# Spatial Segregation Limit of a Quasilinear Competition-Diffusion System 

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Received 26 September 2015; accepted 8 November 2015; published 11 November 2015
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#### Abstract

The aim of this paper is to investigate a Volterra-Lotka competition model of quasilinear parabolic equations with large interaction. Some existence, uniqueness and convergence results for the system are given. Also investigated is its spatial segregation limit when the interspecific competition rates become large. We show that the limit problem is similar to a free boundary problem.


## Keywords

Competition-Diffusion System, Quasilinear, Spatial Segregation, Free Boundary Problem

## 1. Introduction

In this paper, we study the spatial and temporal behavior of interacting biological species. Assuming the reaction rates of competition follow the Holling-Tanner interaction mechanism, the quasilinear reaction-diffusion model under consideration can be given by

$$
\begin{cases}u_{t}-\Delta\left(\left(d_{1}+\alpha_{11} u\right) u\right)=u\left(a_{1}-b_{1} u-c_{1} v /\left(1+\sigma_{1} u\right)\right) & \text { in } D,  \tag{1}\\ v_{t}-\Delta\left(\left(d_{2}+\alpha_{22} v\right) v\right)=v\left(a_{2}-b_{2} u /\left(1+\sigma_{2} u\right)-c_{2} v\right) & \text { in } D, \\ \frac{\partial u}{\partial \gamma}=\frac{\partial v}{\partial \gamma}=0 & \text { on } S, \\ u(0, x)=u_{0}(x), v(0, x)=v_{0}(x) & \text { in } \Omega,\end{cases}
$$

here $D=R^{+} \times \Omega, \bar{D}=R^{+} \times \bar{\Omega}, S=R^{+} \times \partial \Omega$, where $\Omega$ is a bounded domain in $\mathbb{R}^{2}$.
$d_{i}, \alpha_{i i}, a_{i}, b_{i}, c_{i}(i=1,2)$ are all positive constants. $u(t, x)$ and $v(t, x)$ stand for their population densities of ${ }^{*}$ Corresponding author.
the competing species at the time $t$ and at the habitat $x \in \Omega . a_{i} \quad(i=1,2)$ is the respective intrinsic growth rates, $b_{1}$ and $c_{2}$ represent the intra-specific competition rates, whereas $c_{1}$ and $b_{2}$ represent the inter-specific competition rates. The boundary condition models the fact that species have no-flux near the boundary, where $\gamma$ is the outward normal unit vector to $\partial \Omega . \sigma_{1}$ may not be equal to $\sigma_{2}$ from an ecological point of view, but for the convenience of presentation, we may assume $\sigma_{1}=\sigma_{2}$ here.

Quasilinear parabolic equations have received a great attention in recent years. We can refer to [1]-[6] and the references therein for more details. However, the main concerns in above works are for the existence of a global solution, a weak solution, periodic solutions, the existence-uniqueness of positive solutions, blow-up property of the solution, and the qualitative property of the solution including finite time extinction and large time behavior of the solution.

Our main interest is different from those of the above works, we mainly consider the spatial segregation limit of (1) when only the interspecific competition rates $c_{1}$ and $b_{2}$ are very large. To study this case, it is convenient to rewrite (1) as the following equivalent form:

$$
\begin{cases}u_{t}-\Delta\left(\left(d_{1}+\alpha_{11} u\right) u\right)=u\left(a_{1}-b_{1} u-k v /(1+\sigma u)\right) & \text { in } D,  \tag{2}\\ v_{t}-\Delta\left(\left(d_{2}+\alpha_{22} v\right) v\right)=v\left(a_{2}-c_{2} v-\beta k u /(1+\sigma u)\right) & \text { in } D, \\ \frac{\partial u}{\partial \gamma}=\frac{\partial v}{\partial \gamma}=0 & \text { on } S, \\ u(0, x)=u_{0}(x), v(0, x)=v_{0}(x) & \text { in } \Omega,\end{cases}
$$

where $\beta$ and $k$ are positive constants derived from $c_{1}, b_{2}$ and $k$ is the only parameter which is large. For similar studies, here we refer [7]-[15] to the interested readers for more information. A striking difference between (2) and above relevant works is that the diffusion term in (2) is quasilinear. When $\alpha_{i i}=0(i=1,2)$ and $\sigma=0$, the system (2) is reduced to the classical Volterra-Lotka competition model, which has been studied in [9], where Dancer et al. showed that the two competition species spatially segregate as $k$ tends to infinity. Moreover, they proved that, for any $T>0$, there exist subsequences $u^{k_{n}}$ and $v^{k_{n}}$ of the $k$-dependent nonnegative solutions converging weakly in $L^{2}\left(0, T ; H^{1}(\Omega)\right)$ to the positive and negative parts respectively of a limit function $w$ satisfying a scalar equation of the form

$$
\text { (P) } w_{t}-\Delta w=f\left(w^{+}\right)-g\left(w^{-}\right) \quad \text { in }(0, T) \times \Omega \text {, }
$$

where $f(u)=u\left(a_{1}-b_{1} u\right), g(v)=v\left(a_{2}-c_{2} v\right)$, and they also showed that the limit problem (P) turns out to be an explicit Stefan-like type free boundary problem.

Motivated by [9], our main purpose of this paper is to extend most of results of [9] to systems (2) with quasilinear diffusion terms. In addition, we will get the convergence results for the further improvement. Specifically, we have strong convergence in $L^{2}\left(0, T ; H^{1}(\Omega)\right)$.

Note that the study of strong-competition limits in corresponding elliptic of parabolic systems is of interest not only for questions of spatial segregation and coexistence in population dynamics, as here and in [7] [9] [13] [16]-[19] but also is key to the understanding of phase separation in Hartree-Fock type approximations of systems of modelling Bose-Einstein condensates, see [10] [20] [21] [23], and reference therein.

To conclude, we observe that a couple of problems addressed and solved for family of solutions to (2) remains for further study in our general context: firstly, to develop a common regularity theory for the solutions of the system, which is independent of the competition rate $k>0$, as in [16]-[18] [21] [22]; secondly, to study the regularity of the class of limiting profiles, both in terms of the densities and in terms of the emerging free boundary problem, as in [10] [16] [23] [24]; thirdly, the precise description of the singular set in the emerging free boundary problem, as in [25] [26]. These will be object of future investigation.

The outline of this paper is arranged as follows. In Section 2, we give some a prior estimates and some convergence results for solutions of problem (2). Section 3 is focused on the limit problem as $k \rightarrow \infty$. In Section 4, we get the further convergence results in the special case of $\alpha_{11}=\alpha_{22}=0$. Concluding remarks are given in the last section.

## 2. Preliminaries

In order to study the limit case as $k \rightarrow \infty$, we rewrite problem (2) as

$$
\begin{cases}u_{t}^{k}-\Delta\left(\left(d_{1}+\alpha_{11} u^{k}\right) u^{k}\right)=u^{k}\left(a_{1}-b_{1} u^{k}-k v^{k} /\left(1+\sigma u^{k}\right)\right) & \text { in } D,  \tag{3}\\ v_{t}^{k}-\Delta\left(\left(d_{2}+\alpha_{22} v^{k}\right) v^{k}\right)=v^{k}\left(a_{2}-c_{2} v^{k}-\beta k u^{k} /\left(1+\sigma u^{k}\right)\right) & \text { in } D, \\ \frac{\partial u^{k}}{\partial \gamma}=\frac{\partial v^{k}}{\partial \gamma}=0 & \text { on } S, \\ u^{k}(0, x)=u_{0}^{k}(x), v^{k}(0, x)=v_{0}^{k}(x) & \text { in } \Omega .\end{cases}
$$

Throughout this paper, we let $D_{T}=(0, T) \times \Omega$ and suppose the initial functions $u_{0}$ and $v_{0}$ satisfy

$$
\left\{\begin{array}{l}
u_{0}^{k}(x), v_{0}^{k}(x) \in C^{2}(\bar{\Omega}), 0 \leq u_{0}^{k}, v_{0}^{k} \leq M_{0},  \tag{4}\\
u_{0}^{k} \rightharpoonup u_{0}, v_{0}^{k} \rightharpoonup v_{0}, \text { weakly in } L^{2}(\Omega) \text { as } k \rightarrow \infty, \text { and } u_{0} v_{0}=0 \text { a.e. in } \Omega .
\end{array}\right.
$$

We say a pair $\left(u^{k}, v^{k}\right)$ is a solution of (3) in the sense that $\left(u^{k}, v^{k}\right) \in\left[C(\bar{D}) \cap C^{1,2}\left(D_{T}\right)\right]^{2}$ and $\left(u^{k}, v^{k}\right)$ satisfy (3). We now prove some basic facts of solutions for problem (3), which will be used later.

Lemma 1. The solution $\left(u^{k}, v^{k}\right)$ of problem (3) exists and is unique. Moreover, there exist constants $M_{1}$ and $M_{2}$ such that

$$
0 \leq u^{k} \leq M_{1}, 0 \leq v^{k} \leq M_{2} \text { in } \bar{D} .
$$

Proof. The existence and uniqueness of solutions of (3) are followed from the standard parabolic equations theory [4].

By using the maximum principle, the solution is positive for $t>0$ and $x \in \bar{\Omega}$. For the upper bound, it follows from the comparison principle that $u^{k}(t, x) \leq \bar{u}(t)$ for $(t, x) \in \bar{D}$, where

$$
\bar{u}(t):=\frac{a_{1}}{b_{1}} \mathrm{e}^{a_{1} t}\left(\mathrm{e}^{a_{1} t}-1+\frac{a_{1}}{b_{1} M_{0}}\right)^{-1},
$$

which is the solution of the problem

$$
\begin{equation*}
\frac{\mathrm{d} \bar{u}}{\mathrm{~d} t}=\bar{u}\left(a_{1}-b_{1} \bar{u}\right), \quad t>0 ; \bar{u}(0)=M_{0} \tag{5}
\end{equation*}
$$

Thus we have

$$
u^{k}(t, x) \leq M_{1}:=\sup _{t \geq 0} \bar{u}(t)
$$

Similarly, there exists a constant $M_{2}$ such that $v^{k}(t, x) \leq M_{2}$ in $\bar{D}$.
Lemma 2. Let $\left(u^{k}, v^{k}\right)$ be the solution of problem (3), then

$$
\begin{equation*}
\int_{0}^{T} \int_{\Omega} \frac{u^{k} v^{k}}{1+\sigma u^{k}} \mathrm{~d} x \mathrm{~d} t \leq \frac{C_{1}}{k}, \tag{6}
\end{equation*}
$$

where $C_{1}$ is a constant which is independent of $k$.
Proof. Integrating the equation for $u^{k}$ in (3) over $D_{T}$ and using Green's formula yield

$$
\begin{align*}
k \int_{0}^{T} \int_{\Omega} \frac{u^{k} v^{k}}{1+\sigma u^{k}} & =\int_{0}^{T} \int_{\Omega} \Delta\left(\left(d_{1}+\alpha_{11} u^{k}\right) u^{k}\right)+\int_{0}^{T} \int_{\Omega} u^{k}\left(a_{1}-b_{1} u^{k}\right)-\int_{\Omega}\left(u^{k}(T)-u_{0}^{k}\right)  \tag{7}\\
& =\int_{0}^{T} \int_{\Omega} u^{k}\left(a_{1}-b_{1} u^{k}\right)-\int_{\Omega}\left(u^{k}(T)-u_{0}^{k}\right) .
\end{align*}
$$

By Lemma 1 and noting that the right side of (7) is independent of $k$, we get (6).
Lemma 3. Let $\left(u^{k}, v^{k}\right)$ be the solution of problem (3), then

$$
\begin{equation*}
\sup _{t \in[0, T]}\left\|u^{k}\right\|_{L^{2}(\Omega)}^{2}+\int_{0}^{T} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t \leq C_{2}, \sup _{t \in[0, T]}\left\|v^{k}\right\|_{L^{2}(\Omega)}^{2}+\int_{0}^{T} \int_{\Omega}\left|\nabla v^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t \leq C_{2}, \tag{8}
\end{equation*}
$$

where $C_{2}$ is a constant which is independent of $k$.
Proof. Multiplying the equation for $u^{k}$ in (3) by $u^{k}$, integrating over $\Omega$ and applying Green's formula,
we yield

$$
\begin{aligned}
& \frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t} \int_{\Omega}\left(u^{k}\right)^{2} \mathrm{~d} x+d_{1} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x+2 \alpha_{11} \int_{\Omega} u^{k}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x+k \int_{\Omega} \frac{\left(u^{k}\right)^{2} v^{k}}{1+\sigma u^{k}} \mathrm{~d} x \\
& =\int_{\Omega}\left(u^{k}\right)^{2}\left(a_{1}-b_{1} u^{k}\right) \mathrm{d} x
\end{aligned}
$$

which leads to

$$
\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t} \int_{\Omega}\left(u^{k}\right)^{2} \mathrm{~d} x+d_{1} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \leq \int_{\Omega}\left(u^{k}\right)^{2}\left(a_{1}-b_{1} u^{k}\right) \mathrm{d} x
$$

where we have used Lemma 1 . To get the first estimate of (8), we simply integrate the above inequality from 0 to $T$. The second inequality of (8) can be derived similarly.

In order to derive a free boundary problem, we also need to introduce a new function

$$
z^{k}=u^{k}-\frac{v^{k}}{\beta}
$$

which is related with $\left(u^{k}, v^{k}\right)$. Then $z^{k}$ satisfies the scalar problem

$$
\begin{gather*}
z_{t}^{k}-\Delta\left[\left(d_{1}+\alpha_{11} u^{k}\right) u^{k}-\frac{1}{\beta}\left(d_{2}+\alpha_{22} v^{k}\right) v^{k}\right]=u^{k}\left(a_{1}-b_{1} u^{k}\right)-\frac{1}{\beta} v^{k}\left(a_{2}-c_{2} v^{k}\right) \text { in } D_{T}  \tag{9}\\
\frac{\partial z^{k}}{\partial \gamma}=0 \text { on }(0, T) \times \partial \Omega  \tag{10}\\
z^{k}(0, x)=u_{0}^{k}-\frac{1}{\beta} v_{0}^{k} \quad \text { in } \Omega . \tag{11}
\end{gather*}
$$

The following result yields uniform boundedness of $\left\{z_{t}^{k}\right\}$.
Lemma 4. The sequence $\left\{z_{t}^{k}\right\}$ is bounded in $L^{2}\left(0, T ;\left(H^{1}(\Omega)\right)^{\prime}\right)$ uniformly with respect to $k$.
Proof. Multiplying the Equation (9) with $\xi \in L^{2}\left(0, T ; H^{1}(\Omega)\right)$, and integrating over $D_{T}$ using integration by parts, we get

$$
\begin{aligned}
\int_{0}^{T}\left\langle z_{t}^{k}, \xi\right\rangle \mathrm{d} t= & -\iint_{D_{T}}\left(d_{1}+2 \alpha_{11} u^{k}\right) \nabla u^{k} \cdot \nabla \xi+\frac{1}{\beta} \iint_{D_{T}}\left(d_{2}+2 \alpha_{22} v^{k}\right) \nabla v^{k} \cdot \nabla \xi \\
& +\iint_{D_{T}}\left[u^{k}\left(a_{1}-b_{1} u^{k}\right)-\frac{1}{\beta} v^{k}\left(a_{2}-c_{2} v^{k}\right)\right] \xi
\end{aligned}
$$

where $\langle\cdot, \cdot\rangle$ is the duality product between the space $H^{1}(\Omega)$ and $H^{-1}(\Omega)$. By Lemmas 1 and 3, we then have

$$
\left|\int_{0}^{T}\left\langle z_{t}^{k}, \xi\right\rangle \mathrm{d} t\right| \leq M\|\xi\|_{L^{2}\left(0, T ; H_{0}^{1}(\Omega)\right)}
$$

where $M$ is a positive constant which is independent of $k$ or $\xi$. This implies

$$
\left\|z_{t}^{k}\right\|_{L^{2}\left(0, T ; H^{-1}(\Omega)\right)} \leq M .
$$

With the above discussion, below we study some convergence properties. It follows from Lemmas 1 and 3 that $\left\{u^{k}\right\}$ and $\left\{v^{k}\right\}$ are uniformly bounded in $L^{2}\left(0, T ; H^{1}(\Omega)\right) \cap L^{\infty}\left(0, T ; L^{2}(\Omega)\right)$. Hence, there exist subsequences of $\left\{u^{k}\right\}$ and $\left\{v^{k}\right\}$ (still denoted by $u^{k}$ and $v^{k}$ ), and two functions $u, v \in L^{2}\left(0, T ; H^{1}(\Omega)\right) \cap L^{\infty}\left(0, T ; L^{2}(\Omega)\right)$ such that

$$
\begin{equation*}
u^{k} \rightharpoonup u, v^{k} \rightharpoonup v \text { weakly in } L^{2}\left(0, T ; H^{1}(\Omega)\right) \text { and strongly in } L^{2}\left(0, T ; L^{2}(\Omega)\right) \tag{12}
\end{equation*}
$$

and

$$
\begin{equation*}
z^{k}=u^{k}-\frac{1}{\beta} v^{k} \rightarrow z \text { in } L^{2}\left(0, T ; L^{2}(\Omega)\right) \text { and a.e. in } D_{T} \tag{13}
\end{equation*}
$$

as $k \rightarrow \infty$. Furthermore, by Lemma 2, we have
Lemma 5. $u v=0$ a.e. in $D_{T}$.
Below we manage to build the relations between $u, v$ and $w$.
Lemma 6. The subsequences $u^{k}$ and $v^{k}$ are such that

$$
\begin{equation*}
u^{k} \rightarrow z^{+} \text {and } v^{k} \rightarrow \beta z^{-} \text {in } L^{1}\left(D_{T}\right) \text { and a.e. in } D_{T}, \tag{14}
\end{equation*}
$$

as $k \rightarrow \infty$, where $z^{+}:=\max (0, z)$ and $z^{-}:=\max (0,-z)$. Moreover,

$$
\begin{equation*}
u=z^{+} \text {and } \alpha_{1} v=\beta z^{-} \text {and hence } z=u-\frac{1}{\beta} v . \tag{15}
\end{equation*}
$$

Proof. Let $(t, x) \in D_{T}$ be such that

$$
z^{k}(t, x)=u^{k}(t, x)-\frac{1}{\beta} v^{k}(t, x) \rightarrow z(t, x) \text { and }\left(u^{k} v^{k}\right)(t, x) \rightarrow 0 \text { as } k \rightarrow \infty
$$

In order to prove the theorem, we need to divide our proof into three cases:

$$
\text { (a) } z(t, x)>0,(b) z(t, x)<0,(c) z(t, x)=0 \text {. }
$$

In case $(a) z(t, x)>0$, according to the definition of limit, there exists a positive constant $N_{1}$ such that

$$
\left|z^{k}(t, x)-z(t, x)\right| \leq \frac{z(t, x)}{2}, \forall k \geq N_{1},
$$

then we have

$$
u^{k}(t, x) \geq \frac{z(t, x)}{2}>0, \forall k \geq N_{1}
$$

Due to Lemma 2, above inequality implies that

$$
v^{k}(t, x) \rightarrow 0 \text { and } u^{k}(t, x) \rightarrow z(t, x)=z^{+}(t, x) \text { as } k \rightarrow \infty .
$$

Next we consider case $(b) z(t, x)<0$. We proceed as in the proof of case (a), then there exists a positive constant $N_{2}$ such that

$$
v^{k}(t, x) \geq-\frac{z(t, x)}{2}>0, \forall k \geq N_{2} .
$$

Recalling Lemma 2, we claim that

$$
u^{k}(t, x) \rightarrow 0 \text { and } v^{k}(t, x) \rightarrow-\beta z(t, x)=\beta z^{-}(t, x) \text { as } k \rightarrow \infty
$$

For the last case (c) $z(t, x)=0$. We claim that

$$
u^{k}(t, x) \rightarrow 0 \text { and } v^{k}(t, x) \rightarrow 0 \text { as } k \rightarrow \infty .
$$

Otherwise, if there is a subsequence of $u^{k}$, which we still denote by $u^{k}$, such that $u^{k}(t, x) \rightarrow \delta>0$, it follows that $v^{k}(t, x) \rightarrow 0$, consequently $u^{k}(t, x)-\frac{1}{\beta} v^{k}(t, x) \rightarrow \delta>0$, which contradicts the fact $z(t, x)=0$. Similarly, it is impossible to have that $v^{k}(t, x) \rightarrow \theta>0$.

From the boundedness of $u^{k}$ and $v^{k}$, it is easy to achieve convergence in $L^{1}\left(0, T ; L^{2}(\Omega)\right)$. To the end, we get (15) from (14).

## 3. The Limit Problem as $k \rightarrow \infty$

Lemma 6 illustrates that $u=z^{+}, v=\beta z^{-}$and $z^{k}(t, x)=u^{k}-\frac{1}{\beta} v^{k} \rightarrow z(t, x)=u-\frac{1}{\beta} v$ weakly in $L^{2}\left(0, T ; H^{1}(\Omega)\right)$ as $k \rightarrow \infty$. We set

$$
\mathcal{D}(s):= \begin{cases}d_{1}+2 \alpha_{11} s & \text { if } s \geq 0  \tag{16}\\ d_{2}-2 \beta \alpha_{22} s & \text { if } s<0\end{cases}
$$

and

$$
f(s):= \begin{cases}\left(a_{1}-b_{1} s\right) s & \text { if } s \geq 0  \tag{17}\\ \left(a_{2}+\beta c_{2} s\right) s & \text { if } s<0\end{cases}
$$

In this section, we mainly consider the scalar equation

$$
\begin{cases}z_{t}-\operatorname{div}(\mathcal{D}(z) \nabla z)=f(z) & \text { in } D  \tag{18}\\ \frac{\partial z}{\partial \gamma}=0 & \text { on } S \\ z(0, x)=u_{0}(x)-\frac{1}{\beta} v_{0}(x):=z_{0}(x) & \text { for } x \in \Omega\end{cases}
$$

First, we show that problem (18) has a weak solution, which are defined as follows:
Definition 3.1 We say that a function $z \in L^{\infty}(D) \cap L^{2}\left(0, T ; H^{1}(\Omega)\right) \cap C\left([0,+\infty) ; L^{2}(\Omega)\right)$ is a weak solution of (16) if it satisfies

$$
\begin{equation*}
\int_{0}^{T} \int_{\Omega}\left[z \varphi_{t}-\mathcal{D}(z) \nabla z \cdot \nabla \varphi+f(z) \varphi\right]=-\int_{\Omega} z_{0} \varphi(0) \tag{19}
\end{equation*}
$$

for all $T>0$ and any test function $\varphi \in C^{\infty}\left(D_{T}\right)$ with $\varphi(T)=0$.
Theorem 1. The function defined by (15) is the unique weak solution of problem (18). Moreover,
$z \in C^{\frac{1+\mu}{2}, 1+\mu}(\bar{D})$ for some $\mu \in(0,1)$.
Proof. From Lemmas 1 and 3, we easily have $z \in L^{\infty}(D) \cap L^{2}\left(0, T ; H^{1}(\Omega)\right)$, and Lemma 4 yields $z_{t} \in L^{2}\left(0, T ; H^{-1}(\Omega)\right) . \quad z \in C\left([0, T] ; L^{2}(\Omega)\right)$ is derived from by a standard regularity result (see for example [27], Theorem 3, p.287).

Multiplying (9) by a test function $\varphi \in C^{\infty}\left(D_{T}\right)$ with $\varphi(T)=0$, and using integration by parts, we deduce

$$
\begin{aligned}
& -\int_{0}^{T} \int_{\Omega}\left(u^{k}-\frac{1}{\beta} v^{k}\right) \varphi_{t}+\int_{0}^{T} \int_{\Omega}\left[\left(d_{1}+2 \alpha_{11} u^{k}\right) \nabla u^{k} \cdot \nabla \varphi-\frac{1}{\beta}\left(d_{2}+2 \alpha_{22} v^{k}\right) \nabla v^{k} \cdot \nabla \varphi\right] \\
& =\int_{0}^{T} \int_{\Omega}\left[u^{k}\left(a_{1}-b_{1} u^{k}\right)-\frac{1}{\beta} v^{k}\left(a_{2}-c_{2} v^{k}\right)\right] \varphi+\int_{\Omega}\left(u_{0}^{k}-\frac{1}{\beta} v_{0}^{k}\right) \varphi(0) .
\end{aligned}
$$

Let $k \rightarrow \infty$ along the sequence for which (12) holds. By the dominated convergence theorem and Lemma 1, we have

$$
\begin{align*}
& -\int_{0}^{T} \int_{\Omega}\left(u-\frac{1}{\beta} v\right) \varphi_{t}+\int_{0}^{T} \int_{\Omega}\left[\left(d_{1}+2 \alpha_{11} u\right) \nabla u \cdot \nabla \varphi-\frac{1}{\beta}\left(d_{2}+2 \alpha_{22} v\right) \nabla v \cdot \nabla \varphi\right] \\
& =\int_{0}^{T} \int_{\Omega}\left[u\left(a_{1}-b_{1} u\right)-\frac{1}{\beta} v\left(a_{2}-c_{2} v\right)\right] \varphi+\int_{\Omega}\left(u_{0}-\frac{1}{\beta} v_{0}\right) \varphi(0) \tag{20}
\end{align*}
$$

Note that (16) and (17) yield

$$
\left(d_{1}+2 \alpha_{11} u\right) \nabla u-\frac{1}{\beta}\left(d_{2}+2 \alpha_{22} v\right) \nabla v=\mathcal{D}(z) \nabla z
$$

and

$$
u\left(a_{1}-b_{1} u\right)-\frac{1}{\beta} v\left(a_{2}-c_{2} v\right)=f(z)
$$

With (20), we then have that $z$ satisfies

$$
\int_{0}^{T} \int_{\Omega}\left[z \varphi_{t}-\mathcal{D}(z) \nabla z \cdot \nabla \varphi+f(z) \varphi\right]=-\int_{\Omega} z_{0} \varphi(0)
$$

for all $T>0$ and any test function $\varphi \in C^{\infty}\left(D_{T}\right)$ with $\varphi(T)=0$. Namely, z satisfies the differential equation in (18) as well as the homogeneous Neumann boundary condition in the sense of distributions, and the initial condition

$$
z(0, x)=u_{0}(x)-\frac{1}{\beta} v_{0}(x) \text { for } x \in \Omega .
$$

This follows easily that $z$ is the weak solution of problem (18).
It is clear from [2] that the weak solution of problem (18) is unique. Last, for the regularity of $z$, we refer to Theorems 1.1 and 1.3 in [28].

According to the above discussion, there exists a family of closed hypersurfaces $\mathcal{B}:=\{\bigcup \mathcal{B}(t): \mathcal{B}(t) \subset \subset \Omega, t \in[0, T]\}$, which separates the two strongly competing species. That is

$$
z(t)>0 \text { inside } \mathcal{B}(t) \text {, say in } \mathcal{B}_{t}^{i}
$$

and

$$
z(t)<0 \text { outside } \mathcal{B}(t) \text {, say in } \mathcal{B}_{t}^{e} .
$$

We denote

$$
\Omega_{i}:=\bigcup\left\{\mathcal{B}_{t}^{i}, t \in(0, T]\right\} \text { and } \Omega_{e}:=\bigcup\left\{\mathcal{B}_{t}^{e}, t \in(0, T]\right\} .
$$

Finally, as in [9], we rewrite a strong form of the limit problem (18), where the equations can be described a classical two-phase Stefan-like free boundary problem.

Theorem 2. Let $z$ be a weak solution of limit problem (18), if $\mathcal{B}$ is smooth enough, and if the functions

$$
u=z^{+} \text {and } v=\beta z^{-}
$$

are smooth up to $\mathcal{B}(t)$, then $u$ and $v$ satisfy

$$
\begin{cases}u_{t}-\Delta\left(\left(d_{1}+\alpha_{11} u\right) u\right)=u\left(a_{1}-b_{1} u\right) & \text { in } \Omega_{i},  \tag{21}\\ v_{t}-\Delta\left(\left(d_{2}+\alpha_{22} v\right) v\right)=v\left(a_{2}-c_{2} v\right) & \text { in } \Omega_{e}, \\ u=v=0 & \text { on } \mathcal{B}, \\ d_{1} \frac{\partial u}{\partial \gamma}=-\frac{d_{2}}{\beta} \frac{\partial v}{\partial \gamma} & \text { on } \mathcal{B}, \\ \frac{\partial u}{\partial \gamma}=\frac{\partial v}{\partial \gamma}=0 & \text { on } S, \\ u(0, x)=u_{0}(x), v(0, x)=v_{0}(x) & \text { in } \Omega,\end{cases}
$$

where we suppose that $u_{0} v_{0}=0$ a.e. in $\Omega$.

## 4. Further Convergence Results

In this section, we prove that the subsequences $\left\{u^{k}\right\}$ and $\left\{v^{k}\right\}$ of $k$-dependent non-negative solutions to (3) converge strongly in $L^{2}\left(0, T ; H^{1}(\Omega)\right)$. For the convenience of presentation, we consider the special case of $\alpha_{11}=\alpha_{22}=0$.

Theorem 3. If $\alpha_{11}=\alpha_{22}=0$ and $u_{0} v_{0}=0$ a.e. in $\Omega$, then up to a subsequence,

$$
\begin{equation*}
\nabla u^{k} \rightarrow \nabla u, \nabla v^{k} \rightarrow \nabla v \text { in } L^{2}\left(0, T ; L^{2}(\Omega)\right) . \tag{22}
\end{equation*}
$$

and hence $u^{k} \rightarrow u$ in $L^{2}\left(0, T ; H^{1}(\Omega)\right), v^{k} \rightarrow v$ in $L^{2}\left(0, T ; H^{1}(\Omega)\right), z^{k} \rightarrow z$ in $L^{2}\left(0, T ; H^{1}(\Omega)\right)$.
Proof. By arguments as in the proof of Theorem 1, we first obtain

$$
z \in C\left([0, T] ; L^{2}(\Omega)\right) \cap H^{1}\left(0, T ; L^{2}(\Omega)\right)
$$

Thus

$$
u=z^{+}=\frac{|z|+z}{2} \in C\left([0, T] ; L^{2}(\Omega)\right)
$$

This implies

$$
u_{t}=\left(z^{+}\right)_{t} \in L^{2}\left(0, T ; L^{2}(\Omega)\right)
$$

by Lemma 7.6 in [29]. Hence $u \in C\left([0, T] ; L^{2}(\Omega)\right) \cap H^{1}\left(0, T ; L^{2}(\Omega)\right)$. Also by Lemma 7.7 in [29] and Lemma 5, we get

$$
\begin{equation*}
\nabla u \cdot \nabla v=0, v_{t} u=u_{t} v=0 \text { a.e. in } D_{T} . \tag{23}
\end{equation*}
$$

Now, multiplying the second equation in (3) by the limit $u$ and integrating it over $(0, \tau) \times \Omega, \tau \in(0, T)$, we have

$$
\int_{0}^{\tau} \int_{\Omega}\left[v_{t}^{k} u-d_{2} u \Delta v^{k}-u v^{k}\left(a_{2}-c_{2} v^{k}-\beta k u^{k} /\left(1+\sigma u^{k}\right)\right)\right] \mathrm{d} x \mathrm{~d} t=0
$$

Integrating by parts gives

$$
\begin{align*}
& \int_{\Omega} v^{k}(\tau) u(\tau) \mathrm{d} x-\int_{\Omega} v_{0}^{k} u_{0} \mathrm{~d} x-\int_{0}^{\tau} \int_{\Omega} v^{k} u_{t} \mathrm{~d} x \mathrm{~d} t+\int_{0}^{\tau} \int_{\Omega} d_{2} \nabla v^{k} \cdot \nabla u \mathrm{~d} x \mathrm{~d} t \\
& =\int_{0}^{\tau} \int_{\Omega} u v^{k}\left(a_{2}-c_{2} v^{k}\right) \mathrm{d} x \mathrm{~d} t-\beta k \int_{0}^{\tau} \int_{\Omega} \frac{u^{k} v^{k} u}{1+\sigma u^{k}} \mathrm{~d} x \mathrm{~d} t \tag{24}
\end{align*}
$$

Integrating (24) with respect to $\tau$ over $(0, T)$ gives

$$
\begin{aligned}
& \int_{0}^{T} \int_{\Omega}\left[v^{k}(\tau) u(\tau)-v_{0}^{k} u_{0}\right] \mathrm{d} x \mathrm{~d} \tau-\int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} v^{k} u_{t} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau+d_{2} \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} \nabla v^{k} \cdot \nabla u \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \\
& =\int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} u v^{k}\left(a_{2}-c_{2} v^{k}\right) \mathrm{d} x \mathrm{~d} t \mathrm{~d} \tau-\beta k \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} \frac{u^{k} v^{k} u}{1+\sigma u^{k}} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau
\end{aligned}
$$

With (4), (12) and Lemma 5, as $k \rightarrow \infty$, we obtain

$$
\int_{0}^{T} \int_{\Omega} v^{k}(\tau) u(\tau) \mathrm{d} x \mathrm{~d} \tau \rightarrow \int_{0}^{T} \int_{\Omega} v(\tau) u(\tau) \mathrm{d} x \mathrm{~d} \tau=0
$$

and

$$
\int_{0}^{T} \int_{\Omega} v_{0}^{k} u_{0} \mathrm{~d} x \mathrm{~d} \tau \rightarrow \int_{0}^{T} \int_{\Omega} v_{0} u_{0} \mathrm{~d} x \mathrm{~d} \tau=0
$$

Since $u_{t}$ is bounded in $L^{2}\left(0, T ; L^{2}(\Omega)\right)$ and $u_{t} v=0$ a.e. in $(0, T) \times \Omega$, we may apply Fubini theorem to obtain

$$
\begin{align*}
& \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} v^{k} u_{t} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau=\int_{0}^{T}(T-t) \int_{\Omega} v^{k} u_{t} \mathrm{~d} x \mathrm{~d} t \leq T\left|\int_{0}^{T} \int_{\Omega} v^{k} u_{t} \mathrm{~d} x \mathrm{~d} t\right|  \tag{25}\\
& \rightarrow T\left|\int_{0}^{T} \int_{\Omega} v u_{t} \mathrm{~d} x \mathrm{~d} t\right|=0
\end{align*}
$$

as $k \rightarrow \infty$. Similarly, by (12), (23) and Lemma 5, we have

$$
\int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} \nabla v^{k} \cdot \nabla u \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \rightarrow 0, \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} u v^{k}\left(a_{2}-c_{2} v^{k}\right) \mathrm{d} x \mathrm{~d} t \mathrm{~d} \tau \rightarrow 0
$$

Therefore, (24) yields

$$
\beta k \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} \frac{u^{k} v^{k} u}{1+\sigma u^{k}} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \rightarrow 0 \quad \text { as } k \rightarrow \infty
$$

This implies that

$$
\begin{equation*}
k \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} \frac{u^{k} v^{k} u}{1+\sigma u^{k}} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \rightarrow 0 \text { as } k \rightarrow \infty \tag{26}
\end{equation*}
$$

Next, multiplying the first equation in (3) by the limit $u$ and integration it over $(0, \tau) \times \Omega$, we have

$$
\begin{align*}
& \int_{\Omega}\left[u^{k}(\tau) u(\tau)-u_{0}^{k} u_{0}\right] \mathrm{d} x \mathrm{~d} t-\int_{0}^{\tau} \int_{\Omega} u^{k} u_{t} \mathrm{~d} x \mathrm{~d} t+d_{1} \int_{0}^{\tau} \int_{\Omega} \nabla u^{k} \cdot \nabla u \mathrm{~d} x \mathrm{~d} t \\
& =\int_{0}^{\tau} \int_{\Omega} u u^{k}\left(a_{1}-b_{1} u^{k}\right) \mathrm{d} x \mathrm{~d} t-k \int_{0}^{\tau} \int_{\Omega} \frac{u^{k} v^{k} u}{1+\sigma u^{k}} \mathrm{~d} x \mathrm{~d} t . \tag{27}
\end{align*}
$$

Integrating above equation in $\tau$ and passing to the limit as $k \rightarrow \infty$ yield

$$
\begin{align*}
& d_{1} \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \\
& =\int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} u^{2}\left(a_{1}-b_{1} u\right) \mathrm{d} x \mathrm{~d} t \mathrm{~d} \tau-\frac{1}{2} \int_{0}^{T} \int_{\Omega}\left\{u^{2}(\tau)-u_{0}^{2}\right\} \mathrm{d} x \mathrm{~d} \tau \tag{28}
\end{align*}
$$

by using (4), (12) and (26).
Finally, multiplying the first equation in (1) again by $u^{k}$ and integrating it over $(0, \tau) \times \Omega$, we deduce

$$
\begin{aligned}
& \frac{1}{2} \int_{0}^{\tau} \int_{\Omega} \frac{\mathrm{d}}{\mathrm{~d} t}\left(u^{k}\right)^{2} \mathrm{~d} x \mathrm{~d} t+d_{1} \int_{0}^{\tau} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t \\
& =\int_{0}^{\tau} \int_{\Omega}\left(u^{k}\right)^{2}\left(a_{1}-b_{1} u^{k}\right) \mathrm{d} x \mathrm{~d} t-k \int_{0}^{\tau} \int_{\Omega}\left(u^{k}\right)^{2} v^{k} \mathrm{~d} x \mathrm{~d} t
\end{aligned}
$$

This concludes that

$$
\begin{align*}
& d_{1} \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \\
& \leq \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega}\left(u^{k}\right)^{2}\left(a_{1}-b_{1} u^{k}\right) \mathrm{d} x \mathrm{~d} t \mathrm{~d} \tau-\frac{1}{2} \int_{0}^{T} \int_{\Omega}\left\{\left(u^{k}\right)^{2}(\tau)-u_{0}^{2}\right\} \mathrm{d} x \mathrm{~d} \tau \\
& \rightarrow \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega} u^{2}\left(a_{1}-b_{1} u\right) \mathrm{d} x \mathrm{~d} t \mathrm{~d} \tau-\frac{1}{2} \int_{0}^{T} \int_{\Omega}\left\{u^{2}(\tau)-u_{0}^{2}\right\} \mathrm{d} x \mathrm{~d} \tau  \tag{29}\\
& =d_{1} \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x \mathrm{dtd} \tau
\end{align*}
$$

by (28). It follows from (12) and weak lower semi-continuity that

$$
\int_{0}^{\tau} \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x \mathrm{~d} t \leq \liminf _{k \rightarrow \infty} \int_{0}^{\tau} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t .
$$

By Fatou's lemma, we have

$$
\int_{0}^{T} \int_{0}^{\tau} \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau \leq \liminf _{k \rightarrow \infty} \int_{0}^{T} \int_{0}^{\tau} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t \mathrm{~d} \tau
$$

which together with (29) implies that there exists a subsequence $\left\{u^{k}\right\}$, which we denote again by $\left\{u^{k}\right\}$ such that for a.e. $\quad \tau \in(0, T)$

$$
\lim _{k \rightarrow \infty} \int_{0}^{\tau} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t=\int_{0}^{\tau} \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x \mathrm{~d} t .
$$

In other words,

$$
\lim _{k \rightarrow \infty} \int_{0}^{T} \int_{\Omega}\left|\nabla u^{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t=\int_{0}^{T} \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x \mathrm{~d} t .
$$

Hence $\nabla u^{k} \rightarrow \nabla u$ in $L^{2}\left(0, T ; L^{2}(\Omega)\right)$. Similarly, we claim that $\nabla v^{k} \rightarrow \nabla v$ in $L^{2}\left(0, T ; L^{2}(\Omega)\right)$. The rest of the conclusions in this theorem follow consequently.

## 5. Concluding Remarks

The study of spatial behavior of the interacting species has been attracting much attention in population ecology,
in particular, in the case when the interactions are large and of competitive type. Many different models based on partial differential equations can be successfully employed to investigate the phenomenon of coexistence and exclusions of competing species. In this paper, we have attempted to study a class of quasilinear parabolic system (3) describing a Holling-Tanner's competitive interaction of two species. We prove that if inter-specific competition rates tend to infinity, then spatial segregation of the densities $u, v$ and a scalar limit problem (21) are given. In particular, we have obtained the strong convergence results in $L^{2}\left(0, T ; H^{1}(\Omega)\right)$ in the special case of $\alpha_{11}=\alpha_{22}=0$. Ecologically, our results show that competition leads to segregation.

Finally, we want to mention that there are still many interesting questions to do for this kind of problem. First of all, noting that the diffusion term of the first equation in (2) can be written as $\operatorname{div}\left\{\left(d_{1}+2 \alpha_{11} u\right) \nabla u\right\}$, the term $d_{1}+2 \alpha_{11} u$ describes the "self-diffusion". Naturally to ask whether our results can be extended to parabolic systems with "cross-diffusion"? Moreover, as mentioned in the introduction, we have seen that limit profiles of solutions to (2) are segregated configurations, it is then natural to define the free boundary as the nodal set $\Gamma:=\{(x, t): u=v=0\}$. The regularity of the nodal set remains a challenge, and it will be the object of a forthcoming paper.

## Acknowledgements

We thank the Editor and the referee for their comments. This work is partially supported by PRC grant NSFC 11501494 and NSF of the Higher Education Institutions of Jiangsu Province (12KJD110008). This support is greatly appreciated.

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