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Table of Contents

Volume 9 Number 2

February 2019

Steel Beam-to-Column RBS Connections: FEM Analysis under Cyclic Loading

D. S. Sophianopoulos, A. E. Deri.....17

Extensive Analysis of Multi Strand Billet Caster Tundish Using Numerical Technique

R. Agarwal, M. K. Singh, R. B. Kumar, B. Ghosh, S. Pathak.....29

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Steel Beam-to-Column RBS Connections: FEM Analysis under Cyclic Loading

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Abstract

In a companion paper [1], an optimization scheme for extended-end-plate Reduced Beam Section (RBS) connections of steel-moment-frames was presented, based on the component method of Eurocode 3, on regression analysis and on principles of Mechanics under monotone loading. European beam and column profiles were utilized, in conjunction with geometric restrictions and constraints of North American and European Standards for prequalified radius-cut RBS. The aforementioned method aimed for an excellent seismic performance, the verification and validation of which is the content of the present study. Using FEM modeling and accounting for the assumptions used in the optimum design, after calibration with existing experimental data, the optimum connections were numerically analyzed under cyclic loading, adopting a well-accepted displacement-based protocol. All optimum solutions exhibited an excellent cyclic response, and met very satisfactorily all the performance criteria for seismic design. Results in terms of hysteretic $M-\phi$ curves at three characteristic areas of the connections validate the whole analysis, a fact aiming to assist in incorporation the radius-cut RBS concept in European Steel Design Codes and engineering practice.

Keywords

RBS Connections, FE Modeling, Cyclic Loading, Seismic Performance Criteria, Optimum Design, European Standards and Practice

1. Introduction

Since 1995, and after the Northridge and Kobe earthquakes, the Reduced Beam Section connection was introduced as a safety concept for structures in seismic zones. Extensive theoretical and experimental investigations lead to the prequalification of the radius-cut RBS connection in North America [2], but regarding

US and Canadian connection types of steel moment resisting frames. In Europe however, and although the introduction of the RBS was performed by Plumier [3], and also patented in Asia [2], there is poor existing data. Only recently [4] [5] [6] experiments and FEM analyses of RBS connections based on European Practice (beam-to-column welded or extended endplate bolted) were performed, while the only references of the Eurocodes regarding RBS are those given in EC8-Part 3 [7], as also mentioned in the companion paper [1]. Therein, an optimization scheme under monotone loading was adopted, using European I-profiles for the beams and columns of the RBS connection and standard symmetrical extended endplate joints. This led to eight optimum RBS connections, which in the present work are analyzed via the FEM under cyclic loading, in order to validate the whole design and prove that these connections meet to the maximum possible extent the performance criteria of seismic design [8] [9] [10]. After calibration of the proposed FE model with existing experimental data [6] and adopting a preliminary pushover analysis, the aforementioned optimum connections exhibited an excellent response as per every criterion. Hence, it is anticipated that both parts of the foregoing work will assist in incorporating the RBS concept in Eurocodes 3 and 8 as a new design methodology for both static and seismic applications.

Evidently, there are also other types of RBS connections that have been reported in the relevant literature, as for instance in the work by Rahnavard *et al.* [11], where a comparison of the seismic response of these types with the one of the radius-cut RBS was investigated. Furthermore, fragility functions to estimate the probability of reaching or exceeding different damage states in reduced beam section (RBS) beam-to-column moment connections of steel moment resisting frames have been also reported [12]. In the companion paper [1], extended bibliographic information has been given, and it will not be repeated here for brevity. For a detailed overview of the parameters affecting the response of RBS connections, one may refer to an already cited work by the authors [2].

2. Finite Element Modeling

2.1. Formulation of the Model

Let us consider a statically optimized connection [1] with European I-profiles for the beams and columns as well as with radius-cut RBS, as shown in **Figure 1**. The geometry and generalized forces of the optimum connection of the companion paper can be found in tabular form in **Appendix**, at the end of the manuscript. Such a connection is thereafter modeled in Abaqus Software [13] utilizing the C3D10M 10-node continuous solid element, suitable for large nonlinear deformations and contact problems. The parts-assembly concept was adopted and a denser mesh for the RBS and the beam-column interface was introduced. Moreover, fixed conditions were imposed at the ends of the column, while adequate constraints were also added to the beam, in order to minimize local buckling phenomena. The final FE model is illustrated in **Figure 2**, for which a mesh convergence was finally achieved.

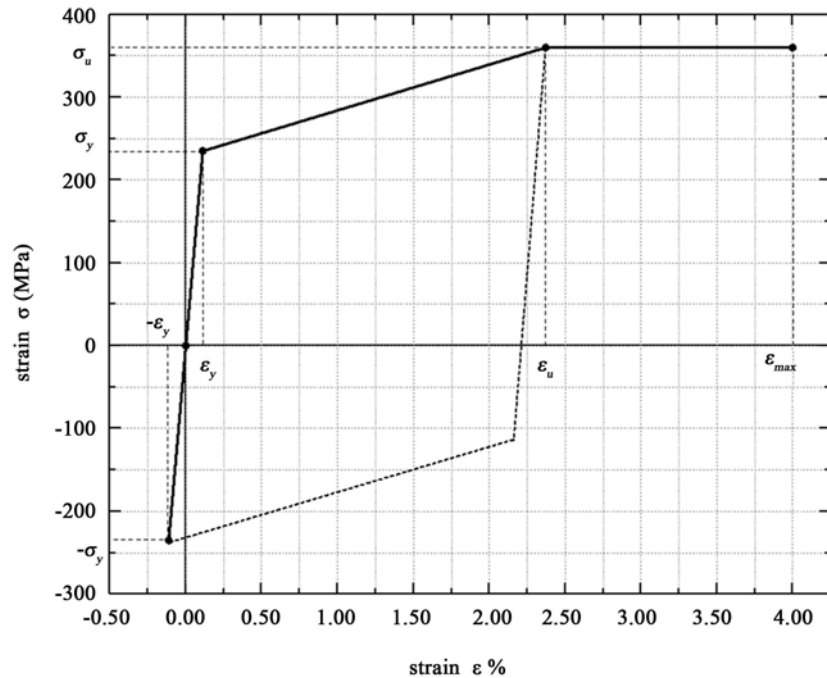


Figure 3. Material model used in the FE simulation (for S235 steel).

2.3. Model Calibration

Before attempting any cyclic analysis, the proposed model was calibrated with existing experimental data [6]. After proper adjustments of this model to the experimental setup (as far as geometry, loading protocol and material properties were concerned), its cyclic response was found in very good agreement with the results of the experiments, as shown throughout **Figure 4**, in terms of hysteretic loops at two characteristic points of the connection.

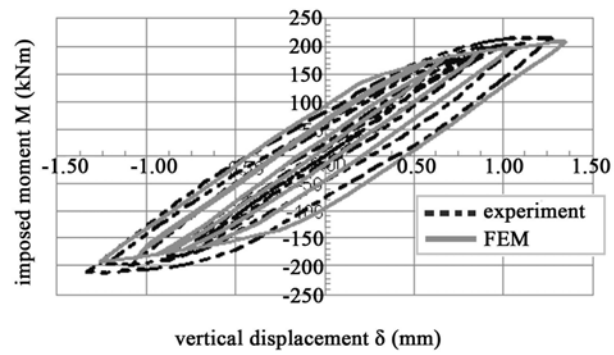
2.4. Loading Protocol and Displacement-Based Cyclic Analysis

The cyclic analysis was based on initially evaluating the failure displacement Δf of each optimum connection, which was achieved via static pushover analysis. The goal was to impose the displacement at a proper point along the beam, such that the shear developing at the middle of the RBS was equal to V_{RBS} as evaluated during the optimization procedure. The whole scheme is shown in **Figure 5**, where the distance z is calculated and from its value, the failure displacement is appraised.

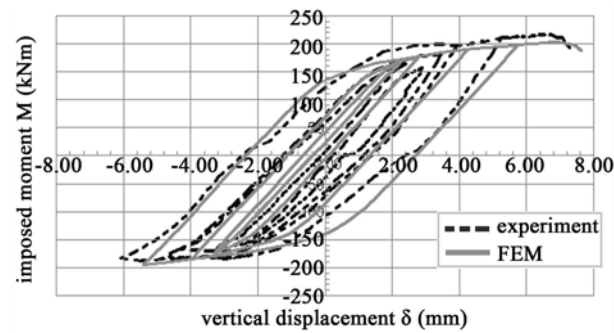
In the sequel, for each optimum solution, a well-established displacement protocol [15] was used, since both the values of z and Δf were found earlier. This protocol, in terms of cycle number vs. dimensionless amplitude imposed, is depicted in **Figure 6**.

2.5. Performance Criteria

For all eight optimum designs, strict seismic performance criteria were considered, in order to validate the whole analysis. These are the following:

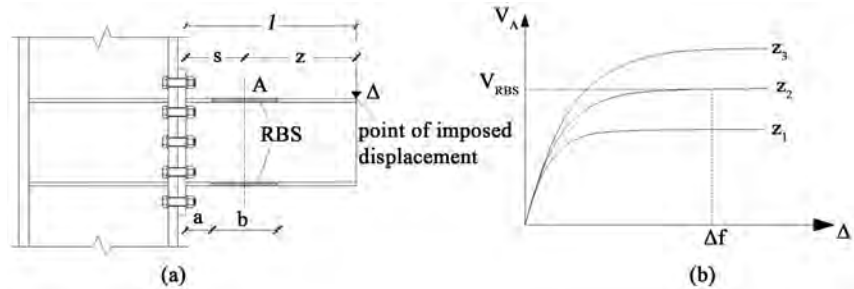


(a)



(b)

Figure 4. Calibration of the proposed FE model, (a) at 3 cm away from the column face; and (b) at the middle of the RBS, in terms of M - δ curves.



(a)

(b)

Figure 5. Geometry (a) and static pushover curves (b) for establishing the point of imposing the cyclic displacement along the beam.

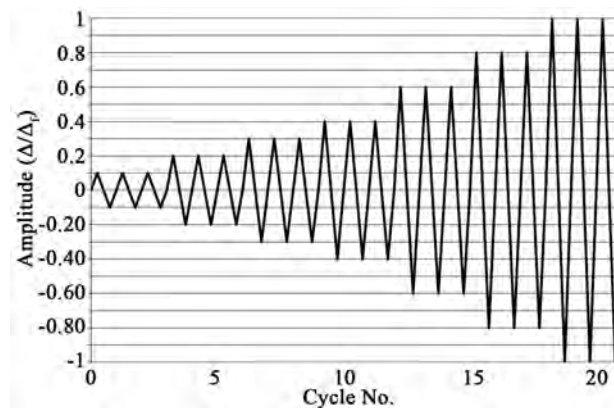


Figure 6. Loading protocol adopted (saw-tooth diagram).

- 1) Formation of the 1st plastic hinge in the Reduced Beam Section;
- 2) Development of a plastic rotation within the RBS of at least 0.03 rad and simultaneous minimal such rotations at the interface between beam and end-plate;
- 3) Large energy dissipation at the RBS, without any local buckling phenomena, that would reduce ductile behavior;
- 4) Avoidance of yield spreading in the bolts and minimum prying forces;
- 5) Steady hysteretic response of the panel zone with small energy dissipation; and
- 6) Elastic response of the column flange connected.

Hence, three specific and characteristic areas of the connections were examined, namely the middle of the RBS, the interface between beam and end-plate, and middle of the panel zone, as illustrated below, in **Figure 7**.

3. Numerical Results and Discussion

Numerical results, in terms of hysteretic loops—moment/rotation curves were obtained for all the eight statically optimized connections, at the three areas shown in the previous figure. For brevity, the outcome of the pushover and cyclic analysis will be presented 1) for the best optimum solution, *i.e.* connection 2 (see **Appendix**), and 2) as the overall results for the first four optimum connections. Similar response was obtained for the rest of the optimum connections.

More specifically, in **Figure 8(a)** and **Figure 8(b)** one may perceive the static pushover curve and the distribution of stresses of connection 2, while in **Figures 9(a)-(c)** the $M-\phi$ curves for this specific connection are shown. Moreover, **Figures 10(a)-(c)** depict the outcome of the FE cyclic analysis for the 1st four optimum solutions, in terms of $M-\phi$ curves, as previously stated.

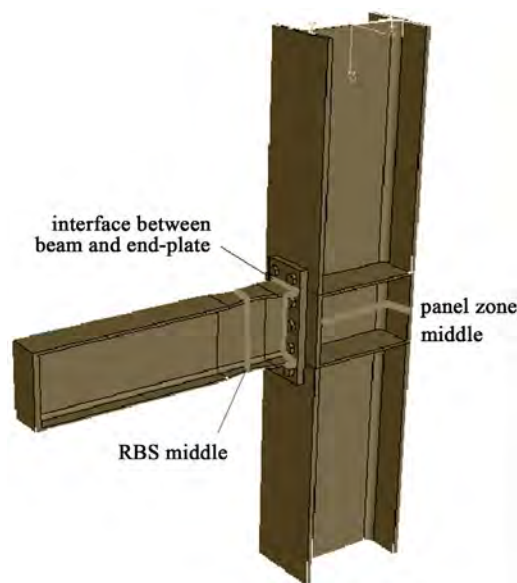


Figure 7. The three characteristic areas of the connections, for which numerical results were obtained.

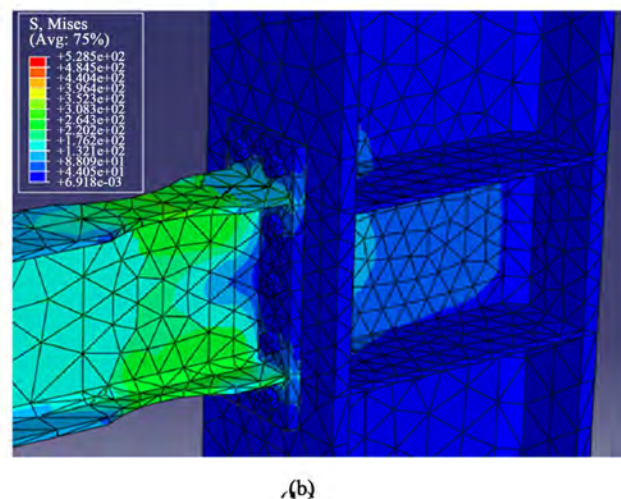
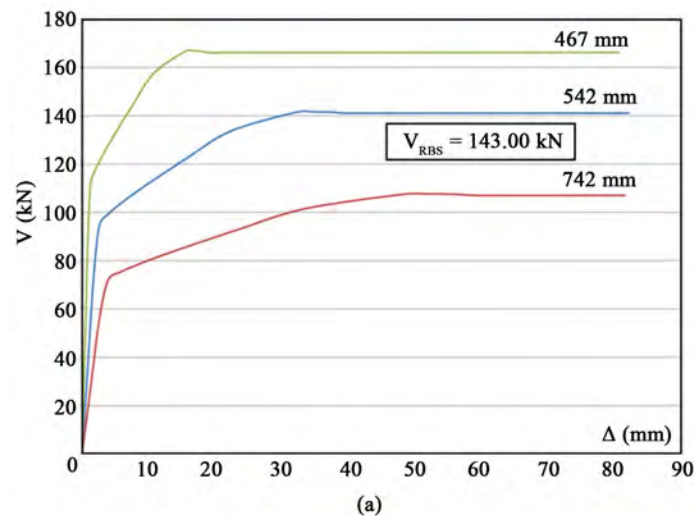


Figure 8. Static pushover curve (a); and distribution of stresses in the FE model of connection 2 (b), as in [1].

From these figures, it is proven that all the performance criteria were met in a very satisfactory manner. No local buckling was encountered (*i.e.* low cycle fatigue), prying forces did not seem to appear and additionally the panel zone was not affected by the increasing amplitude of the displacement until the plastic hinge was formed in the RBS. The bolts and the column flange connected performed as designed and expected, while the desired energy dissipation was concentrated within the RBS. The above results can be interpreted as a success of the whole analysis and optimum design methodology proposed in the foregoing as well as in the companion paper. This fact will hopefully assist in incorporating the RBS concept as a design alternative for moment resisting steel frames in both EC3 and EC8 as well as in everyday European engineering practice.

Future work requires the effect of a much larger axial force on the columns, in order to use alternative modeling of the RBS connections (details given in [1]). The work is ongoing and will produce results that are more interesting in the near future, accompanied by experimental ones.

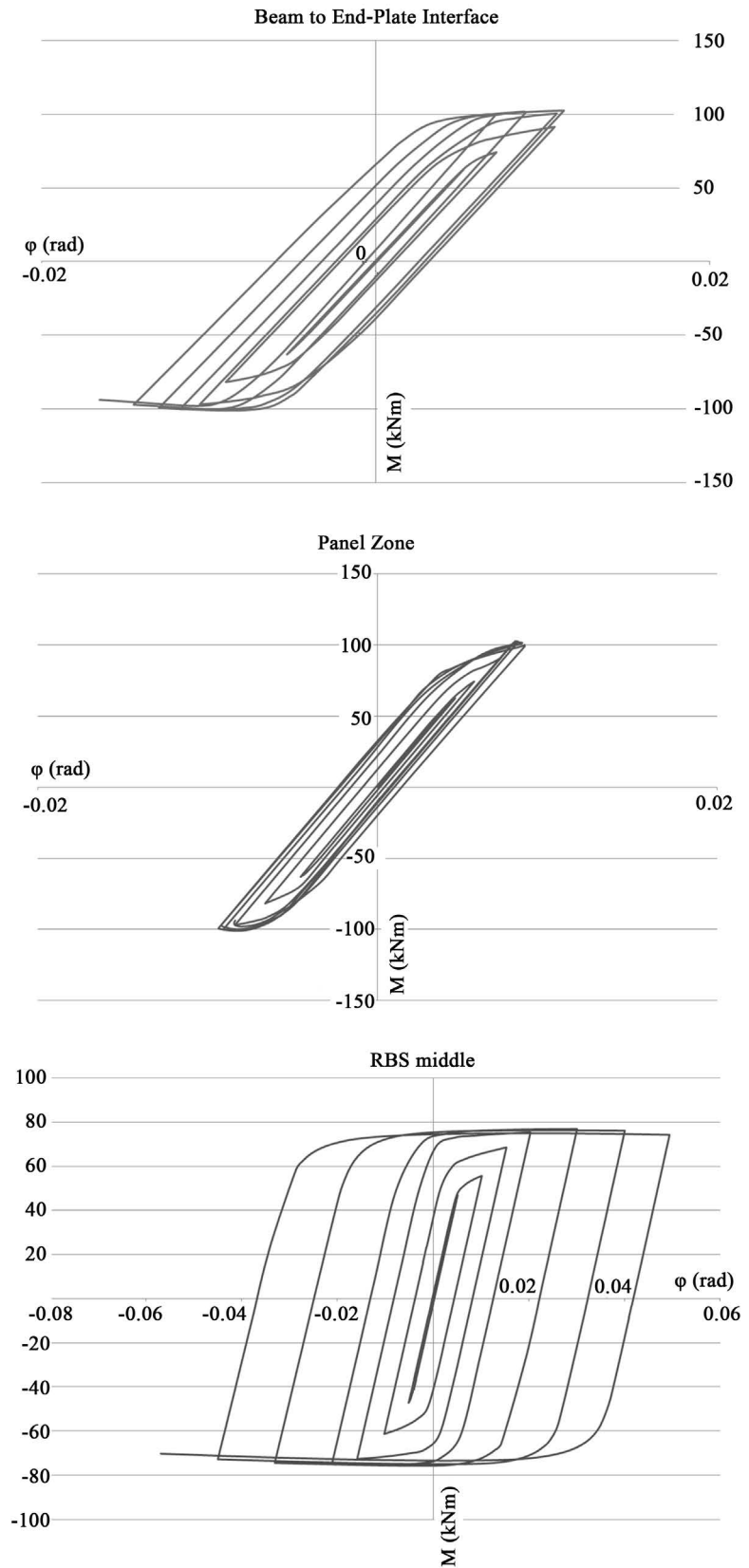


Figure 9. Results, in terms of moment-rotation curves, for connection 2 according to [1], at the three characteristic areas described previously.

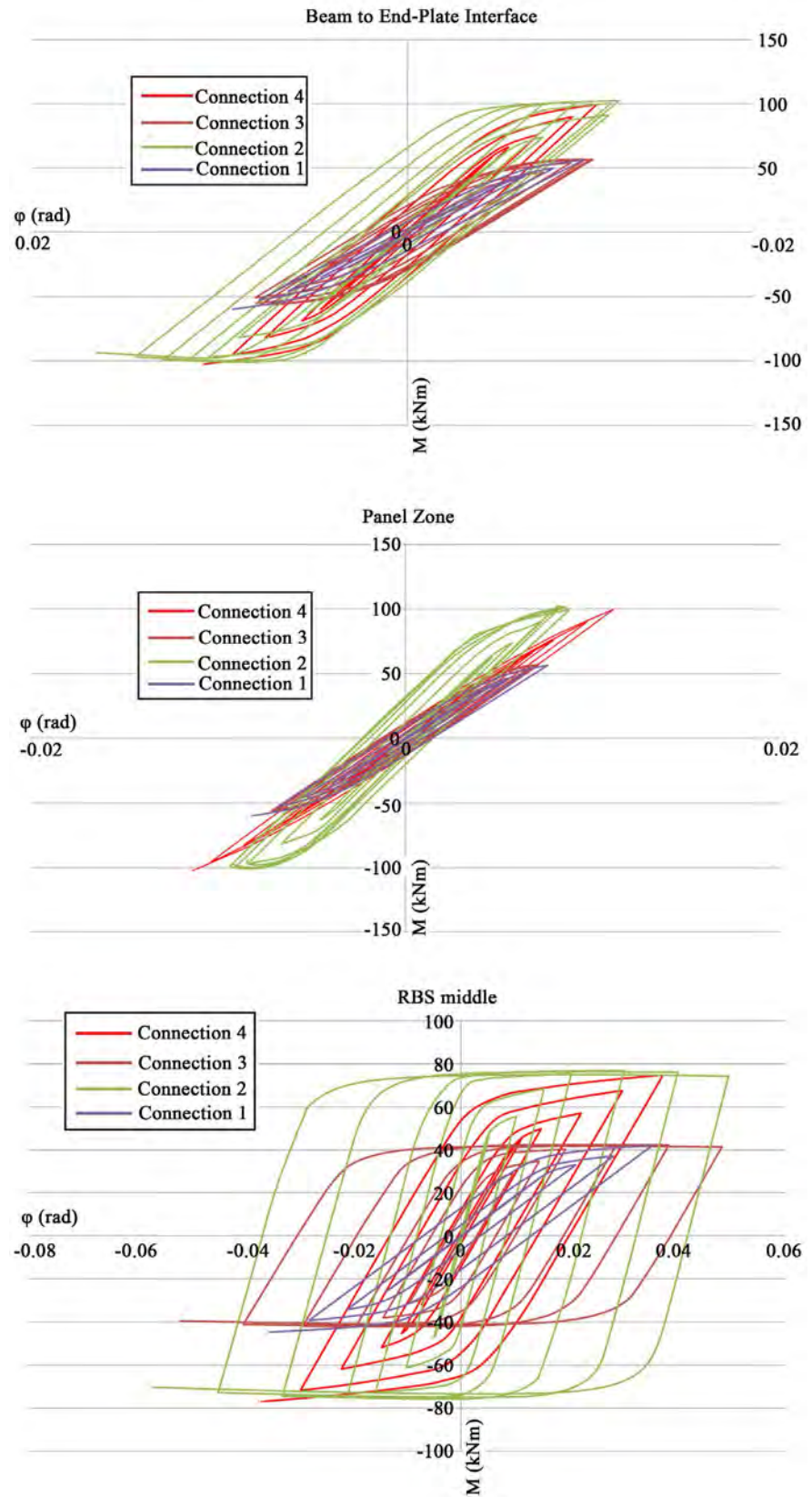


Figure 10. Overall results, in terms of moment-rotation curves, for the 1st four optimized connections, according to [1] (see also **Appendix**).

4. Conclusions

As declared also in the Abstract, the aim of this work was the validation of the results obtained via static optimization procedure [1] by a FE cyclic analysis. This was achieved in a very satisfactory extent, and hence one may draw the following conclusions:

- 1) The FE modeling of the RBS connections was adequate, since it was properly calibrated with existing relevant experimental result;
- 2) The displacement-based cyclic FE analysis adopted fully validated the optimization methodology under monotone loading—outcome of the companion paper;
- 3) All optimum designs showed excellent cyclic performance and met all strict performance criteria;
- 4) The goal of the whole scheme proposed will hopefully assist in incorporating the RBS concept for the seismic design of moment resisting steel frames in Europe, both in Standards and practice.

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The authors are indebted to Prof. E. S. Mistakidis at their home Department and to Associate Prof. K.-D. Tsavdaridis at the University of Leeds, UK, for their valuable suggestions and help.

Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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Appendix

The geometry and the generalized forces developing in the eight statically optimized connections of the companion paper [1] are given in the following **Table A1** and **Table A2**.

Table A1. Geometry of optimized connections.

No	Beam	Column	x (mm)	y (mm)	a (mm)	b (mm)	c (mm)	e/e_1^* (mm)	t_p (mm)	Bolts
1	IPE220	HEB400	100	75	66	165	25	35	20	M20/8.8
2	IPE270	HEB450	95	90	81	202.5	33	40	30	M24/10.9
3	IPE220	HEA550	100	70	66	165	27	35	20	M20/8.8
4	IPE270	HEA500	85	95	81	202.5	33	40	30	M24/10.9
5	HEA220	HEB400	110	110	132	157.5	53	60/35	20	M20/8.8
6	HEA220	HEB500	100	90	132	157.5	47	65/40	30	M24/10.9
7	HEA220	HEA450	100	100	132	157.5	52	70/35	20	M20/8.8
8	HEA220	HEA360	100	90	132	157.5	48	70/40	30	M24/10.9

*if only one number appears, it means that $e = e_1$.

Table A2. Additional geometry and generalized forces of the optimum connections.

No	Base plate dimensions (mm)		Values of Generalized Forces within each Connection*			
	b_p	h_p	$M_{f_{rd}}$ (kNm)	M_{RBS} (kNm)	Objective Function as defined in [1]	V_{RBS} (kN)
1	170	370	68.84	44.13	3.98	102
2	175	440	116.23	77.503	2.3	143
3	170	350	65.09	41.42	4.2	95.78
4	165	460	116.33	77.503	2.398	143
5	230	400	143.878	98.86	2.014	157.143
6	240	350	165.162	108	10.182	171.686
7	240	370	154.185	100.384	10.134	159.567
8	240	350	157.483	106.483	4.68	169.262

*In all connections the value of the ratio $V_{RBS}/V_{pl,RBS}$ was found less than 42%.

Extensive Analysis of Multi Strand Billet Caster Tundish Using Numerical Technique

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Abstract

Continuous casting of steel involving different grades in the same casting sequence remains a challenge to billet caster operators. The intermixed composition obtained during the grade change does not meet the specification of either grade and must be downgraded. Incorrect identification of this intermixed region may result in non-conforming products reaching the customer. In this study, a numerical model based on CFD (computational fluid dynamics approach) has been developed which predicts the start and end of the intermixed composition and the tonnage to be downgraded under different casting conditions. This model was validated and the results were in good agreement with the actual plant data for a 6-strand billet caster at LD-1 of TATA Steel, India. This model is used to calculate transition tonnage for different scenarios, e.g. when one of the outermost strands is not functional or some combinations are not functional and varying casting speed during operation. Furthermore, impact of different design of baffles on performance of Tundish has been evaluated to find a way to reduce transition or intermixed composition.

Keywords

Continuous Casting, CFD, Billet, Tundish, Grade Change, Modelling, Quality Control, Fluid Flow, Heat Transfer

1. Introduction

Continuous casting of steel involves liquid steel to be transferred from ladle to Tundish and finally to mould. The mould provides desired shape, where partial solidification of liquid steel happens. The Tundish works as a buffer between mould and ladle. Tundish provides two functional requirements: inclusion floa-

tation and equal flow to the moulds [1] and [2] for multi strand caster configurations. The number of moulds is in general 1 to 2 for slab casters, 2 to 4 for bloom casters and 2 to 8 for billet caster [3].

When two heats of different composition are cast in a continuous sequence without replacing the Tundish produces intermixed products or grade transition. In such cases, products with intermixed composition are produced which are neither conformal to either composition and are needed to be diverted or downgraded [4] [5] [6]. The casting operators need to know the location and extent of the intermixed region and how it is affected by grade specifications and casting conditions [3] [5]. With the strict norms for steel grades with specific composition, there is a consequent rise of grade transitions in the casting sequence, thus giving a further increase in the cost associated with the intermixed steel.

For the prediction of the intermixed region due to the transition, different techniques have been developed [1] [2]. Water models [1] [2] [7], 3D numerical models [6] [8] and semi-empirical numerical models [3] are the typical tools to address this problem. But each of the method has its own limitations; for example the water model fails to satisfy both Froude and Reynolds similarity criteria on scaled models to predict the transition. In the three-dimensional numerical modelling [8] [9] [10], it requires an injection of tracer, but the credibility of the model is based on the validation with the plant data [8] [11] [12] [13] [14]. Third case of semi-empirical model is based on experiment on real plant conditions where billet/slab composition is tracked with time to predict transition tonnage. The strong point of this approach is that it is based on real plant condition; however, for multi strand casting especially in billet and bloom casting, it is difficult to perform experiments for different plant condition. It is also important to note that design of Tundish also plays a major role in this and a model developed for a design of Tundish may not be valid for other Tundish designs.

Therefore, in the present work, a three-dimensional numerical model has been developed based on computational fluid dynamics (CFD) for the prediction of transition tonnage for 6 strands billet caster of Tata Steel India. The model is first validated with the available plant data and after the successful validation, the model is used to predict the transition tonnage under different plant conditions when one or more strand is non-functional or to find the effect of different casting speeds.

There is always an emphasis in the industry to reduce the transition tonnage to reduce the losses or diversions. Generally, baffles and weirs have proven to be a factor to reduce intermixed quantity [6] [7] [10]. In this study, two designs of baffles have been analysed to find the efficiency regarding intermixed quantity.

2. Problem Definition

As mentioned in the previous section, the scope of the study includes establishment of a well validated numerical model for grade transition for caster#3

(CC#3) of Tata Steel and further use this model to predict various scenarios existing in the plant. In addition, a means to minimize grade transition by using special baffle arrangement has also been evaluated. **Figure 1(a)** shows general schematics of a Tundish with 6 strands. Tata Steel India produces around 3.5 million tons of long products and out of which, 1 million tons is produced via caster 3 (CC#3) route. The Caster 3 covers the range from low carbon, to Thermo-mechanical treatment (TMT) bars to high carbon grades processing (wire and wire rods).

In general, Tundish is a combination of plug flow reactor (PFR) and Continuously stirred tank reactor (CSTR) [14] [15] [16]. During sequence change of the casting, grade change leads to mixing of grades which may be undesirable for critical grades. Grade change leading to transition can be explained as follows, suppose a grade with “ x ” *Composition* (Chemistry) is being casted and after a certain time the other grade with *Composition* “ y ” is poured in the Tundish with ($y > x$) [3]. A general picture regarding concentration variation at a strand (outlet from Tundish to inlet of mould) with time can be plotted as shown in **Figure 2(a)**. The concentration plot can be made dimensionless using Equation (1), as shown in **Figure 2(b)**.

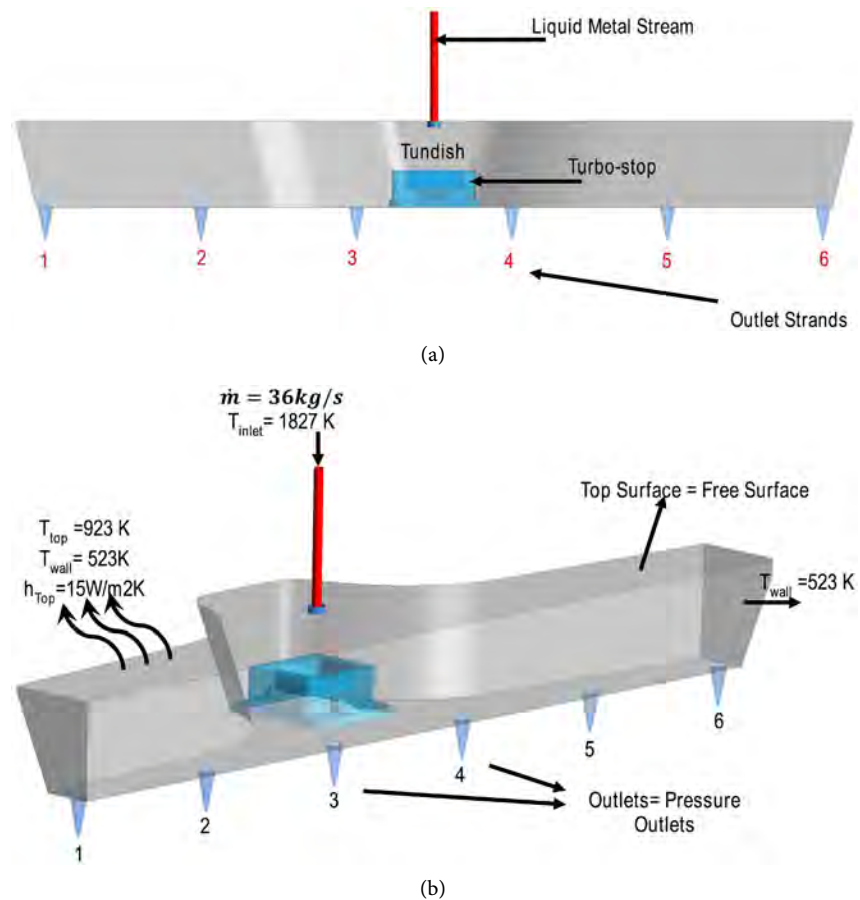


Figure 1. Geometry and boundary conditions for 6 strand Tundish. (a) Schematics of a 6-Strand Tundish; (b) Boundary conditions for 6 strand billet caster.

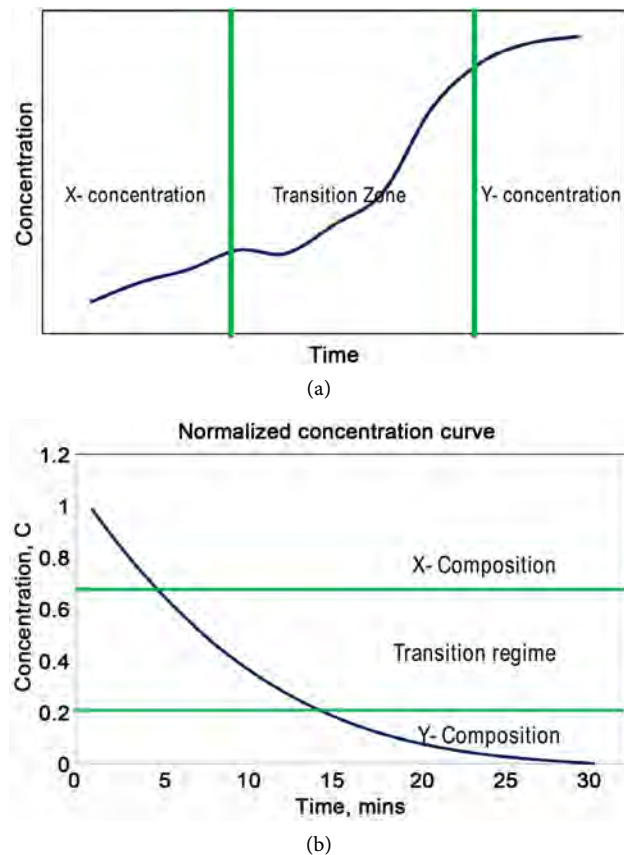


Figure 2. Concentration variation from grade x to grade y . (a) Concentration vs. time; (b) Normalised concentration vs. time.

$$c^* = \frac{c(t) - x}{y - x} \quad (1)$$

In the equation c^* is dimensionless concentration, $c(t)$ is the composition of given element in time t , x and y are the element composition for old and new grade respectively.

Using the above methodology, a concentration plot is obtained for Tundish using CFD model by tracking the concentration of tracer. This forms the basis for calculation of grade transition. The details are outlined in the next section where numerical approach and boundary conditions are provided.

3. Numerical Approach

3.1. Governing Equations

CFD analysis has been performed to get the flow field and tracer evolution in the Tundish. The underlying equations used for the study are outlined as follows:

- For the mass conservation, continuity equation (Equation (2)) is solved

$$\frac{\partial \rho V}{\partial t} + \nabla \cdot (\rho V) = 0 \quad (2)$$

Here V is the velocity.

For the momentum balance and heat transfer, Navier-Stokes equation [11] [12] [13] (Equation (3)) and thermal energy equation (Equation (4)) are solved, respectively

$$\frac{\partial \rho u}{\partial t} + \nabla \cdot (\rho V \times V) = -\nabla \cdot p + \mu \nabla^2 V - g \alpha \Delta T \quad (3)$$

$$\frac{\partial \rho E}{\partial t} + \nabla \cdot (\rho \bar{V} (E + p)) = \nabla \cdot k_{eff} \nabla T \quad (4)$$

Here E is the energy, T is the temperature, t is the time, k is the effective diffusion term, p is the pressure, μ is the dynamic viscosity, g is the acceleration due to gravity, α is the thermal expansion coefficient.

Thermal induced buoyancy has been modelled using Boussinesq approximation [11]. This has been added as a source term in the momentum equation (Equation (3)), see the rightmost term of Equation (3). The reference density of steel in Boussinesq approximation is taken as 7200 kg/m^3 .

- To model turbulence, realizable k- ε model with enhanced wall treatment has been used. The realizable k- ε model with enhanced wall treatment has been found to be better for Tundish flow simulations as mentioned in references [16] [17].

$$\frac{\partial}{\partial t}(\rho K) + \nabla \cdot (\rho K V) = \nabla \cdot \left[\left(\frac{\mu_t}{\sigma_K} \right) \nabla K \right] + 2\mu S_{ij} \cdot S_{ij} - \rho \varepsilon \quad (5)$$

Here $\mu_t = \rho C_\mu \frac{K^2}{\varepsilon}$.

Here C_μ is dimensionless constant and $C_\mu = 0.09$.

$$\begin{aligned} & \frac{\partial}{\partial t}(\rho \varepsilon) + \nabla \cdot (\rho \varepsilon V) \\ &= \nabla \cdot \left[\left(\frac{\mu_t}{\sigma_\varepsilon} \right) \nabla \varepsilon \right] + \rho C_1 S_\varepsilon - \rho C_2 \frac{\varepsilon^2}{K + \sqrt{\nu \varepsilon}} + C_{1\varepsilon} \cdot \frac{\varepsilon}{K} C_{3\varepsilon} G_b \end{aligned} \quad (6)$$

where $C_1 = \left[0.43, \frac{\eta}{\eta + 5} \right]$, $\eta = S \cdot \frac{K}{\varepsilon}$ and $S = \sqrt{2S_{ij}S_{ij}}$.

And value of $C_{1\varepsilon} = 1.44$, $C_2 = 1.9$, $\sigma_K = 1.0$ and $\sigma_\varepsilon = 1.2$.

The Pressure-Implicit with Splitting of Operators (PISO) [17] algorithm was used for the pressure-velocity coupling and Quadratic Upstream Interpolation for Convective Kinematics (QUICK) [17] scheme was used for the discretization of momentum, energy, turbulent kinetic energy and turbulent dissipation rate equations.

- The strategy to mimic transition of grades during Tundish operation is realized via injecting a tracer for one second (pulse injection of the tracer) and then tracking the evolution of the tracer for longer duration. Note that the tracer is tracked on a developed flow field that is after solving the flow field for more than two times of theoretical residence time [3] [7]. The concentration equation (Equation (7)) is solved to track species concentration over time. The tracer study is similar to injecting a dye in a water models for an

instant of time and tracking the evolution of dye with time [6].

$$\frac{\partial \rho_c C}{\partial t} + \nabla \cdot (\rho V C) = \nabla \cdot (\rho_c D_e \nabla C) \quad (7)$$

where, C is the species mass fraction D_e is effective diffusion which is sum of molecular diffusion and turbulent diffusion. The turbulent diffusion coefficient is determined the turbulent diffusion coefficient is determined from the following relationship (assuming that the turbulent Schmidt number equals unity):

$$\frac{\partial \rho D_e}{\mu_e} \sim 1 \quad (8)$$

As mentioned above, the tracer is tracked on the frozen flow field till most of the injected tracer leaves the Tundish via strands/outlets. For each strand/outlet, the concentration variation of the species is tracked with respect to time. This history of concentration variation with respect to time is called RTD (Residence time distribution) curve. In general, aRTD curve is a characteristic function of continuous process system and provides information on malfunction(s) if any and flow pattern *i.e.* degree of mixing [2] [8] [15] [18].

This RTD curve is further normalized to get the Exit Age distribution curves (E-Curve) [2] [8] [15] [19] [20] as follow:

$$E(t) = \frac{c(t) - c(t=0)}{\int_0^n [c(t) - c(t=0)] dt} \quad (9)$$

Such that

$$\int_0^n E_i(t) dt = 1 \quad (10)$$

where, $i = 1, 2, \dots, n$, $c_i(t)$: tracer concentration obtained either from experiment or numerical models and $E_i(t)$: residence time distribution function.

After getting the E curve, further normalization of E curve is done to get normalized concentration C as follow:

$$C(t) = 1 - \int_0^n E_i(t) dt \quad (11)$$

where $C(t)$ represents the normalized concentration of tracer at time t . This normalized concentration $C(t)$ forms the basis for predicting the transition tonnage.

3.2. Geometry and Boundary Conditions

The 3-D design of Tundish is as shown in **Figure 1(b)**. It is a six strand Tundish with a turbo stop just beneath the inlet to control turbulence.

Mass flow rate based on casting speed has been provided at the inlet with turbulence intensity of 5% [9]. The no slip condition was employed on each wall surface with the zero velocity at the wall. The outflow boundary condition was taken at each outlet. The top surface was assumed as a free surface with the zero-shear stress. The acceleration due to gravity was taken as 9.81 m/s^2 .

For the heat transfer calculation, the boundary conditions include the incom-

ing liquid steel temperature as 1823 K. The heat losses were supposed to be taking place through the walls, bottom and free surface of fluid in the Tundish. The heat transfer coefficient at the top surface is taken as 15 W/m²K and for Tundish walls heat transfer coefficient is taken as 3.46 W/m²K [9]. The higher heat transfer at top surface is due to extra radiative heat transfer taking place as compared to walls of Tundish where only conductive heat transfer happens.

Further detailed boundary conditions are listed in **Table 1**. The commercial ANSYS Fluent V.15 has been used in this study.

4. Grid Independence Study

A grid independence study has been performed to find the appropriate grid for the Tundish flow. The results were assessed for four different grids: 81,470, 333,320, 5,076,362 and 9,466,023 elements with maximum element size varying from 100 mm, 75 mm, 45 mm and 25 mm respectively.

Table 2 shows the temperature and velocity at outlet number 3 for the above four meshes. **Figure 3** shows the temperature value on a line passing through the cross-section of the Tundish along X axis (6.34 m domain). The difference in average results for velocity at outlet 3 for 81,470 elements and 9,466,023 elements is about 10% while the difference in the results for 5,076,362 elements and 9,466,023 elements is about 1%. Therefore, in the present study, the 3-D computational grid having 5,076,362 has been considered.

Table 1. Boundary conditions for 6 strand Tundish.

Parameter	Unit	Tundish
No. of strands	[-]	6
Casting speed	[m/min]	3
Mass flow rate	[Kg/s]	36
Mass flow rate	[Metric Ton/minute]	2.16
Volume	[m ³]	4.1
Total liquid steel	[Metric Ton]	32
Theoretical residence time	[s]	900
Shroud internal diameter	[m]	0.067
Outlet nozzle diameter	[m]	0.018
Submergence depth of the shroud	[m]	0.05
Temperature of inlet stream (T_{in}) [*during trial]	[K]	1823
Heat transfer coefficient at Tundish top (h_{top})	[W/m ² K]	15
Heat transfer coefficient at Tundish top (h_{walls})	[W/m ² K]	3.46
Temperature of top wall (T_{top})	[K]	1200
Temperature of side walls (T_{sides})	[K]	523
Density of liquid stream and Tracer	[kg/m ³]	7200
Conductivity of liquid steel	[W/mk]	35
Specific heat capacity of liquid steel	[J/kg.k]	640

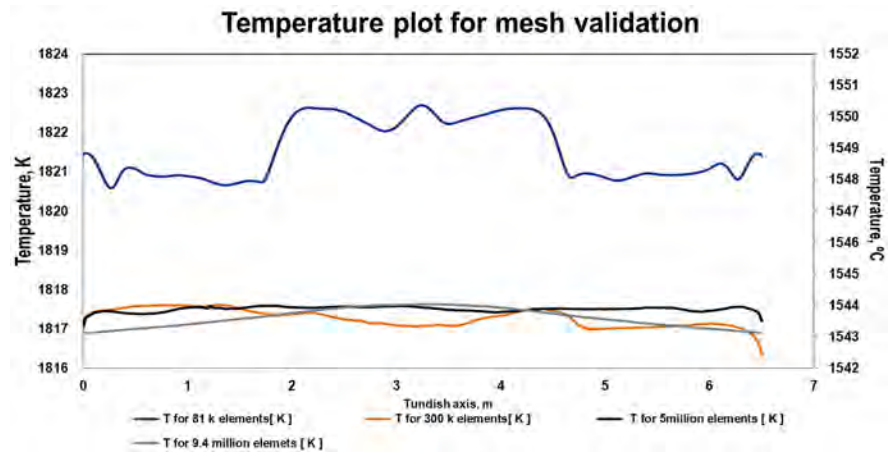


Figure 3. Temperature on a line along length of Tundish for the grid independence.

Table 2. Mesh validation for Tundish grade transition.

No. of Cells	Velocity at Outlet 3 (m/s)	Temperature at outlet 3 (K)
81470	3.528	1815.255
333320	3.411	1816.047
5076362	3.248	1816.871
9466023	3.235	1817.298

5. Results and Discussion

This section will describe the important results and validation aspects of this work.

5.1. Flow Features in the Tundish

To understand the general flow feature of the Tundish, flow pattern, temperature field contours and velocity vectors are visualized at different planes. **Figures 4-6** show the velocity contour, vectors, and streamlines respectively for 3 m/min (0.05 m/s) casting speed for 28 Ton (28,000 kg) Tundish weight (total liquid steel content in the Tundish).

Based on the contours, vectors and streamlines, it is visible that flow is predominantly surface driven; this is evident by the presence of high velocity near top of the Tundish spanning across the width. Just below this high velocity zone, there exist many slow-moving zones or say slow moving islands (see the blue coloured region in the contour plots and the recirculation loop marked by arrows in the vector plot (**Figure 4(a)**)). A noteworthy observation is that, see **Figure 5**, a high velocity zone is present near the top surface of the rear end of Tundish and this high velocity zone propagates very near to rear wall spanning the whole width. This can provide a clue that there can be erosion issue at rear side of wall due to this high velocity.

To understand flow and short-circuiting phenomena, snapshots of streamline are plotted for different intervals as shown in **Figure 6**. It is evident from initial

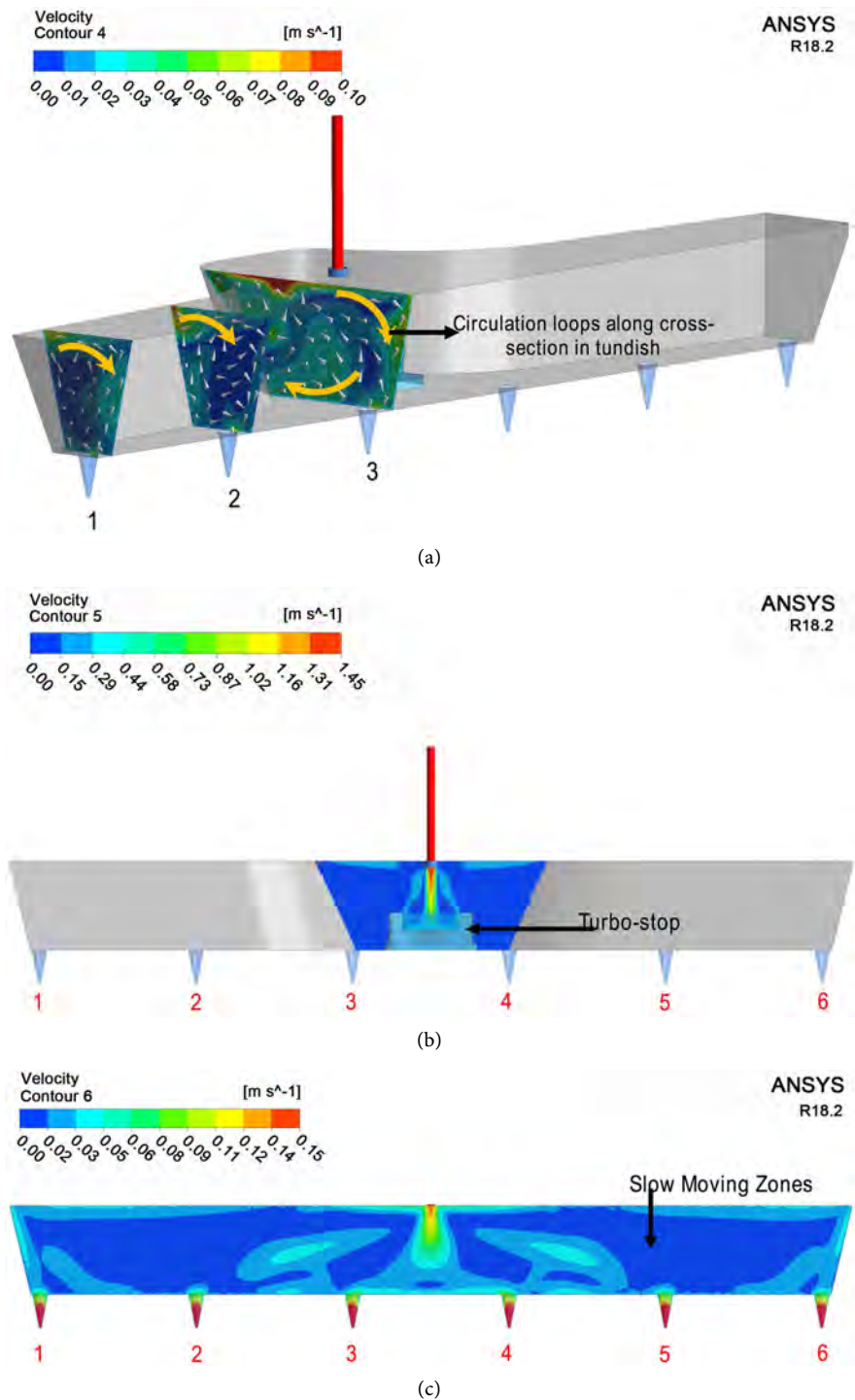


Figure 4. Velocity contours on various planes in 6 strands Tundish for all strands running. (a) Velocity field on a plane across the Tundish near three outlets for 6 strand Tundish; (b) Velocity field on a plane passing through the inlet for 6 strand Tundish; (c) Velocity field on a plane passing through all outlets for 6 strand Tundish.

streamline paths that there are heavy recirculation zones near inlet due to special curved refractory design near the inlet part. Based on streamline, a fair judgment can be done on short circuiting, see **Figure 6(b)** and **Figure 6(c)**. It is obvious

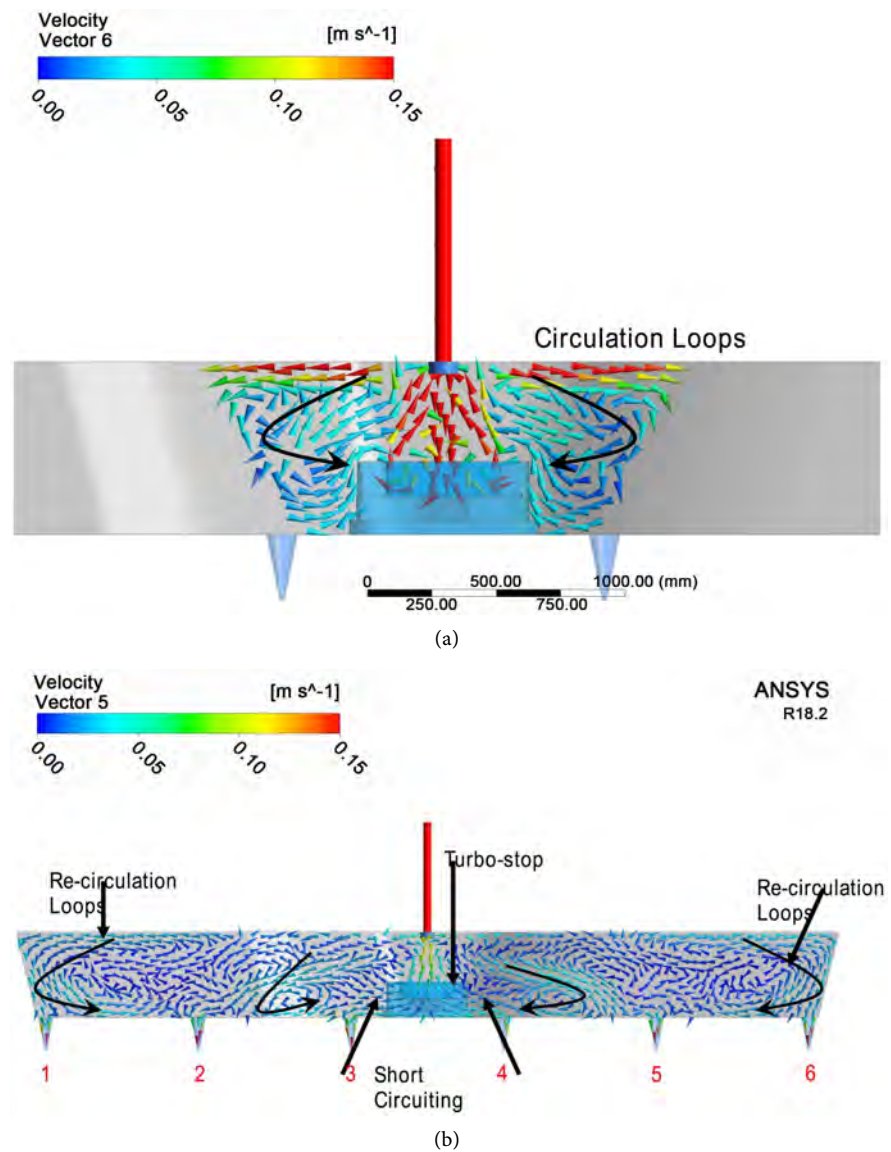


Figure 5. Velocity vectors at various locations in 6 strands Tundish all strand functional. (a) Velocity vector field on a plane passing through the inlet for 6 strand Tundish; (b) Velocity vector field on a plane passing through all outlets for 6 strand Tundish.

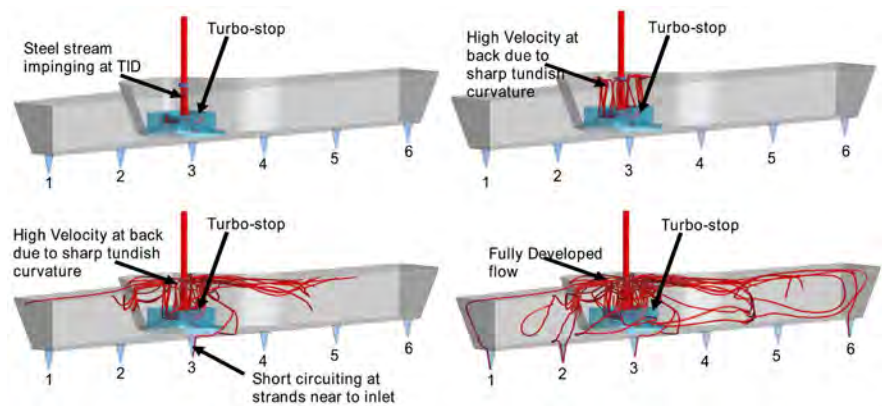


Figure 6. Streamline plot for 6 strands Tundish at various intervals.

that the strands closest to the inlet are receiving the material first. This will have consequences in the grade transition and will be more evident during tracking of tracer which has been covered in the next section.

Figure 7(a) and **Figure 7(b)** show temperature distributions on two planes along the width passing through inlet and all the outlets, respectively. Overall, a maximum drop of temperature in the Tundish is about 10°C . To compare temperature at different strands, the temperatures at all six strand outlets are shown in **Figure 8** with respect to inlet temperature. As expected the farthest strand has highest temperature drop. Higher temperature is achieved in the nearest strands from the inlet. Predominantly two factors are responsible for this large temperature drop in the outer strands: first one is presence of numerous slow moving zones and second one is higher residence time. However, comparing nearest to the farthest strands regarding temperature drop, there is a minimal difference of 2°C in the temperature.

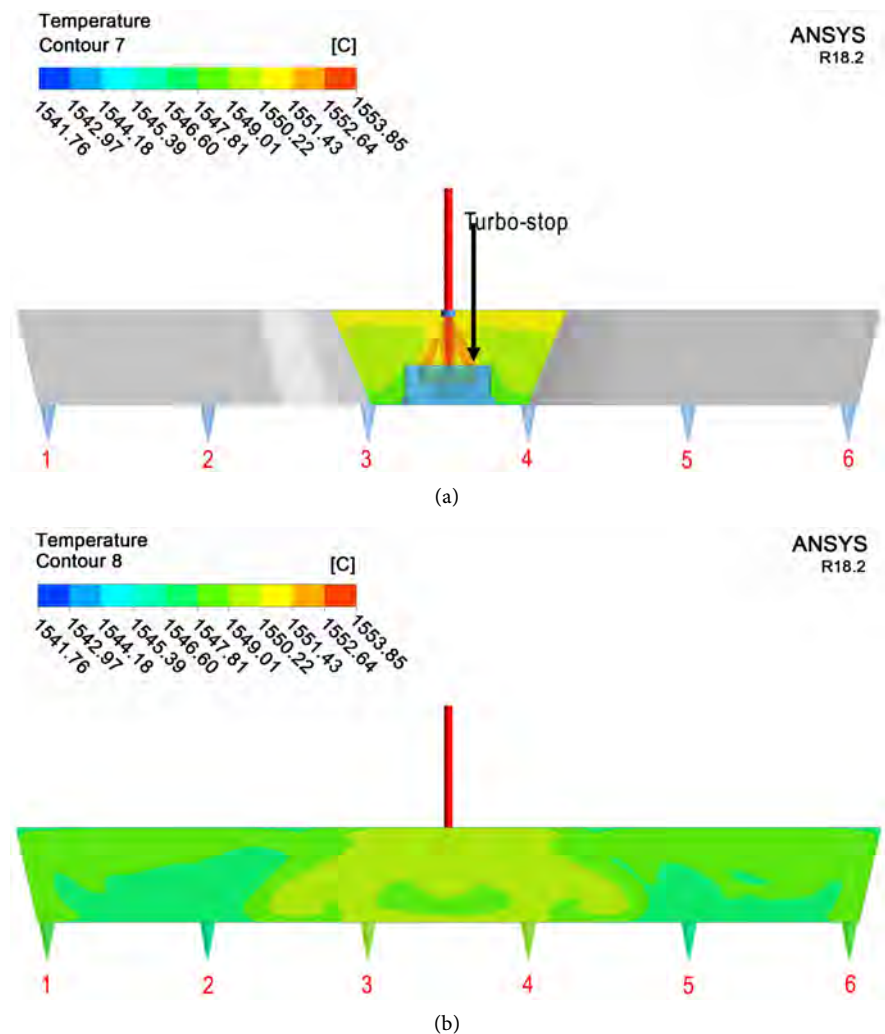


Figure 7. Temperature counters on various planes in 6 strands Tundish all strand functional. (a) Temperature field on a plane passing through the inlet for 6 strand Tundish; (b) Temperature field on a plane passing through all outlets for 6 strand Tundish.

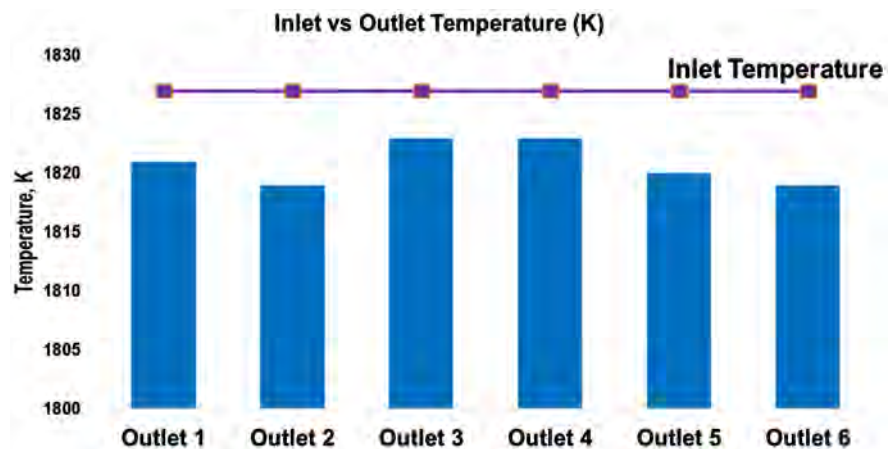


Figure 8. Comparison of Inlet temperature to outlet temperatures of strands for 6 strands Tundish all strands functional.

5.2. Characteristics of Tundish

5.2.1. Residence Time Distribution (RTD) Curves

To characterize Tundish behaviour, many authors [2] [21] have used plug flow, dead volume, and well-mixed regions also called RTD parameters. If the proportion of the well mixed region is higher, this indicates adequate mixing in the melt phase and hence better material and heat transport. On the other hand, a large plug flow volume indicates better possibility of inclusion floatation. In addition, higher the dead volume, higher will be the heat loss and higher the transition tonnage.

The RTD parameters are obtained from tracer concentration evolution as described in Section 3.1. Here analyses have been performed to find these parameters for 3 different scenarios: when all strands are working, when the one of the outermost strand is off (6th off) and when one of the strands closest to inlet is off (4th off). To find a single RTD curve for a given Tundish, Tracer concentrations at respective outlets (strands) are averaged with respect to number of strands. **Figure 9** presents the dimensionless RTD plot for above mentioned three scenarios. The corresponding RTD values are presented in **Table 3**. The data about volumes shows that when one of the strands is non-functional, the dead volume increases while plug flow volume decreases.

It will also be interesting to find if above volumes was impacted by change in casting speed. **Table 4** compares these volumes for 3 and 3.5 m/min casting speed. There is insignificant impact of casting speed change on the volumes. In other words, increase or decrease in casting speed does not change the characteristics of the Tundish.

5.2.2. Prediction of Grade Transition

Figure 10(a) shows the concentration plot (E-Curve) with respect to time for two strands, strand 4 (nearest to the inlet) and strand 1 (farthest from the inlet). Looking at **Figure 10(a)**, it is evident that nearest strand is receiving the material first (red curve in the figure) as well as the decay rate for this strand is faster.

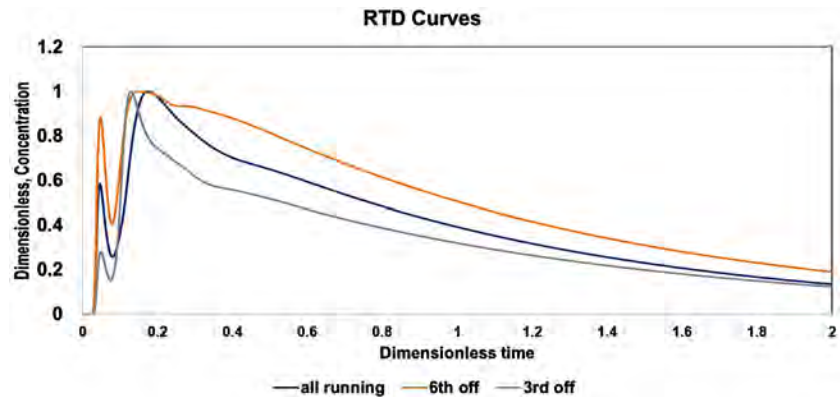
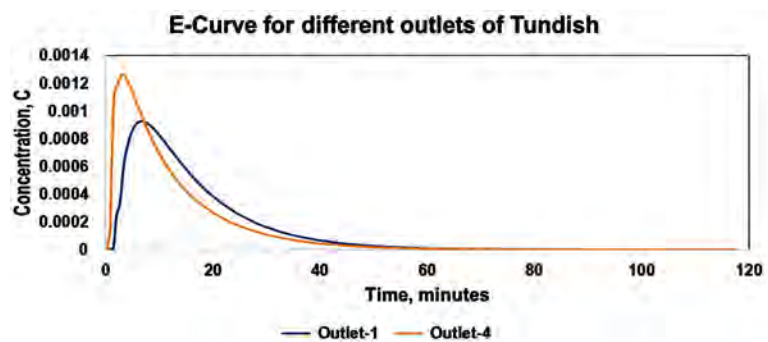
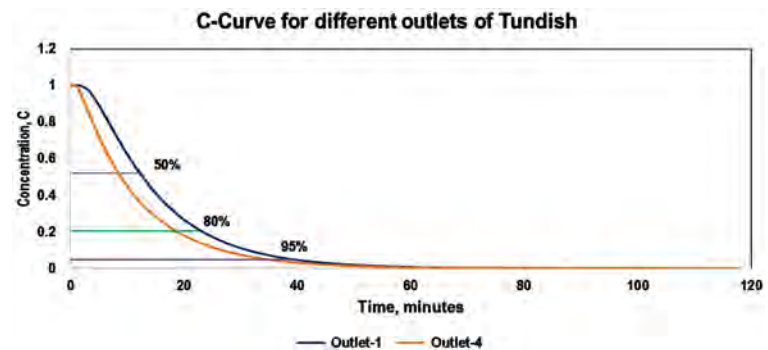


Figure 9. RTD curves for different strand operational on dimensionless concentration with dimensionless time.



(a)



(b)

Figure 10. Prediction of grade transition at different level (50%, 80% and 95%) for 6 strands Tundish. (a) E-Curve for strand 1 and 4; (b) Normalized concentration curve for strand 1 and 4.

Table 3. Comparison of RTD parameters of Tundish for different plant scenarios.

		All strand working	6 th strand off	3 rd strand off
θ_{\min}	Dimensionless minimum residence time	0.05	0.025	0.02
θ_{mean}	Dimensionless mean residence time	0.72	0.63	0.55
V_{Dead} (%)	Dead volume	25.65	37.6	41.87
V_{DPlug} (%)	Dispersed plug flow volume	32.25	25.11	16.44
V_{mix} (%)	Well mixed volume	42.1	37.8	41.01

Table 4. Comparison for RTD for different casting speed.

	All strand working (casting speed: 3 m/min)	All strand working (casting speed: 3.5 m/min)
Plug flow region (%)	17.51	17.82
Dead regions (%)	28.70	27.16
Well mixed region (%)	53.73	55.08

This shows short-circuiting phenomenon as mentioned in literature [7] [10] and as obvious from streamline plots (see **Figure 6**).

To predict the transition tonnage during the grade change, the exit age distribution, E-curve, obtained for each strand is normalized on the scale of 0 to 1 by using Equation (8), Equation (9) and Equation (10). The curve thus obtained is called C-curve as shown in **Figure 10(b)**. This C-curve forms the basis of the prediction of transition tonnage [7]. The transition time and tonnage obtained depends on the composition difference of the grades and acceptance criteria at plant. For example, transition can finish at 50% or 80% or 95% as indicated by horizontal lines in the plot of **Figure 10(b)**, is solely dictated by customer requirement.

In real plant scenario, transition tonnage is predicted by comparing transition of critical elements (e.g. C, Mn, Si, Cr, Vetc.) during grade change. This requires transition percentage to be calculated based on the limiting element. Based on the band of acceptable composition of a grade (e.g. 80%, 90%, 95%), the corresponding transition time and transition tonnage is predicted.

As shown in **Figure 10(b)**, the transition time for strand 4 is lesser than strand 1. Here in LD#1 CC3 caster, the strand with largest transition time (strand 1 or 6) is the limiting strand. This is because the torch cutting system of billets has certain limitations in its automation system. However, there is a possibility to automate the transition cutting system for each strand to minimize losses.

5.2.3. Validation of the Grade Transition Model

To get the confidence in the grade transition model, a plant trial was executed. The trial casting conditions and grade composition are shown in **Table 5** and **Table 6**. In the trial, all the strands were functional and average casting speed was in range of 2.71 m/min. Strand 6 was chosen for sampling of billets to track the chemistry variation of elements [C, Mn, Si] with respect to casting time. Nine billet samples were collected from the *strand 6* at different time intervals after the Grade 2 ladle was opened to be poured into the Tundish. **Table 7** shows the variation of Mn, Si and C concentration (both normalized and non-normalized) with respect to casting time. As it is evident from **Table 7** that the critical element for the trial sequence is Mn since the transition of Mn is slowest among all elements. The normalized concentrations obtained from both CFD and plant is compared as shown in **Figure 11**. The transition time to achieve 92% of

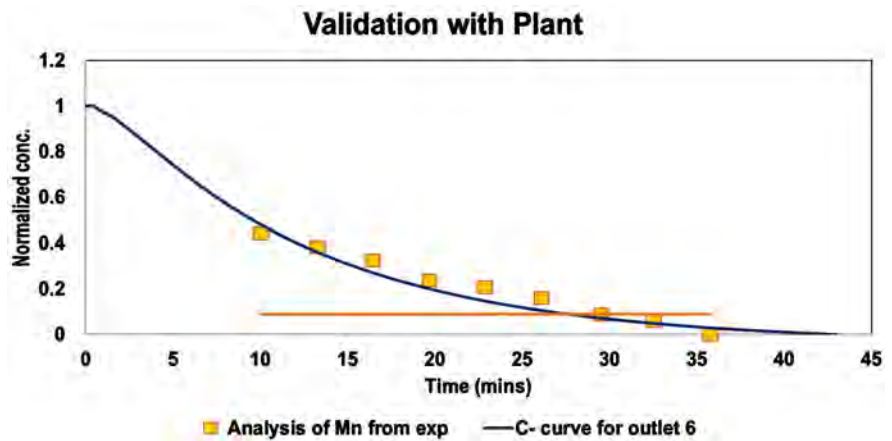


Figure 11. Validation for 6 strands Tundish with experimental data points.

Table 5. Grades used for validation during plant experiment.

	Grade1	Grade2
	PC No. 479—M75480	PC No. 975—Heat Id M75483
Critical element—Carbon	0% - 0.06 %	0.0% - 0.07%
Actual % C	0.03%	0.068%
Critical element—Manganese	0.5% - 0.55 %	0.27% - 0.35%
Actual % Mn	0.504%	0.335%
Critical element—Silicon	0.018% - 0.028 %	0.035% - 0.07%
Actual % Si	0.024%	0.047%

Table 6. Casting speed for each strand during plant experiment.

Casting Speed, m/min (Avg.)	Strd1	Strd2	Strd3	Strd4	Strd5	Strd6
Tundish weight at ladle open = 23.7 T	2.71	2.71	2.71	2.71	2.71	2.71

Table 7. Elements variation with time during plant experiment.

Time (mins)	C		Mn		Si	
	Non-Normalized %	Normalized	Non-Normalized %	Normalized	Non-Normalized %	Normalized
10	0.06	0.741935	0.4	0.443	0.032	0.653846
13.25	0.06	0.741935	0.39	0.384	0.034	0.576923
16.41	0.054	0.548387	0.375	0.325	0.034	0.5
19.66	0.053	0.516129	0.37	0.236	0.039	0.5
22.83	0.06	0.741935	0.362	0.207	0.039	0.307692
26.083	0.06	0.741935	0.35	0.159	0.04	0.307692
29.5	0.044	0.225806	0.345	0.088	0.043	0.269231
32.5	0.042	0.16129	0.335	0.059	0.043	0.153846
35.75	0.039	0.064516	0.4	0	0.043	0.153846

transition according to CFD analysis is around 28 minutes while plant trial composition variation reveals it is around 29.5 minutes. Looking at the validation plot (**Figure 11**), a good match between numerical model and plant data can be established. This provides a good confidence in the model to analyse different plant scenarios. The next section will be presenting different plant conditions regarding grade transition.

6. Prediction of Transition Tonnage for Different Plant Condition

In this section, various ifs and buts for numerous plant conditions will be presented. Due to breakout or other mechanical failures of strands during casting, numerous scenarios may prevail. For example, outer strand may become non-functional or one of the inner strands may be closed or any of the two strands may become non-functional. As known from previous section about RTD analysis that the closure of strands with respect to inlet position changes the flow characteristics as well as RTD features. Therefore, it is suspected that the above scenarios may impact the transition tonnage generated during the grade change. To understand that, here numerous situations are analysed. This exercise in essence can provide a guideline to plant in taking proper action to cut the transition tonnage at accurate time. In addition, casting speed during grade change may vary. This also needs a deep evaluation to find if there is impact of casting speed on grade transition tonnage or not.

6.1. Grade Transition Based on Strand Availability

As stated earlier during casting operation, there is a possibility that certain strands are not operational. Here three scenarios are analysed for the six strands Tundish: first case where all 6 strands are functional, second case where *number 6* strand is non-functional (farthest from the inlet) and the third case where *number 4* strand is non-functional (nearest from the inlet), for nomenclature of strands see **Figure 1(b)**. Note that here casting speed is fixed and taken as 3.1 m/min and Tundish weight is 28 Tons (total content of liquid steel in the Tundish). The casting speed remains same (3.1 m/min) defined at outlet of strand (for closure of one strand case) and hence total input (mass flow rate) to Tundish is scaled by number of strands functional. The strands are made non-functional by defining one of the outlets as wall during the simulation.

Note that the casting speed and the weight of the steel in Tundish are based on real plant scenario. The transition tonnage is calculated as follows:

$$\text{Transition Tonnage} = \text{casting speed} \times \text{density of steel} \times \text{area of the billet} \\ \times \text{transition time} \times \text{No. of strands running} \quad (15)$$

To predict transition tonnage for different plant scenarios, numerous permutations and combinations for strand unavailability is analysed. **Figure 12** compares the transition tonnage and time for the cases where anyone or any two strands are non-functional. For single strand closure, the highest transition

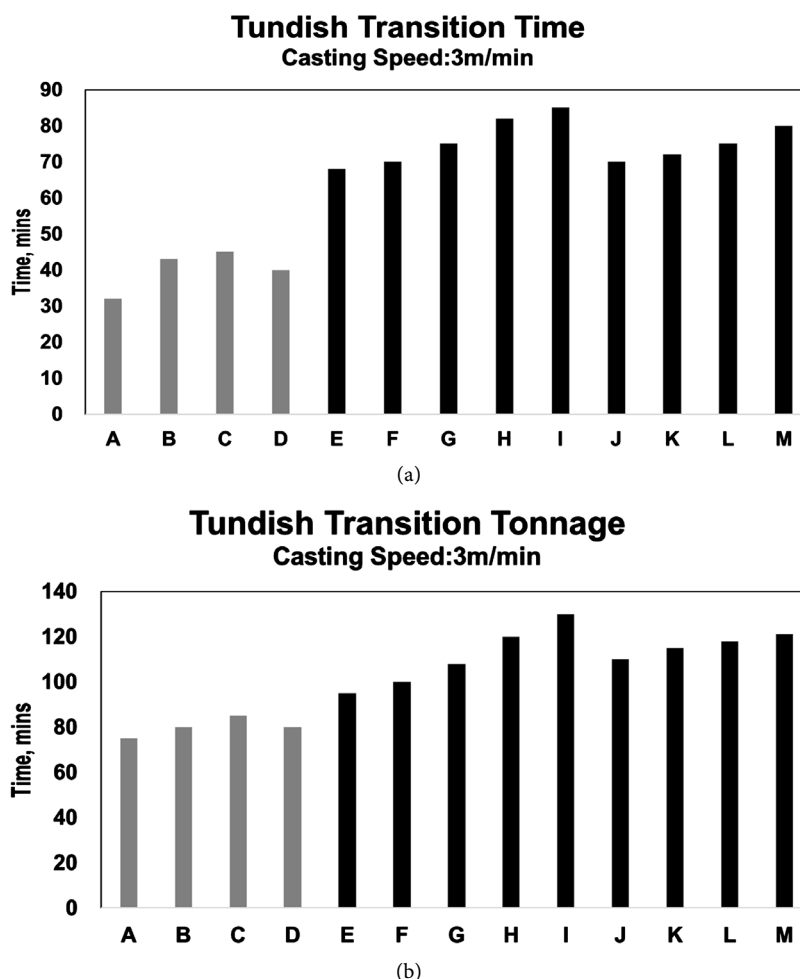


Figure 12. Comparison of transition time and tonnage for 6 strands Tundish under different plant scenario. (a) Transition time for 6 strands Tundish for all strand running scenario; (b) Transition tonnage for 6 strands Tundish for all strand running scenario. Symbol: Case. A: All strand functional; B: 1st strand off; C: 3rd strand off; D: 2nd strand off; E: 1st and 4th strand off; F: 2nd and 4th strand off; G: 2nd and 3rd strand off; H: 1st and 6th strand off; I: 3rd and 4th strand off; J: 1st and 5th strand off; K: 2nd and 5th strand off; L: 1st and 3rd strand off; M: 1st and 2nd strand off.

tonnage is produced when closest strand to the inlet, strand (3 or 4) is non-operational. For two strand closure cases, the strand 1 and 2 closure leads to highest transition tonnage.

6.2. Impact of Casting Speed on Grade Transition

A pertinent question is that whether at different casting speed, the transition time and tonnage will be different. To answer this, transition tonnage and time is computed for two casting speeds, 3 and 3.5 m/min for all strand working scenario. **Figure 13** shows a comparison of transition time and tonnage based on limiting strand (strand 1 and 6 farthest). As evident that the increase in casting speed from 3 to 3.5 m/min decreases the transition time from 44.3 to 37 minutes, while change in transition tonnage is insignificant (80.1 to 78.5 tons). For

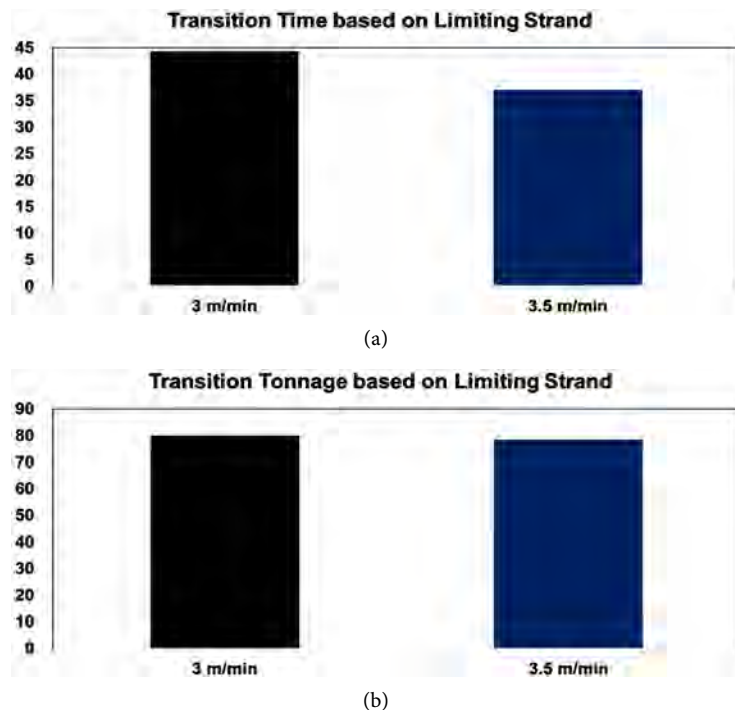


Figure 13. Comparison transition plot for 6 strands Tundish with different casting speed. (a) Comparison based on transition time; (b) Comparison based on transition tonnage.

the operational people, transition tonnage is the deciding factor to remove the mixed composition. It can be stated that the CC#3 Tundish has nominal impact on transition tonnage due to increase in casting speed. The above fact essentially tells that there is no change in flow characteristics of Tundish due to change in casting speed. This was already obvious from the analysis of dead, plug and well mixed volume in Section 5.2.1 where no significant impact on the volumes was found due to change in the casting speed. Hence, this signifies that no. of rounds of billets which will be downgraded for transition remains same irrespective of casting speed.

7. Effect of Baffles (Flow Modifiers) on the Performance of Tundish

There is always an emphasis to decrease the intermixed quantity. One of the methods is to provide special baffles. To study the impact of baffles on the transition tonnage, here two types of design of baffles for six strands Tundish have been performed. The two designs are shown in **Figure 14** (say design 1) and **Figure 15** (say design 2) respectively. The Design 1 (**Figure 15**) presents a design of Tundish, in which two dams are placed across the width of Tundish adjacent to the turbo-stop. The Design 2 (**Figure 16**) presents the design of Tundish in which a single long dam is made between inlet and outlet, the dam is placed just in front of the turbo-stop. The height of the dam is taken to be half height of Tundish height. Both the new designs were simulated for the same casting speed of 3.1 m/min.

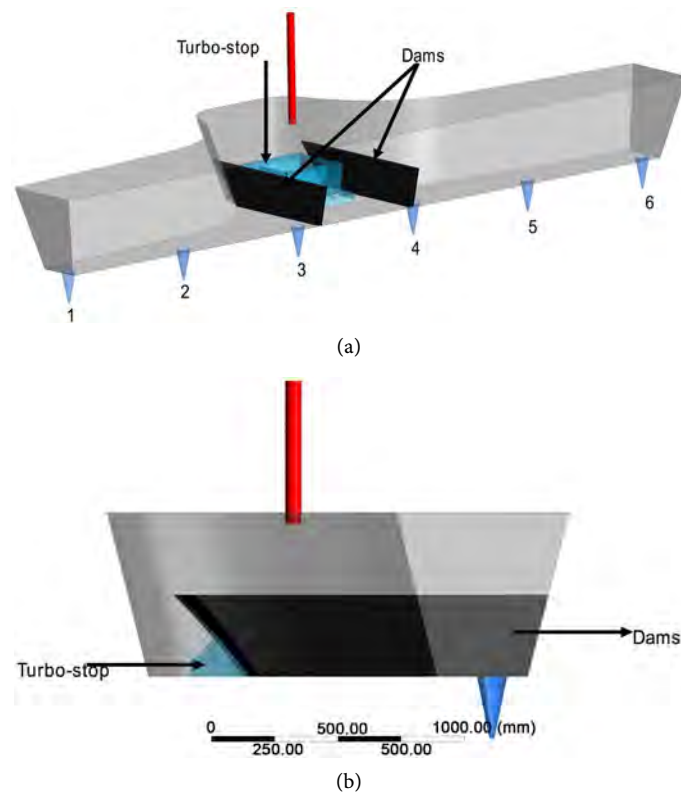


Figure 14. Tundish design with two symmetrical baffles (Design 1). (a) Iso-view of Tundish with 2 dams; (b) Side view of Tundish with 2 dams.

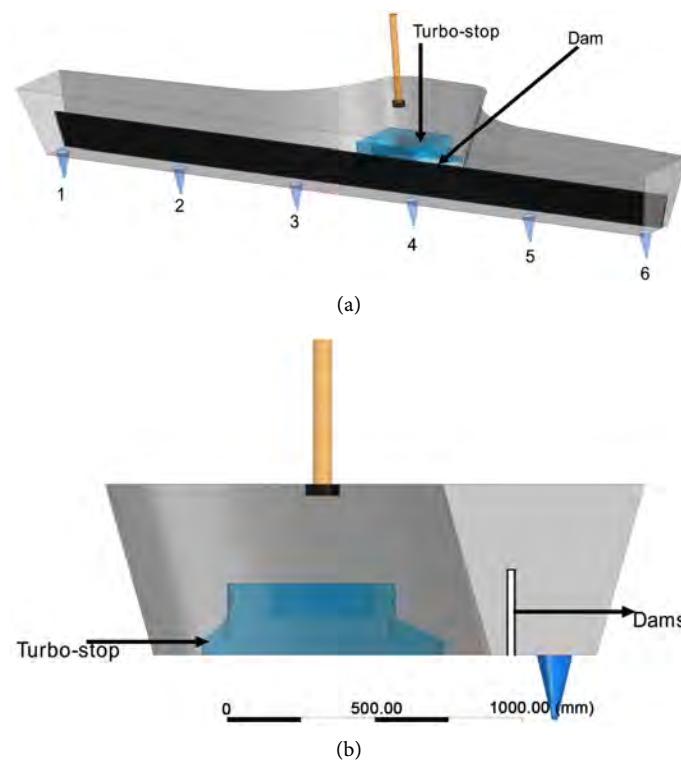


Figure 15. Tundish design with long baffle (Design 2). (a) Iso-view of Tundish with long dam; (b) Side view of Tundish with 1 long dams.

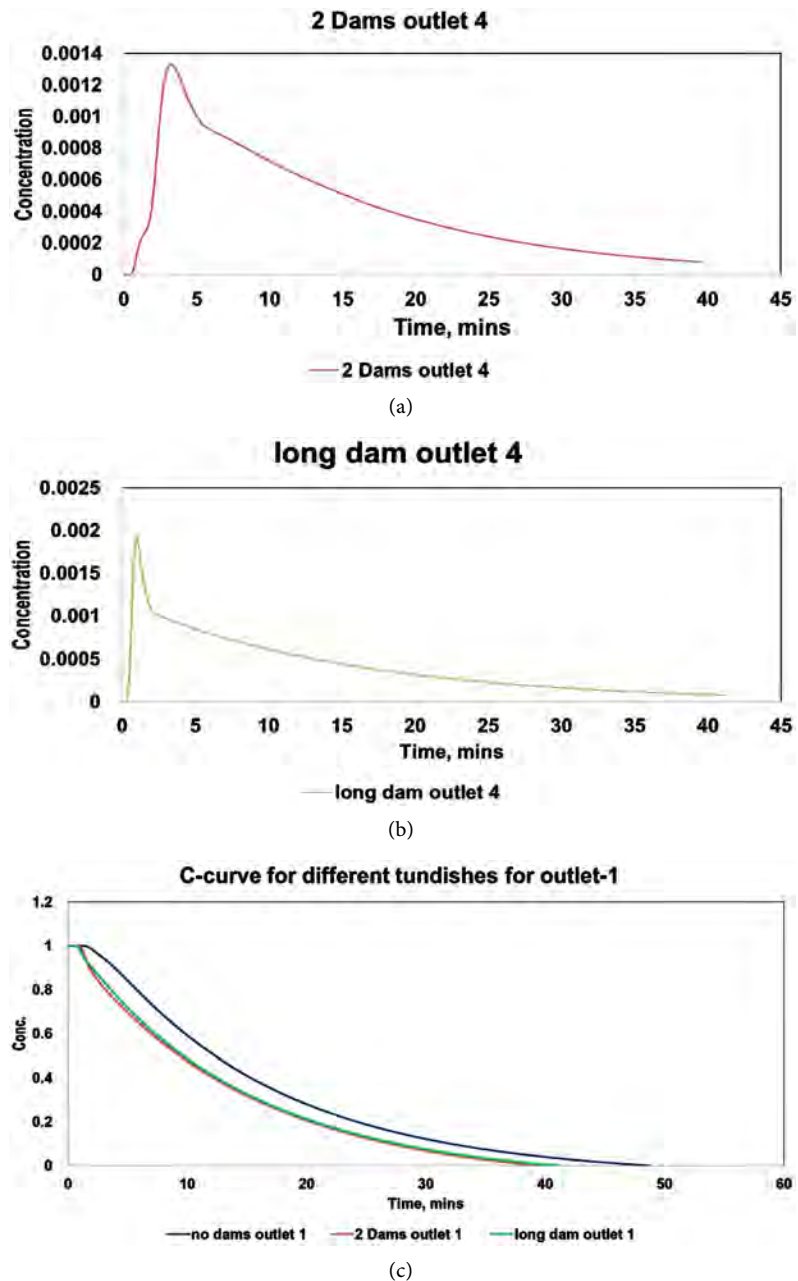


Figure 16. Effects of baffles on the performance of Tundish. (a) RTD curve for strands 1 and 4 for two baffle Tundish; (b) RTD curve for strands 1 and 4 for long baffle Tundish; (c) Transition time prediction for different Tundish designs (no dams, single long dam and 2 dams).

To understand the impact of short circuiting, **Figure 16(a)** and **Figure 16(b)** are plotted. **Figure 16(a)** and **Figure 16(b)** show the RTD curves for Design 1 and Design 2 respectively for strands 1 and 4. When comparing **Figure 16(a)** and **Figure 16(b)** (Tundish design with baffles) with **Figure 10(a)** (Tundish without baffles), it is evident that short-circuiting is diminished by introducing baffles in the Tundish.

Figure 16(c) shows the concentration plot for Tundish with no baffle, Tun-

dish with 2 symmetric baffles (Design 1) and one long baffle (Design 2). The transition times for Tundish without baffle, Design 1 and Design 2 are 48, 39.5 and 41.1 minutes respectively. It is clear that the Tundish with 2 baffles (Design 1) is best for productivity increase by decreasing the intermixed quantity.

On calculating the tonnage saving for Tundish with 2 baffles (Design 1) reveals that 21 tons material (3 rounds of 9 m billet) can be prevented from down-gradation or diversion. This is a huge saving.

8. Conclusions

In this study, a model to predict transition tonnage and time for 6 strand billet caster Tundish of Tata Steel India has been developed using CFD methodology. The developed model in this study validates quite well with the plant trial findings. The model has been used to analyse different plant conditions e.g. if nearest strand to inlet or farthest strand to inlet has been non-operational; then what will be the impact on transition tonnage. The model has shown its efficacy to provide insights about what happens during grade change. The important conclusions from this study are outlined as follows:

- Flow field inside the Tundish is symmetrical and short circuiting phenomena are observed to happen for a strand nearest to inlet.
- Due to special curved design near inlet, high surface velocity regions directed towards long side wall away from strand outlets are found. This may lead to heavy erosion of Tundish refractory in the top region of rear wall area.
- The closure of the one or more strands plays a vital role for dictating the transition tonnage to be downgraded.
- For single strand closure situation, highest transition tonnage is produced when strand nearest to inlet is non-functional and minimum transition tonnage is achieved when all strands are functional.
- Casting speed plays a role in reducing transition time, but it does not have significant impact on transition tonnage. This was due to the fact that insignificant changes in the plug, dead and well mixed zones were found due to increase or decrease in the casting speed.
- Baffles improve the performance of Tundish and reduce the intermixed quantity.

A future study is underway to find the best baffle height, number of baffles and position of baffles to further reduce the intermixed quantity.

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Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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