=1}^{M+} W_{j}\left(s_{0}\right) G\left(s_{j}\right),\left(\left|s_{0}\right|<a\right)  \tag{16}\\
\frac{1}{\pi} \int_{-a}^{a} \sqrt{a^{2}-s^{2}} G(s) d s=\frac{1}{M+2} \sum_{j=1}^{M+1}\left(a^{2}-s_{j}^{2}\right) G\left(s_{j}\right),\left(\left|s_{0}\right|<a\right), \tag{17}
\end{gather*}
$$

where $G(s)$ is a given regular function, $M \in \mathbb{Z}$,

$$
s_{j}=s_{0 j}=a \cos \left(\frac{j \pi}{M+2}\right), j=1,2,3, \ldots, M+1,
$$

and

$$
W_{j}\left(s_{0}\right)=-\frac{2}{M+2} \sum_{n=0}^{M}(n+1) V_{j}^{n} U_{n}\left(\frac{s_{0}}{a}\right),
$$

where

$$
V_{j}^{n}=\sin \left(\frac{j \pi}{M+2}\right) \sin \left(\frac{(n+1) j \pi}{M+2}\right)
$$

Here $U_{n}(t)$ is a Chebyshev polynomial of the second kind, defined by

$$
U_{n}(t)=\sin \left(\frac{(n+1) \theta}{\sin \theta}\right), t=\cos \theta
$$

$H_{1}(s)$ and $H_{2}(s)$ can be evaluated using

$$
\begin{equation*}
H_{1}(s)=\sum_{n=0}^{M} c_{1 n} U_{n}\left(\frac{s}{a}\right),|s| \leq a \tag{18}
\end{equation*}
$$

and

$$
\begin{equation*}
H_{2}(s)=\sum_{n=0}^{M} c_{2 n} U_{n}\left(\frac{s}{b}\right),|s| \leq b \tag{19}
\end{equation*}
$$

where

$$
\begin{align*}
c_{1 n} & =\frac{2}{M+2} \sum_{j=1}^{M+1} V_{j}^{n} H_{1}\left(s_{1}\right)  \tag{20}\\
c_{2 n} & =\frac{2}{M+2} \sum_{j=1}^{M+1} V_{j}^{n} H_{2}\left(s_{2}\right) \tag{21}
\end{align*}
$$

and $H_{1}\left(s_{1}\right)$ and $H_{2}\left(\mathrm{~s}_{2}\right)$ are defined from (14) and (15) respectively.

## 4. Numerical Results

The stress intensity factor (SIF) of inner and outer cracks can be calculated respectively

$$
\begin{equation*}
K_{A_{j}}=\left(K_{1}-i K_{2}\right)_{A_{j}}=\sqrt{2 \pi} \lim _{t \rightarrow t_{A_{j}}} \sqrt{\left|t-t_{A_{j}}\right|} \mid g_{1}^{\prime}(t) \tag{22}
\end{equation*}
$$

and

$$
\begin{equation*}
K_{B_{j}}=\left(K_{1}-i K_{2}\right)_{B_{j}}=\sqrt{2 \pi} \lim _{t \rightarrow t_{B_{j}}} \sqrt{\left|t-t_{B_{j}}\right|} g_{2}^{\prime}(t) \tag{23}
\end{equation*}
$$

where $g_{1}^{\prime}(t)$ and $g_{2}^{\prime}(t)$ can be obtained by using Equations (12) and (13) simultaneously.
As the two cracks are far apart, the formulations in Equations (12) and (13) become an equation for a straight and a curved crack respectively. For the straight crack with length $2 a$, we obtain $K=1.000 \sqrt{\pi \mathrm{a}}$ which is similar to the exact solution $K=\sqrt{\pi a}$. Whereas, for the curved crack, we compare the result of the curved crack with the exact solution using the remote traction $\sigma_{x}^{\infty}=\sigma_{y}^{\infty}=1$, given by [9]

$$
\begin{equation*}
K_{1}=\frac{(\pi a)^{1 / 2} \cos \left(\frac{a}{2}\right)}{1+\sin ^{2}\left(\frac{a}{2}\right)}, K_{2}=\frac{(\pi a)^{1 / 2} \sin \left(\frac{a}{2}\right)}{1+\sin ^{2}\left(\frac{a}{2}\right)} \tag{24}
\end{equation*}
$$

The numerical results are tabulated in Table 1. It can be seen that maximum error is not more than $1.0 \%$ and the results show very good agreement.

### 4.1. Example 1: Mode I

Consider the traction applied is $\sigma_{x}^{\infty}=\sigma_{y}^{\infty}=p_{1}$ and the calculated results for SIF at the crack tips $A_{1}, A_{2}, B_{1}$ and $B_{2}$ are respectively expressed as

$$
\begin{aligned}
& K_{i A_{j}}=F_{i A_{j}}(b / a) p_{1} \sqrt{\pi a}, i, j=1,2 \\
& K_{i B_{j}}=F_{i B_{j}}(b / a) p_{1} \sqrt{\pi a}, i, j=1,2
\end{aligned}
$$

Figure 3 shows the nondimensional SIF for a curved crack when $\frac{c}{a}=0.8,0.9,1.0$. It is found that the real
Table 1. The SIF for single curved crack: A comparison between exact and numerical results.

| $\sigma$ | $K_{1 A_{1}}$ | $K_{1 A_{1}}$ (exact) | $K_{2 A_{A}}$ | $K_{2 \mathcal{A}_{1}}$ (exact) |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0.9972 | 0.9956 | 0.0435 | 0.0413 |
| 10 | 0.9887 | 0.9840 | 0.0865 | 0.0777 |
| 20 | 0.9748 | 0.9677 | 0.1283 | 0.1091 |
| 30 | 0.9560 | 0.9493 | 0.1686 | 0.1584 |
| 40 | 0.9326 | 0.9308 | 0.2068 | 0.2046 |
| 50 | 0.9053 | 0.9133 | 0.2426 | 0.2420 |
| 60 | 0.8746 | 0.8966 | 0.2758 | 0.2560 |
| 70 | 0.8413 | 0.8788 | 0.3062 | 0.3058 |
| 80 | 0.8059 | 0.8240 | 0.3338 | 0.3411 |
| 90 | 0.7690 | 0.7786 | 0.3806 | 0.3798 |
|  |  |  |  |  |



Figure 3. Nondimensional SIF when $\theta$ is changing.
parts of SIF at the left crack tip $B_{1}$ is equal to its right crack tip $B_{2}\left(F_{1 B_{1}}=F_{1 B_{2}}\right)$, whereas the imaginary parts give opposite sign $\left(F_{2 B_{2}}=-F_{2 B_{1}}\right)$. The effect of the distance between both cracks is also studied and the result is shown in Figure 4. The nondimensional SIF for the straight crack is decreased at the same rate when $\theta<10^{0}$ whereas increased with different rates when $\theta>10^{\circ}$ and the SIF becomes higher as the two cracks are close together.

### 4.2. Example 2: Mode II

The traction applied for this mode is $\sigma_{x}^{\infty}=\sigma_{y}^{\infty}=p_{2}$ and the calculated results for SIF at the crack tips $A_{1}, A_{2}, B_{1}$ and $B_{2}$ are respectively expressed as

$$
\begin{aligned}
& K_{i A_{j}}=F_{i A_{j}}(b / a) p_{2} \sqrt{\pi a}, i, j=1,2 \\
& K_{i B_{j}}=F_{i B_{j}}(b / a) p_{2} \sqrt{\pi a}, i, j=1,2
\end{aligned}
$$

Figure 5 shows the nondimensional SIF for a curved crack when $\frac{c}{a}=0.8,0.9,1.0$ and the effect of the distance between both cracks is shown in Figure 6. The nondimensional SIF for the straight crack is decreased with different rates at the considered domain. As the two cracks are close together, the nondimensional SIF at the crack tip is higher.

### 4.3. Example 3: Mode III

Consider the traction applied is $\sigma_{x}^{\infty}=\sigma_{y}^{\infty}=q$ and the calculated results for SIF at the crack tips $A_{1}, A_{2}, B_{1}$ and $B_{2}$ are respectively expressed as

$$
\begin{aligned}
& K_{i A_{j}}=F_{i A_{j}}(b / a) q \sqrt{\pi a}, i, j=1,2 \\
& K_{i B_{j}}=F_{i B_{j}}(b / a) q \sqrt{\pi a}, i, j=1,2
\end{aligned}
$$

Figure 7 shows the nondimensional SIF for a curved crack when $\frac{c}{a}=0.8,0.9,1.0$. It is found that the imagi-


Figure 4. Nondimensional SIF when $\theta$ is changing.


Figure 5. Nondimensional SIF when $\theta$ is changing.


Figure 6. Nondimensional SIF when $\theta$ is changing.
nary parts of SIF at the left crack tip $B_{1}$ is equal to its right crack tip $B_{2}\left(F_{2 B_{1}}=F_{2 B_{2}}\right)$, whereas the real parts give opposite sign ( $F_{1 B_{2}}=-F_{1 B_{1}}$ ). The effect of the distance between both cracks is shown in Figure 8. For $\theta<15^{0}$ the nondimensional SIF is decreased at the same rate but later increased at the different rates.

## 5. Conclusion

In this paper, the different types of loading modes have been applied to the interaction between straight and curved cracks problem in plane elasticity. As the result, we obtained different results of nondimensional SIF due to the different loading modes. We also observed that the SIF increases as both cracks become closer. For a


Figure 7. Nondimensional SIF when $\theta$ is changing.


Figure 8. Nondimensional SIF when $\theta$ is changing.
symmetry shape crack problem, the real parts of SIF for the left side of the crack is equal to its right side while the imaginary parts give the opposite sign.

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