Published Online August 2014 in SciRes. http://www.scirp.org/journal/am http://dx.doi.org/10.4236/am.2014.515229



Construction of Regular Heptagon by Rhombic Bicompasses and Ruler

A. Wünsche

Humboldt-Universität Berlin, Institut für Physik, Berlin, Germany Email: alfred.wuensche@physik.hu-berlin.de

Received 26 May 2014; revised 2 July 2014; accepted 14 July 2014

Copyright © 2014 by author and Scientific Research Publishing Inc.
This work is licensed under the Creative Commons Attribution International License (CC BY).
http://creativecommons.org/licenses/by/4.0/



Open Access

Abstract

We discuss a new possible construction of the regular heptagon by rhombic bicompasses explained in the text as a new geometric mean of constructions in the spirit of classical constructions in connection with an unmarked ruler (straightedge). It avoids the disadvantages of the neusis construction which requires the trisection of an angle and which is not possible in classical way by compasses and ruler. The rhombic bicompasses allow to draw at once two circles around two fixed points in such correlated way that the position of one of the rotating points (arms) on one circle determines the position of the points on the other circle. This means that the positions of all points (arms) on both circles are determined in unique way.

Keywords

Plane Geometry, Algebra, Geometric Constructions, Heptagon, Cyclotomic Equations, Neusis

1. Introduction

It is well known that the regular heptagon (n = 7) is the first in the series of regular n-polygons which cannot be constructed by compasses and ruler (e.g., [1]-[8]). The neusis construction [3] [8] is, in principle, an exact construction but it requires the trisection of an angle which is not possible by compasses and ruler alone. This makes it necessary to fit a distance markable on a ruler (straightedge) between a line and a circle in such a way that the ruler finally intersects a given point on the circle and a new point on the line which last marks the vertex of the trisected angle. We describe in this paper a new exact construction by a mean which we call rhombic bicompasses in connection with a ruler. The rhombic bicompasses can be fixed to arbitrary two points and the arms possess then one degree of freedom which allow them to describe two circles in correlated way. The position of a point on one circle determines then at once the positions of all other movable points on the two

circles. It is important that in case of the regular heptagon, the relative coordinates of the fixed points are geometrically constructible since they are given only by rational numbers together with a square root of a natural number. We explain this in Section 3 and give the formulae for the coordinates of the correlated movable points of the bicompasses in dependence on the two fixed points in an **Appendix A**.

2. Circle Division and Factorizations of Cyclotomic Equation for Regular Heptagon

The regular heptagon with significant points for our construction method which we describe in the following is shown in **Figure 1**.

The points
$$z_k = \exp\left(ik\frac{2\pi}{n}\right) = z_1^k = z_{-k}^*, \left(z_k^n = z_n = z_0 = 1\right)$$
 which solve the cyclotomic equation $z^n - 1 = 0$

and thus the circle division problem (we set radius r=1) determine the corners of the regular heptagon in case of n=7. The corresponding palindromic polynomial of 6th degree which determines the primitive roots $\exp\left(ik\frac{2\pi}{7}\right)$, $(k=1,\dots,6)$ is represented in the usual approach [1] in the following way [1] [6] [7]

$$0 = z^{7} - 1 = (z - 1)(z^{6} + z^{5} + z^{4} + z^{3} + z^{2} + z + 1) = (z - 1)z^{3} \left\{ (z + z^{-1})^{3} + (z + z^{-1})^{2} - 2(z + z^{-1}) - 1 \right\}. \tag{1}$$

The solution of the obtained cubic equation for $z + z^{-1} = z + z^*$ by the formulae of Cardano provides the Cosines of the angles to the points $z_k = 1, \dots, 6$ according to

$$(k=1,6\leftrightarrow l=0, k=2,5\leftrightarrow l=1, k=3, 4\leftrightarrow l=2)$$

$$\cos\left(k\frac{2\pi}{7}\right) = \frac{z_k + z_k^*}{2} = \frac{1}{6}\left(-1 + \varepsilon^l \sqrt[3]{\frac{7}{2}\left(1 + i3\sqrt{3}\right)} + \varepsilon^{*l} \sqrt[3]{\frac{7}{2}\left(1 - i3\sqrt{3}\right)}\right),\tag{2}$$

where ε denotes the cubic roots of 1 as follows

$$\varepsilon = \exp\left(i\frac{2\pi}{3}\right) = \frac{-1 + i\sqrt{3}}{2}, \quad \varepsilon^2 = \exp\left(i\frac{4\pi}{3}\right) = \frac{-1 - i\sqrt{3}}{2} = \varepsilon^{-1} = \varepsilon^*, \tag{3}$$

Regular heptagon with significant points

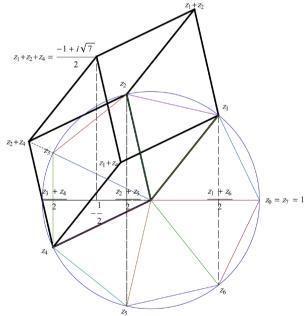


Figure 1. Regular heptagon with axes projection of corners and summation of roots z_1, z_2, z_4 in complex z-plane.

and where the two cubic roots in (2) are to take as complex conjugate ones (which ones can change the assignment to k on left-hand side). An analogous approach of separation of an equation for $z+z^{-1}$ of degree m is possible for arbitrary odd n=2m+1 and in modified form for arbitrary even n=2m+2.

Another approach with factorization of the polynomial of 6-th degree of the cyclotomic equation for n = 7 into two cubic polynomials although not in the field \mathbb{Q} of rational coefficients but in an extension by complex number $i\sqrt{7}$ is the following

$$0 = (z-1)\left(z^{3} + \frac{1-i\sqrt{7}}{2}z^{2} - \frac{1+i\sqrt{7}}{2}z - 1\right)\left(z^{3} + \frac{1+i\sqrt{7}}{2}z^{2} - \frac{1-i\sqrt{7}}{2}z - 1\right)$$

$$= (z-z_{0})\left((z-z_{1})(z-z_{2})(z-z_{4})\right)\left((z-z_{6})(z-z_{5})(z-z_{3})\right).$$
(4)

It comprises in one cubic factor the 3 cubic roots (z_1, z_2, z_4) and in the other cubic factor the 3 complex conjugate roots $z_1^* = z_6, z_2^* = z_5, z_4^* = z_3$ (see **Figure 1**). One can easily check the factorization (4) but one can derive the possibilities also in a systematic way. In the systematic way for arbitrary prime number n (e.g., [5] [6] [9]) one takes an arbitrary primitive root z_k , $(k = 1, 2, \dots, n)$ and forms then sequences of powers

 $(z_k)^{g^l}$, $(l=0,1,\cdots,m;\ g=1,2,\cdots)$ of z_k up to the moment when due to $z_{k+n}=z_k$ these sequences return to the chosen initial element z_k as follows

$$(z_k)^{g^0} = z_k, (z_k)^{g^1} = z_{gk}, (z_k)^{g^2} = z_{\sigma^2 k}, (z_k)^{g^3} = z_{\sigma^3 k}, \dots, (z_k)^{g^m} = z_{\sigma^m k} = z_k, \quad (\text{modulo } n).$$
 (5)

This happens with necessity latest after n-1 steps since the root $z_0=z_n=1$ forms its own sequence with only one element and due to the construction which guarantees that all roots of two sequences are different from each other or one has the same sequence in a different cyclic order of the roots. In our case of three-root cycles $(z_1,z_2,z_4,(z_8\equiv z_1 \bmod 7))$ and $(z_1^*,z_2^*,z_4^*)=(z_6,z_{12}\equiv z_5,z_{24}\equiv z_{10}\equiv z_3 \pmod 7)$ one finds from $z_1z_2z_4=z_1^7=z_7=z_0=1$ that the last coefficient in the factorized polynomials of degree 3 is equal to -1 and from $z_1+z_2+z_3+z_1^*+z_2^*+z_3^*=-z_0=-1$ and $z_1z_2+z_1z_4+z_2z_4=z_3+z_5+z_6=z_4^*+z_2^*+z_1^*$ that the first and se-

cond coefficient are negative complex conjugate with real part equal to $-\frac{1}{2}$ and it remains to determine only an imaginary part in the first and second coefficient that is easily to find from the product of the factors.

A further difference between the type of polynomial in Equation (1) and the type of polynomials in the factorization in (4) is, as already mentioned, that the coefficients of the corresponding polynomials are rational (field \mathbb{Q}) in first case and complex irrational in second case (more specially of the form $a+b\sqrt{n}$ with complex rational (a,b) and integer n). However, this is not important for the considered solutions in radicals by the formula of Cardano which in both cases belong to the field \mathbb{C} and the involved cubic roots are complex numbers belonging to the "Casus irreduciblis" (e.g., [9]). The solution of the two cubic equations (4) by the formulae of Cardano provides for k=1,2,4 (with correspondences

$$k = 1 \leftrightarrow l = 0, k = 2 \leftrightarrow l = 1, k = 4 \leftrightarrow l = 2$$
)

$$z_{k} = \frac{1}{6} \left[-1 + i\sqrt{7} + \varepsilon^{l} \sqrt[3]{4\left(14 + 3\sqrt{21} - i\sqrt{7}\right)} + \varepsilon^{2l} \frac{i4\sqrt{7}}{\sqrt[3]{4\left(14 + 3\sqrt{21} - i\sqrt{7}\right)}} \right],\tag{6}$$

and for k = 3,5,6 (with correspondences $k = 3 \leftrightarrow l = 1, k = 5 \leftrightarrow l = 2, k = 6 \leftrightarrow l = 0$)

$$z_{k} = \frac{1}{6} \left[-1 - i\sqrt{7} + \varepsilon^{2l} \sqrt[3]{4\left(14 - 3\sqrt{21} + i\sqrt{7}\right)} - \varepsilon^{l} \frac{i4\sqrt{7}}{\sqrt[3]{4\left(14 - 3\sqrt{21} + i\sqrt{7}\right)}} \right],\tag{7}$$

where again ε^{l} denotes the cubic roots of 1 according to (3). For the cubic roots in each of the formulae (6) and (7) one has to take the same (but arbitrary) of the 3 possible values that is the reason that we do not

¹In addition, we note that when trying to solve the equation $z^7 - 1 = 0$ by "Mathematica 6", it provides the roots only in the form equivalent to $z_k = \exp\left(ik\frac{2\pi}{7}\right), (k=0,1,\dots,6)$.

transform them into the numerator¹.

Other factorizations than (4) involving 3 of the roots, for example $(z-z_1)(z-z_2)(z-z_3)$ and $(z-z_4)(z-z_5)(z-z_6)$, do not lead to cubic polynomials with coefficients containing only square roots of the form $a+b\sqrt{n}$ with (a,b) from $\mathbb Q$ but contain higher-order roots for which last the sum of the 3 roots is then not constructible by compasses and ruler.

3. Rhombic Bicompasses and Geometrical Construction of the Regular Heptagon

We describe now a new device in the spirit of classical geometrical constructions by compasses and ruler and suggest to call it rhombic bicompasses. It is schematically shown in **Figure 2** on the left-hand side. It consists of 12 arms of equal length 1 (in some measure) connected in 8 corners and rotatable around these corners. As a whole it looks like the parallel projection of a spatial cuboid but is meant as a planar device. If fixed in one of the corner points, say O, it possesses two degrees of freedom which allow complicated motions. If fixed in two opposite corner points which we call O and P its motion is restricted by one degree of freedom to two circles and the motion of one of the free corner points called A, B, C, D, E, F forces to move the other free corner points in correlated way and the whole motion goes along two circles with radius equal to 1 around the two fixed points O and P due to equal lengths of the arms. In a minimum variant of the rhombic bicompasses which is sufficient for our purposes we may omit 7 arms, for example,

OD, *PC*, *PF*, *AF*, *CD*, *CE*, *DF* and get the device shown on the right-hand side in **Figure 2**. All this means that the rhombic bicompasses are more than only connected double compasses².

As coordinate origin we choose the point O which possesses then the plane coordinates (0,0). The coordinates of the second fixed point P we denote by (p_1, p_2) . We parameterized the rotation of the point A of the rhombic bicompasses by the rotation angle α and calculated the motion of all other points in dependence on this parametrization. The results of these calculations are presented in **Appendix A**. For the special purpose of the construction of the regular heptagon the second fixed point P of the rhombic

bicompasses has to be specialized as the point with Cartesian coordinates $(p_1, p_2) = \left(-\frac{1}{2}, \frac{\sqrt{7}}{2}\right)$ with the

Maximum rhombic bicompasses with 12 arms

Minimum rhombic bicompasses with 5 arms

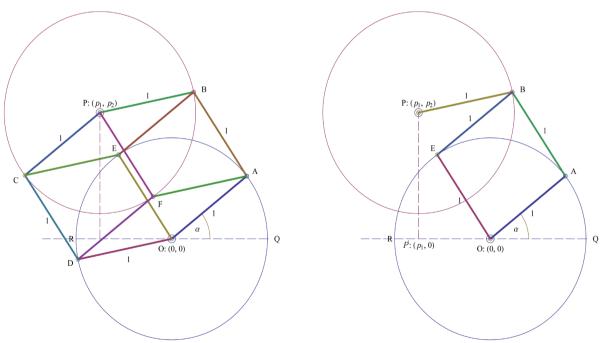


Figure 2. Rhombic bicompasses fixed in point O and in arbitrary point P in full variant with 12 arms and in a reduced variant with 5 arms of unit length.

distance from O to P equal to $\overline{OP} = \sqrt{2}$ which can be constructed by compasses and ruler. Since we have the root sum $z_1 + z_2 + z_4 = \frac{-1 + \mathrm{i}\sqrt{7}}{2}$ for the roots z_1, z_2, z_4 which are somewhere on the circle around the coordinate origin O its sum ends on the fixed point P. This guarantees that in a certain position of the rhombic bicompasses which up to now we do not know the points A, E, D correspond exactly to the roots z_1, z_2, z_4 . Since $z_2 = z_1^2$ the point z_1 lies on the bisection of the angle between $z_0 = 1$ and z_2 . Thus we have now to find the position of the rhombic bicompasses where the point A lies on the bisection of the angle between points Q and E. This can be made by a simple additional device with two arms of equal but arbitrary (within certain limits) lengths a and rotatable around movable point a0 which we connect rotatably with the points a1 and a2 and a3. When the point a3 reaches the prolongation of the line from a4 of the rhombic bicompasses possesses then the desired coordinates a3 and the corresponding point a4 of the rhombic bicompasses possesses then the desired coordinates a4 and the corresponding point a5 and the point a5 and the point a6 and the point a6 and the point a7 and the point a6 and the point a8 and the point a9 and the

the coordinates $\left(\cos\left(\frac{4\pi}{7}\right),\sin\left(\frac{4\pi}{7}\right)\right)$, respectively, and the essential part of the problem of the construction of

the regular heptagon is completed (**Figure 5**). Since $z_4 = z_2^2$ the same construction as here described with the points (Q, A, E) leading to the roots $(z_0 = 1, z_1, z_2 = z_1^2)$ can be also made with the points (Q, E, D) leading to the roots $(z_0 = 1, z_2, z_4 = z_2^2)$ (see **Figure 5** on right-hand side).

Apart from the rhombic bicompasses as a new mean for geometrical constructions it is necessary to refer to a further difference to usual constructions by compasses and ruler. The bisection of an angle cannot be made in our construction at a final stage of a figure but has to be controlled continuously in the process of construction by the rhombic bicompasses.

Absolute minimum bicompasses with 3 equal arms

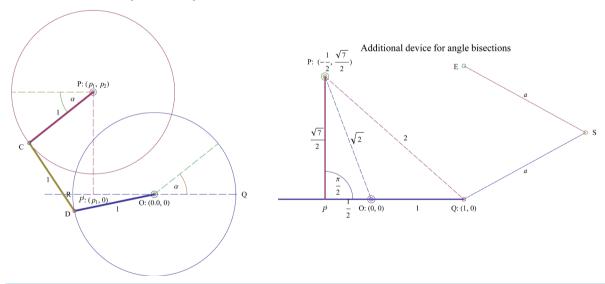
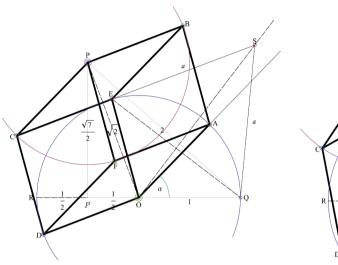


Figure 3. Absolute minimum bicompasses fixed in point O and in arbitrary point P (on the left) and additional device for angle bisection (on the right). The absolute minimum bicompasses with arms of equal lengths (set 1) and with the special parameters $(p_1, p_2) = \left(-\frac{1}{2}, \frac{\sqrt{7}}{2}\right)$ for the heptagon are appropriate for fixing the position when the arm CD goes through the point R with coordinates (-1,0) in which case we have $\alpha = \frac{2\pi}{7}$ (see Section 4). In the device for angle bisection we used the special parameters (p_1, p_2) for heptagon and the points Q and E have to be connected in rotatable way with the points Q and E of the rhombic bicompasses (or with Q and D, respectively).

²It is easy to build a primitive model of rhombic bicompasses by simple means such as the arms from thin cardboard and with rivets at the corners to allow rotations

Rhombic bicompasses for $\alpha < \frac{2\,\pi}{7}$; bisection between OQ and OE

Rhombic bicompasses for $\alpha > \frac{2\pi}{7}$; bisection between OQ and OE



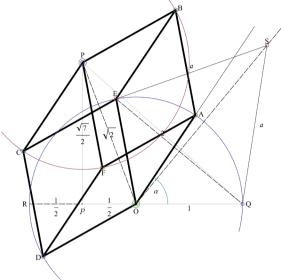
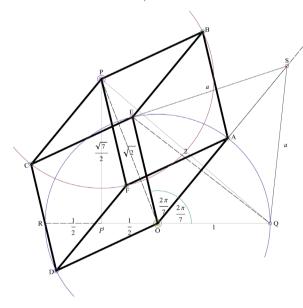


Figure 4. Rhombic bicompasses fixed at O:(0,0) and $P:\left(-\frac{1}{2},\frac{\sqrt{7}}{2}\right)$ in positions with angle $\alpha < \frac{2\pi}{7}$ and $\alpha > \frac{2\pi}{7}$.

Rhombic bicompasses for $\alpha=\frac{2\,\pi}{7}$; bisection (Q, E) \equiv (z_0 , z_2) \rightarrow A \equiv z_1

Rhombic bicompasses for $\alpha=\frac{2\,\pi}{7}$; bisection (Q, D) $\equiv(z_0,\,z_4)\to {\rm E}\equiv z_2$



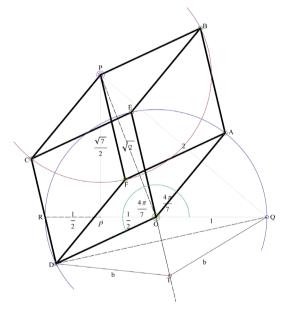


Figure 5. Rhombic bicompasses fixed at O:(0,0) and $P:\left(-\frac{1}{2},\frac{\sqrt{7}}{2}\right)$ in position with angle $\alpha=\frac{2\pi}{7}$ and with two different determinations of half angles. The arm CD goes exactly through the point R:(-1,0).

4. Alternative Method to the Described Angle Bisections

From Figure 1 it is seen that the prolonged ray from coordinate origin through the point z_3 which lies on the

unit circle around O of the complex plane goes also through the point $z_2 + z_4$ which lies on the unit circle around the point P. This becomes clear from the fraction

$$\frac{z_2 + z_4}{z_3} = \frac{\exp\left(i2\frac{2\pi}{7}\right) + \exp\left(i4\frac{2\pi}{7}\right)}{\exp\left(i3\frac{2\pi}{7}\right)} = 2\cos\left(\frac{2\pi}{7}\right) \approx 1.24698.$$
 (8)

which is a real number. From **Figure 1** it is also seen that the line between the points $z_2 + z_4$ and z_4 goes through the point z = -1 (denoted by R) of the complex plane. This line is described in parametric representation with the parameter t by

$$z = t\left(z_2 + z_4\right) + \left(1 - t\right)z_4 = z_4 + tz_2 = \exp\left(i4\frac{2\pi}{7}\right) + t\exp\left(i2\frac{2\pi}{7}\right), \quad (0 \le t \le 1).$$
 (9)

It is easy to check that for parameter value t according to

$$t = -\left(z_2 + z_2^*\right) = -\left(z_2 + z_5\right) = -2\cos\left(2\frac{2\pi}{7}\right) \approx 0.445042, \quad \Rightarrow \quad z = -1,$$
 (10)

the line (9) goes exactly through the point z=-1 of the complex plane (point R in Figure 4 and Figure 5). This can also be used for the determination of the right position of the rhombic bicompasses for the construction of the regular heptagon by controlling the angle α for which the line between points C and D goes through the point z=-1. Using this the absolute minimum bicompasses in Figure 3 are already sufficient for the construction of the angle $\frac{2\pi}{7}$ which is then the angle between the sides OC and OD from coordinate origin O (see also Figure 5 and Figure 1).

5. A few Words about Neusis Construction of the Regular Heptagon

The known construction of the regular heptagon rests on the trisection of an arbitrary angle attributed to Archimedes and belongs to a kind of constructions which is often called a neusis construction [3] [8] (see there also for word explanation from the Greek). It is not possible by compasses and unmarked ruler where the ruler serves to draw a line between given points but neusis constructions require to fit a given length markable on a ruler in such a way that it intersects at once a given line and a given circle or second line with its marked ends and where the ruler has to go through a further given point on the circle which cannot be fixed on the ruler and has to be fitted (e.g., [1]-[3] [7] [8]).

The equation for the trisection of a given angle φ and therefore of its given $\cos(\varphi)$ is

$$4x^3 - 3x - \cos(\varphi) = 0, \quad \left(x = \cos\left(\frac{\varphi}{3}\right)\right). \tag{11}$$

The cubic Equation (1) for $\frac{z+z^{-1}}{2}$ leads with a substitution to the same type of Equation (11) with 3 real solutions, concretely to

$$4x^{3} - 3x - \frac{\sqrt{7}}{14} = 0, \quad \left(x = \frac{3}{\sqrt{7}} \left(\frac{z + z^{-1}}{2} + \frac{1}{6} \right) \right), \tag{12}$$

which is equivalent to a certain Cosine of an angle φ according to $\cos(\varphi) = \frac{\sqrt{7}}{14}$ or $\sin(\varphi) = \frac{3\sqrt{21}}{14}$ and thus $tg(\varphi) = 3\sqrt{3}$ which can be constructed by compasses and ruler. The trisection of this angle φ (corresponds approximately to $\varphi \approx 0.878962\frac{\pi}{2}$) is then to make by the neusis construction of Archimedes and

from the positive solution $x = \cos\left(\frac{\varphi}{3}\right)$ one can determine then $\cos\left(\frac{2\pi}{7}\right)$ according to (the two negative

solutions for
$$x$$
 correspond to $\cos\left(\frac{4\pi}{7}\right) = \frac{z_2 + z_5}{2}$ and to $\cos\left(\frac{6\pi}{7}\right) = \frac{z_3 + z_4}{2}$)
$$\cos\left(\frac{2\pi}{7}\right) = \frac{\sqrt{7}}{3}x - \frac{1}{6},$$
(13)

which is possible by compasses and ruler. Detailed such neusis constructions can be found in the given references [3] [8], in [3] in addition to case n = 7 also constructions for n = 9, 13, 17.

6. Conclusion (With a Short Outlook on 7-Fold Symmetry in Living Nature)

It was shown that the regular heptagon can be constructed by a new mean which we called rhombic bicompasses in connection with a ruler. The rhombic bicompasses allow to draw at once two circles of given fixed distance of their centers in such correlated way that the position of one arm determines the positions of all other arms. Evidently, the solution of a cubic equation which is necessary for the construction of the regular heptagon is hidden in the correlation of the arms of the bicompasses and, explicitly, appear only square roots in the points for the construction, for example, the distances of the fixed points of the rhombic bicompasses.

One may ask whether or not it is possible to construct other regular n-gons for prime numbers n > 7 by rhombic bicompasses. The case n = 11 is the worst case up to n = 17 since the palindromic polynomial to the cyclotomic equation for n = 11 can only be factorized into the product of two polynomials of 5-th degree with coefficients which contain only square radicals and with the roots $z_k = \exp\left(ik\frac{2\pi}{11}\right)$ corresponding to

k = (1, 3, 4, 5, 9) in one and k = (2, 6, 7, 8, 10) in the other polynomial that leads to 5-th degree equations of general form which cannot be solved in radicals due to absent further symmetries of the roots in each cycle [2] [4] [10]. This is as it is known not possible to construct by compasses and ruler and also not by the new mean of rhombic bicompasses. The palindromic part of the cyclotomic equation for n=13 after separation of factor z-1 can be factorized into 4 polynomials of third degree with only (complex) quadratic radicals in the coefficients but corresponding to two different sums of three roots and therefore apart from coordinate origin

O to two different centers of the bicompasses which are $\frac{\sqrt{13}-1+i\sqrt{2(13-\sqrt{13})}}{4}$ and

$$\frac{-\sqrt{13}-1+i\sqrt{2\left(13+\sqrt{13}\right)}}{4}$$
, correspondingly (or of their complex conjugate), and with the roots $z_k \equiv \exp\left(ik\frac{2\pi}{13}\right)$ corresponding to $k = (1,3,9)$ and $k = (2,5,6)$ (or to their complex conjugate

$$z_k = \exp\left(ik\frac{2\pi}{13}\right)$$
 corresponding to $k = (1, 3, 9)$ and $k = (2, 5, 6)$ (or to their complex conjugate

k = (4, 10, 12) and k = (7, 8, 11) in each polynomial factor of third order. This means that one does not have angles and doubled angles in one cycle but, at least, only angles and their threefold angles such as in $k = (1, 3, 9, (27 \equiv 1 \mod 13))$ and the construction by the bicompasses is only possible in connection with a neusis construction to fix the trisection of an angle during the correlation of the points on one circle. Since, however, this neusis construction can be made only during the controlled work with the bicompasses it cannot be considered as an appropriate geometric construction. The case of the regular polygon to n = 17 is well known as constructible by compasses and ruler since the 16-th order palindromic part of the cyclotomic equation can be resolved by products of second-degree equations with only quadratic radicals in the coefficients. As is very famous, Gauss discovered this in 1796 (published in "Disquisitiones Arithmeticae" in 1801) and he found

additionally that all regular polygons with odd $n = p_1 p_2 \cdots p_k$ of the form $p_i = 2^{\binom{2^{i_i}}{2}} + 1$ to non-negative integers l_i if resulting p_i are prime numbers (Fermat numbers) and therefore, clearly, with all even $n' = 2^m n, (m = 1, 2, \cdots)$ by angle bisections are constructible by compasses and ruler [1]-[9].

Let us make some remarks on seven-fold symmetries in living things. Nature does not often realize the symmetry C_7 of a regular heptagon contrary to ubiquitous cyclic symmetries C_3, C_4, C_5 and C_6 and more rarely also C_8 (e.g., Dryas octopetala, Rosaceae (mountain avens)) and nearly C_{∞} in the flowers of flowering plants. Mostly this is combined with mirror symmetry in form of C_{nv} instead of C_n alone but certain exception are species of Apocynaceae, the dogbane family, e.g., Nerius oleander (oleander), Vinca minor (lesser periwinkle) and *Plumeria* (frangipani) which possess only C_5 but not C_{5v} . One may ask why this is so and does it possess somewhat of a far connection to impossible constructibility by compasses and ruler. In other words: is it more difficult for nature to realize 7-fold symmetry than 3-, 4-, 5- or 6-fold symmetry. One example from nature for a 7-fold symmetry is the flower of *Trientalis europaea*, *Primulaceae* (chickweed wintergreen; in German: Europäischer Siebenstern, substituted by Trientalis borealis, T. latifolia in North America) that, however, is even an exception among the Primula family which members mostly possess a stable 5-fold symmetry. This 7-fold symmetry of *Trientalis europaea* is not very stable since one may often find exemplars of this species with 6-fold symmetry and more rarely with 8-fold symmetry as one can see from pictures and as I found by myself in nature. A 7-fold symmetry C_7 is very rare within the world of living organisms also in the other kingdoms such as animals (e.g., a few species of sea stars with seven arms), whereas astonishingly the 5-fold symmetry is very common in the kingdom of plants, in particular, within the flowering plants in Dicotyledones (e.g., the most species of the families Rosaceae, Primulaceae, Boraginaceae, Solanaceae, Saxifragaceae, Campanulaceae, Geraniaceae, Malvaceae, Linaceae among others and some families with a major part of species with 5-fold symmetry such as Ranunculaceae, Caryophyllaceae, Ericaceae and Gentianaceae, in these cases also species with 4-fold symmetry and zygomorphic species in the first). Clearly, there are also families with only 4-fold symmetry C_4 of the flowers (e.g., Rubiaceae and Brassicaceae, in last case only the petals and sepals but not the 6 stamens) and also 3-, and 6-fold symmetries C_3 and C_6 (most Monocotyledones) mostly combined with mirror symmetries in form of C_{nv} .

Acknowledgements

We note here commendably that all figures are made using Wolfram's "Mathematica 6".

References

- [1] Courant, R. and Robbins, H. (1996) What Is Mathematics? Oxford University Press, Oxford.
- [2] Stewart, I. (2004) Galois Theory. 3rd Edition, Chapman & Hall/CRC, Boca Raton.
- [3] Convay, J.H. and Guy, R.K. (1996) The Book of Numbers. Springer, New York. http://dx.doi.org/10.1007/978-1-4612-4072-3
- [4] Edwards, H. (1984) Galois Theory. Springer, New York.
- [5] Postnikov, M.M. (1963) Teorija Galoa (in Russian), Fizmatgiz, Moskva. (English translation: Postnikov, M.M. (2004) Foundations of Galois Theory. Dover Publications, New York).
- [6] Shkolnik, A.G. (1961) The Problem of Circle Division (in Russian). Uchpedgiz, Moscow.
- [7] Bold, B. (1969) Famous Problems of Geometry and How to Solve Them. Dover, New York.
- [8] Weisstein, E.W. (2013) Heptagon, from MathWorld—A Wolfram Web Resource. http://mathworld.wolfram.com/Heptagon.html
- [9] van der Waerden, B.L. (1964) Algebra, 1. Teil. 6th Edition, Springer, Berlin.
- [10] Klein, F. (1884) Vorlesungen über das Ikosaeder und die Auflösung der Gleichungen vom fünften Grade. Leipzig.

Appendix A. Points and Geometric Objects in the Rhombic Bicompasses Fixed at Points O and P

We collect here the results of Cartesian coordinates (x, y) corresponding to the complex number x+iy for the positions of the points of rhombic bicompasses with two opposite points fixed at the coordinate origin O and at a general point P which we later specialize for the regular heptagon

$$O: (0,0), P: (p_1, p_2); Q: (1,0), R: (-1,0).$$
 (1)

The movable points of rhombic bicompasses on the circle around O in dependence on the angle α possess the coordinates (see Figure 2)

A:
$$(a_1(\alpha), a_2(\alpha)) = (\cos(\alpha), \sin(\alpha)),$$

E: $(e_1(\alpha), e_2(\alpha)) = \left(\frac{p_1 - \cos(\alpha)}{2} + t\frac{p_2 - \sin(\alpha)}{2}, \frac{p_2 - \sin(\alpha)}{2} - t\frac{p_1 - \cos(\alpha)}{2}\right),$ (2)
D: $(d_1(\alpha), d_2(\alpha)) = \left(\frac{p_1 - \cos(\alpha)}{2} - t\frac{p_2 - \sin(\alpha)}{2}, \frac{p_2 - \sin(\alpha)}{2} + t\frac{p_1 - \cos(\alpha)}{2}\right),$

and on the circle around P

$$C: (c_{1}(\alpha), c_{2}(\alpha)) = (p_{1} - \cos(\alpha), p_{2} - \sin(\alpha)),$$

$$F: (f_{1}(\alpha), f_{2}(\alpha)) = \left(\frac{p_{1} + \cos(\alpha)}{2} - t\frac{p_{2} - \sin(\alpha)}{2}, \frac{p_{2} + \sin(\alpha)}{2} + t\frac{p_{1} - \cos(\alpha)}{2}\right),$$

$$B: (b_{1}(\alpha), b_{2}(\alpha)) = \left(\frac{p_{1} + \cos(\alpha)}{2} + t\frac{p_{2} - \sin(\alpha)}{2}, \frac{p_{2} + \sin(\alpha)}{2} - t\frac{p_{1} - \cos(\alpha)}{2}\right),$$

$$(3)$$

with the abbreviation

$$t = t(\alpha) = +\sqrt{\frac{3 - p_1^2 - p_2^2 + 2(p_1 \cos(\alpha) + p_2 \sin(\alpha))}{1 + p_1^2 + p_2^2 - 2(p_1 \cos(\alpha) + p_2 \sin(\alpha))}},$$
(4)

where changing the sign of the root interchanges the points $E \Leftrightarrow D$ and $F \Leftrightarrow B$. Using the given coordinates one may easily check the independence of the following distances on the angle α

$$\overline{OA} = \overline{OE} = \overline{OD} = 1, \quad \overline{PC} = \overline{PF} = \overline{PB} = 1,
\overline{AB} = \overline{AF} = \overline{CD} = \overline{CE} = \overline{BE} = \overline{DF} = 1.$$
(5)

The above formulae are necessary to reproduce the given figures for the bicompasses and for the construction of the regular heptagon.

In case of the regular heptagon, we have to apply (2) and (3) in connection with (4) in the specialization

$$P: (p_1, p_2) = \left(-\frac{1}{2}, \frac{\sqrt{7}}{2}\right), \quad p_1^2 + p_2^2 = 2,$$

$$t = t(\alpha) = +\sqrt{\frac{1 - \cos(\alpha) + \sqrt{7}\sin(\alpha)}{3 + \cos(\alpha) - \sqrt{7}\sin(\alpha)}}.$$
(6)

In particular, for $\alpha = 0$ from which follows t = t(0) = 0 the bicompasses take on a special degenerate position with identities A = Q: (1,0), $C: \left(-\frac{3}{2}, \frac{\sqrt{7}}{2}\right)$, $D = E: \left(-\frac{3}{4}, \frac{\sqrt{7}}{4}\right)$ and $B = F: \left(\frac{1}{4}, \frac{\sqrt{7}}{4}\right)$ and forming two bordering rhombi of equal form.

The points S and T for angle bisections are parameterized by the angle α and the arbitrary parameters a and b (within certain limits) using $(e_1(\alpha))^2 + (e_2(\alpha))^2 = (d_1(\alpha))^2 + (d_2(\alpha))^2 = 1$ by

$$S: (s_{1}(\alpha, a), s_{2}(\alpha, a)) = \left(\frac{1}{2}\left(1 + e_{1}(\alpha) + \sqrt{\frac{2a^{2} - (1 - e_{1}(\alpha))}{1 - e_{1}(\alpha)}}e_{2}(\alpha)\right),$$

$$\frac{1}{2}\left(e_{2}(\alpha) + \sqrt{\frac{2a^{2} - (1 - e_{1}(\alpha))}{1 - e_{1}(\alpha)}}(1 - e_{1}(\alpha))\right)\right),$$

$$T: (t_{1}(\alpha, b), t_{2}(\alpha, b)) = \left(\frac{1}{2}\left(1 + d_{1}(\alpha) + \sqrt{\frac{2b^{2} - (1 - d_{1}(\alpha))}{1 - d_{1}(\alpha)}}d_{2}(\alpha)\right),$$

$$\frac{1}{2}\left(d_{2}(\alpha) + \sqrt{\frac{2b^{2} - (1 - d_{1}(\alpha))}{1 - d_{1}(\alpha)}}(1 - d_{1}(\alpha))\right)\right),$$
(7)

with the distances

$$\overline{SE} = \overline{SQ} = a, \quad \overline{TD} = \overline{TQ} = b.$$
 (8)

If we set $\alpha = \frac{2\pi}{7}$ in the above formula we obtain for A, E, D points on the regular heptagon corresponding to the roots (z_1, z_2, z_4) of the cyclotomic equation for n = 7 and for S a point on the half angle between the roots $z_0 = 1$ and z_2 .



Scientific Research Publishing (SCIRP) is one of the largest Open Access journal publishers. It is currently publishing more than 200 open access, online, peer-reviewed journals covering a wide range of academic disciplines. SCIRP serves the worldwide academic communities and contributes to the progress and application of science with its publication.

Other selected journals from SCIRP are listed as below. Submit your manuscript to us via either submit@scirp.org or Online Submission Portal.































